
PAL User Manual

Installation and Operation

HTC PAL

PAL HTC-*xt*

Printing History

| | | |
|-----------|---------------|-------------------------------|
| Edition 1 | January 1999 | Software Version 2.0 |
| Edition 2 | April 2003 | Software Version 2.0 |
| Edition 3 | November 2009 | Software Version 2.5 to 4.1.X |
| Edition 4 | March 2010 | Software Version 2.5 to 4.1.X |
| Edition 5 | June 2010 | Software Version 2.5 to 4.1.X |
| Edition 6 | March 2013 | Software Version 2.6 to 4.3.X |

Original Instructions

CTC Analytics AG reserves the right to make improvements and/or changes to the product(s) described in this document at any time without prior notice.

CTC Analytics AG makes no warranty of any kind pertaining to this product, including but not limited to implied warranties of merchantability and suitability for a particular purpose.

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A. Safety Information

Safety Information and Warnings for Users of the PAL System

General Considerations



The PAL System User Manual and related documents must be consulted by the user under all circumstances before a unit is put to use.

Changes or modifications to this unit not expressly approved by the party responsible for compliance could void the user's authority to operate the equipment.

The user should be aware that if the equipment is used in a manner not specified by the manufacturer, the protective and safety features of the equipment may be impaired.

The repair of instrument failures caused by operation in a manner not specified by the manufacturer is expressly excluded from the standard warranty and service contract coverage.

When, for technical reasons, it is necessary to work on instrument parts which may involve a potential hazard (moving parts, components under voltage, etc.) the authorized representative of CTC Analytics AG must be contacted. In general, this type of situation arises when access to the parts is only possible using a tool. Should an operator perform such a maintenance operation, he/she must have received proper training to carry out that specific task.

Environmental Conditions

The environmental conditions in which the PAL System can be operated are listed in the corresponding section of the PAL User Manual; see the section 'Specifications'.

Electrical Hazards



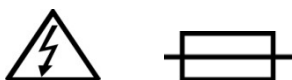
Every analytical instrument has specific hazards, so be sure to read and comply with the following precautions. They will help ensure the safe, long-term use of your PAL System.

The installation category (over-voltage category) for this instrument is Level II. The Level II category pertains to equipment receiving its electrical power from a local level, such as an electrical wall outlet.

Connect the PAL System only to instruments complying with IEC 61010 safety regulations.

The power line and the connections between the PAL System and other instruments used in the configuration setup of the total analytical system must maintain good electrical grounding. Poor grounding represents a danger for the operator and may seriously affect instrument performance.

Do not connect the PAL System to power lines that supply devices of a heavy duty nature, such as motors, refrigerators and other devices that can generate electrical disturbances.



Use only fuses of the type and current rating specified. Do not use repaired fuses and do not short-circuit the fuse holder.

The supplied power cord must be inserted into a power outlet with a protective earth contact (ground). When using an extension cord, make sure that the cord also has an earth contact.

If the supplied power cord does not fit the local electrical socket and a replacement or adapter has to be purchased locally, make sure that only a certified power cord is used. Any power cord used should be certified by the appropriate local authorities.

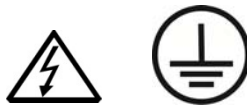
Pay attention not to leave any cable connecting the PAL System and the chromatographic system or the power cord close to heated zones, such as the injector or detector heating blocks or the GC hot air vents.

Always replace any cable showing signs of damage with another one provided by the manufacturer. Safety regulations must be respected.



Do not change the external or internal grounding connections. Tampering with or disconnecting these connections could endanger you and/or damage the PAL System.

The instrument is properly grounded in accordance with these regulations when shipped. You do not need to make any changes to the electrical connections or the instrument's chassis to ensure safe operation.



The combination of a PAL System with an LC/MS System also requires that the safety measures described by the LC/MS System manufacturer be followed. Detailed instructions for the safety grounding on the LC/MS System are outlined in the corresponding operating/installation manual.

CTC Analytics recommends using a grounding cable connected on one side to the Injection Valve, Loop or any other suitable direct metallic contact, and on the other side to an appropriate ground point on the LC/MS System. This supplementary grounding measure will complement the safety strategy of the LC/MS System manufacturer.



Do not turn the instrument on if you suspect that it has incurred any kind of electrical damage. Instead, disconnect the power cord and contact a CTC Analytics representative for a product evaluation. Do not attempt to use the instrument until it has been evaluated. Electrical damage may have occurred if the PAL System shows visible signs of damage, exposure to any liquids or has been transported under severe stress.



Damage can also result if the instrument is stored for prolonged periods under unfavorable conditions (e.g. subjected to heat, moisture, etc.). Ensure that the power supply/controller unit is always placed in a clean and dry position. Avoid any liquid spills in the vicinity.



Before attempting any type of maintenance work, always disconnect the power cord(s) from the power supply(ies) if optional devices are installed. Capacitors inside the instrument may still be charged even though the instrument is turned off.

To avoid damaging electrical parts, do not disconnect an electrical assembly while power is being supplied to the PAL System. Once the power is turned off, wait approximately 30 seconds before you disconnect an assembly.

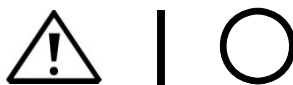


The instrument includes a number of integrated circuits. These circuits may be damaged if exposed to excessive line voltage fluctuations and/or power surges or electrostatic charges.



Never try to repair or replace any components of the instrument that are not described in the PAL User Manual without the assistance of a CTC Analytics representative.

There are no operator-serviceable or replaceable parts inside the power supply(ies) or in the PAL System.
If a power supply is not functioning, contact a CTC Analytics representative.



The power supplies for the PAL System and the Peltier Stack Module have the symbols I/O on the power switch label to indicate ON/OFF.

If a Peltier Stack Module is installed in combination with a PAL System, then a second power supply is active in the complete system. Turning OFF the two power supplies or pulling the two power cords in an emergency will stop the entire PAL System.



It is important that the power supply(ies) be in a location where the power ON | OFF switch is accessible and easy to operate, and where it is possible to unplug the AC power cord from the power supply/wall outlet in case of emergency.

Laser Safety Information

Barcode Reader Model: LS-1220

Safety Warning for Laser CDRH/IEC Class II/2 Product.



Warning

The installed Laser device is a CDHR/IEC Class II/2 Laser Product. Class II/2 Laser devices are not considered to be hazardous when used for their intended purpose. The following statement is required to comply with US and international regulations:

Caution

Use of controls, adjustments or performance of procedures other than those specified herein may result in hazardous laser light exposures.

For more details see label on the product or manufacturer specifications and safety warnings.

Other Hazards



To avoid injury and possible infection through contamination during PAL System operation, keep your hands away from the syringe.



Do not operate the PAL System without the safety guard. The safety guard must be installed for safe operation.
Do not place any objects inside the area of the safety guard. Keep away from the area around the safety guard during operation of the PAL System.



Danger of crushing to fingers and hands. To avoid injury keep your hands away from moving parts during operation. Turn off the power to the PAL System if you need to reach inside a mechanically powered system with moving parts.



To avoid injury, observe safe laboratory practice when handling solvents, changing tubing, or operating the PAL System. Know the physical and chemical properties of the solvents you use. See the Material Safety Data Sheets (MSDS) from the manufacturer of the solvents being used.

When using the PAL System, follow the generally accepted procedures for quality control and method development.



When using the PAL System in the field of chromatographic analysis, if a change in the retention of a particular compound, in the resolution between two compounds, or in peak shape is observed, immediately determine the reason(s) for the changes. Do not rely on the separation results until you determine the cause of a change.

Do not operate on the instrument components that form part of the work area of the PAL System when this is in motion.



Use caution when working with any polymer tubing under pressure:

- Always wear eye protection when near pressurized polymer tubing.
- Do not use polymer tubing that has been severely stressed or kinked.
- Do not use polymer tubing, in particular no PEEK or Tefzel tubing, when using tetrahydrofuran (THF), dimethylsulfoxide (DMSO), chlorinated organic solvents, concentrated mineral acids such as nitric, phosphoric or sulfuric acids, or any related compounds.



Do not use vials without a sealing cap, or microtiter or deepwell plates without a plate seal. Vapor phase from organic solvents can be hazardous and flammable. Acidic vapor phase can cause corrosion to critical mechanical parts.



When sample vials have to undergo heating and agitation, it is important to consider the glass quality. Use high quality glass only. Remember that depending on the application conditions, high pressure can build up in the vial. Whenever a temperature greater than 60 °C is applied, consider the vapor pressure of the solvent used to ensure that no excessive pressure builds up. This is important when using a temperature above 100 °C and especially at the maximum temperature of 200 °C. Be aware that solid materials can also contain volatile compounds such as water (humidity) which could cause build-up of excess vapor pressure.



Do not reuse headspace vials. During the process of washing the vial, micro-cracks can form which will weaken the glass wall and increase the chances of the vial breaking.



In case of a single fault situation where the temperature control of the Agitator fails, there is the potential danger that the device will heat up in an uncontrolled manner until it reaches the cut-off temperature of the over-temperature fuse, in this case, 240 °C.

Based on this single fault scenario, when working with flammable solvents, the user must ensure that the solvent used has a flash point which is 25 °C higher than the maximum potential temperature (240 °C) of the Agitator.

Working with Toxic or other Harmful Compounds



Before using dangerous substances (toxic, harmful, etc.) please read the hazard indications and information reported in the Material Safety Data Sheet (MSDS) supplied by the manufacturer referring to the relevant CAS (Chemical Abstract Service) number. The PAL System requires the use of several chemical products with different hazard characteristics, which are present in vials and syringes. Before using these substances or replacing the syringe, please read the hazard indications and information reported in the MSDS supplied by the manufacturer referring to the relevant CAS number.

During sample preparation, please refer to local regulations for the ventilation conditions of the work room.

All waste materials must be collected and eliminated in compliance with the local regulations and directives in the country where the instrument is used.

Biological Hazards



In laboratories where samples with potential biological hazards are handled, the user must label any equipment or parts thereof which may become contaminated with biohazardous material. The appropriate warning labels are included with the shipment of the instrument. It is the user's responsibility to label the relevant parts of the instrument.

When working with biohazardous materials, it is the user's responsibility to fulfill the following mandatory requirements:

- Instructions on how to safely handle biohazardous material must be provided.
- Operators must be trained and made aware of the potential dangers.
- Personal protective equipment must be provided.
- Instructions must be provided on what to do in case operators are exposed to aerosols or vapors during normal operation (within the intended use of the equipment) or in case of single fault situations such as a broken vial.
The protective measures should consider potential contact with the skin, mouth, nose (respiratory organs) and eyes.
- Instructions for decontamination and safe disposal of the relevant parts must be provided.

It is the user's (operator's) responsibility to handle hazardous chemicals or biological compounds, including (but not limited to) bacterial or viral samples and the associated waste, safely and in accordance with international and local regulations.

Maintenance

Any external cleaning or maintenance must be performed with the PAL System turned off and the power cord disconnected. Avoid using solvents and spraying on electrical parts. For the removal of potentially dangerous substances (toxic, harmful, etc.) read the hazard indications and information reported in the MSDS (Material Safety Data Sheet) supplied by the manufacturer referring to the relevant CAS (Chemical Abstract Service) number. Use proper protective gloves.

When working with hazardous materials such as radioactive, biologically hazardous material, etc., it is important to train all operators how to respond in case of spills or contamination.

Depending on the class of hazardous material, the appropriate measures have to be taken immediately. Therefore, all chemicals or solvents needed for decontamination must be on hand.

Any parts of the equipment which can potentially be contaminated, such as the sample vial rack, syringe tool, wash module, etc., should be cleaned regularly. The waste solvent from cleaning and any hardware which needs to be disposed of has to be properly eliminated with all the necessary precautions, abiding by national and international regulations.

When preparing for decontamination, ensure that the solvent or chemical to be used will not damage or react with the surface, dye (color) of the instrument, table or other nearby objects.

If in doubt, please contact your CTC Analytics representative to verify the compatibility of the type or composition of solvents with the PAL3 System.

It is the user's (operator's) responsibility to handle hazardous chemicals or biological compounds, including (but not limited to) bacterial or viral samples and the associated wastes, safely and in accordance with international and local regulations.

Disposal



Do not dispose of this equipment or parts thereof unsorted in municipal waste. Follow local municipal waste regulations for proper disposal provisions to reduce the environmental impact of waste electrical and electronic equipment (WEEE).

European Union customers: Call your local customer service representative responsible for the PAL System for complimentary equipment pick-up and recycling.

Warning

The customer has to ensure that the PAL System has not been contaminated by any hazardous chemical or biological compounds including (but not limited to) bacteria or viruses.

Any part which has had direct contact with the analytical sample must be identified and must undergo an appropriate decontamination procedure prior to shipping for disposal. Potentially dangerous components are: Syringes, Valves, Loops, Tubing, Vials and Well Plates.

Any critical parts sent for disposal must be handled according to national laws for hazardous compounds.

The customer and the service engineer/technician are fully responsible for enforcing these requirements. CTC Analytics AG will hold the representative and/or customer responsible if these regulations are not observed.

Regulatory Compliance

CTC Analytics performs complete testing and evaluation of its products to ensure full compliance with applicable domestic and international regulations.

CTC Analytics declares, under sole responsibility, that the product as originally delivered complies with the requirements of the following applicable European Directives and carries the CE marking accordingly:

Low Voltage Directive: 2006/95/EC
EMC Directive: 2004/108/EC
Machinery Directive: 2006/42/EC

... and conforms with the following product standards:

Electromagnetic Compatibility (EMC):

EN 61326-1:2006 / IEC 61326-1:2005
EN 61000-6-2:2005 / IEC 61000-6-2:2005 |
EN 61000-6-3:2007 / IEC 61000-6-3:2006

Safety:

ANSI/UL 61010-1:2004 2nd Edition
CAN/CSA C22.2 No. 61010-1:2004 2nd Edition.

FCC Compliance Statement

CTC Analytics AG hereby declares that our product has been tested and complies with the requirements of FCC Part 15 Subpart B (Class B).

This device complies with part 15 of the FCC Rules. Operation is subject to the following two conditions:

- (1) This device may not cause harmful interferences, and
- (2) This device must accept any interference received, including interference that may cause undesired operation.

FCC Compliance Statement Note

This equipment has been tested and found to comply with the limits of Class B digital devices, pursuant to part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference in a residential installation. This equipment generates, uses and can radiate radio frequency energy and, if not installed and used in accordance with the instructions, may cause harmful interference to radio communications. However there is no guarantee that interference will not occur in a particular installation. If this equipment does cause harmful interference to radio or television reception, which can be determined by turning the equipment off and on, the user is encouraged to try to correct the interference by one or more of the following measures:

- Reorient or relocate the receiving antenna.
- Increase the separation distance between the equipment and receiver.
- Connect the equipment into an outlet on a circuit independent to that to which the receiver is connected.

Consult the dealer or an experienced radio/TV technician for help.

RoHS and WEEE Compliance

The Supplier Certificate is valid for the following product(s) as delivered by CTC Analytics:

PAL System including the optional modules

Referenced Documents

The following European Union directives are referenced in terms of inquiries, specifications, standard(s) or substance list(s):

- Directive 2002/95/EC on Restriction of the use of certain Hazardous Substances, RoHS
- Directive 2002/96/EC on Waste Electrical and Electronic Equipment, WEEE

Confirmation

We herewith confirm that the aforementioned product(s) does/do not contain any of the reportable substances (substances banned or to be declared) as listed in the referenced documents in concentrations above the limits as specified therein, or – if there are no concentration limits specified – in concentrations being intentionally introduced.

The design and production of the electrical and electronic equipment takes into account the dismantling and recovery of WEEE and its components and materials.

WEEE Marking

The products that are subject to the WEEE Directive shipped after July 1st 2006 (date of enforcement of WEEE Directive by the European Union) are compliant with the WEEE marking requirements.

See WEEE symbol above, section 'Disposal'. This symbol indicates that the product must not be disposed of with household waste.

Declaration of Compliance

All PAL Systems including the optional modules comply with RoHS and WEEE requirements. There is no substance to be declared.

Disclaimer

All information in this declaration is given to the best of our present knowledge and beliefs. The information given does not constitute a warranty within the meaning of warranty law.

Safety Alerts and Important Information

Make sure that you follow the precautionary notices presented in this guide and in any additional documentation such as the PAL User Manual. Safety and other special notices include the following:

Notice on the Proper Use of CTC Analytics Instruments.
In compliance with international regulations: Use of this instrument in a manner not specified by CTC Analytics AG could impair the safety and protective features of the instrument.

Warning

*For your safety, and in compliance with international regulations, the physical handling of this CTC Analytics instrument requires a team effort to lift and/or move the equipment.
This instrument is too heavy and bulky for one person alone to handle safely.
Before lifting or moving the PAL System, secure all moving parts first to avoid crushing hands or tipping over the unit.*

















Warning

This is the general safety warning symbol and safety alert word to prevent actions that could cause personal injury. It highlights a general hazard or signifies the presence of another specific safety symbol. This is usually followed by an appropriate safety precautionary message. When you see a safety alert on your instrument or in the documentation, please carefully read the safety instructions before proceeding.

note

Note that highlights information necessary to prevent damage to software, loss of data, invalid test results or instrument damage; might contain information that is critical for optimal performance of the system or other important information about a task.

Commonly Used Symbols

| Symbol | Description |
|---|--|
|  | Caution, or refer to User Manual |
|  | Caution, Risk of Needle-Stick Puncture |
|  | Caution, Hot Surface or High Temperature |
|  | Danger of crushing to fingers and hands |
|  | Laser Warning, Barcode Reader |
|  | Biological Hazard |
|  | Direct Current |
|  | Alternating Current |
|  | Protective Conductor Terminal, Ground |
|  | Fuse |
|  | Electrical Power ON Used with Main PAL Power Supply |
|  | Electrical Power OFF Used with Main PAL Power Supply |
|  | Caution, Risk of Electrical shock (high voltage) |
|  | Disposal: Do not dispose in municipal waste. Follow local waste regulations to reduce electrical and electronic waste (WEEE). |

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D. How to Use this Manual

note

This User Manual covers the HTC PAL and PAL HTC-xt Systems. Issues specific to the PAL HTC-xt model have been emphasized as such.

Follow the description given in this User Manual to install and operate PAL model "PAL HTC-xt," which, as compared to the HTC PAL model, differs only by its electronic board (APR Control-xt) and the firmware version necessary to operate the PAL-xt version and is thus not handled separately. Unless stated otherwise, this manual refers to all HTC PAL models.

The manual is divided into the following major sections:

- Safety Information
- HTC PAL Operating Instructions
- Specifications
- Product Warranty
- HTC PAL Description and Installation
- Troubleshooting
- Replacing Parts
- Maintaining PAL System
- Appendices

The "HTC PAL Operating Instructions" in section E are intended for infrequent PAL users or new users who already have experience using automated systems to perform standard analytical methods.

note

The HTC PAL must be installed and set up properly before the Operating Instructions in Section E can be used.

Users who are installing an HTC PAL system or HTC PAL accessories, or who need to adjust an installed system, should consult "HTC PAL Description and Installation" in Section F.

The Appendices provide useful information such as the Software Flow Chart, Definition of Terms, Injection Cycle parameter descriptions, or the HTC PAL accessories guide.

E. HTC PAL Operating Instructions

1. Using the Control Terminal

The following procedures present the key steps required to set up and process multiple groups of samples with the HTC PAL. They are intended to provide an overview for new users and a reminder for infrequent users. The HTC PAL and all accessories should be installed with Objects defined correctly. A syringe of the specific type called for by a particular method should also be installed.

Figure 1 illustrates the PAL control terminal and the conventions used to enter, edit, and view information.

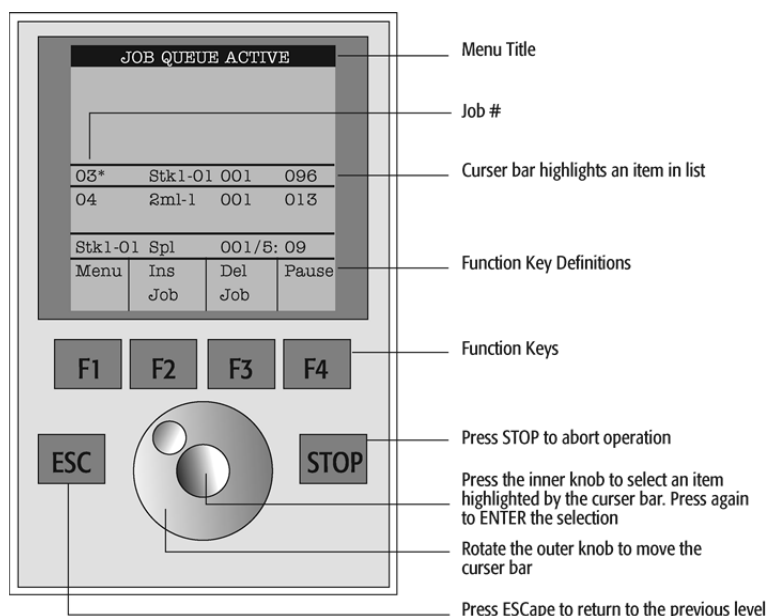


Figure 1. PAL Control Terminal and Conventions

1.1. Menu Screens

Different menu screens are displayed, depending on the HTC PAL operating status and the particular function being accessed by the operator. All menu screens have the same basic format. The menu title is displayed at the top of the screen. A list of items is displayed below the title. The date and time, or status, are shown in the highlighted area above the Function key labels on the bottom of the screen.

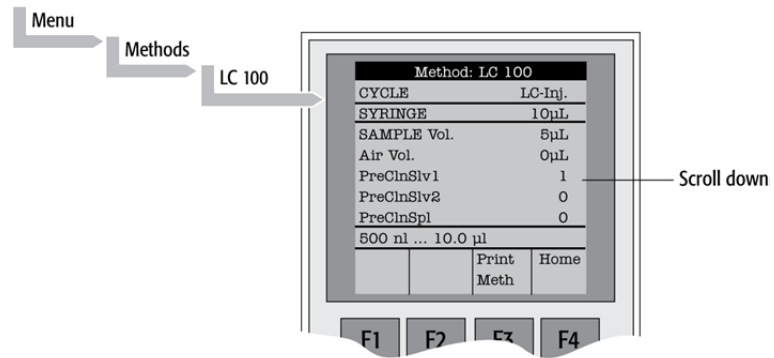


Figure 2. Accessing a Method Screen

1.2. Function Keys

Options for a particular menu are assigned to the corresponding function keys (F1, F2, F3 and F4) directly below each function key label.

Pressing the function key labeled **Home** will always return to the Job Queue menu.

1.3. ESCape and STOP Keys

Press the **ESC**ape key to return to the previous menu. Press the **STOP** key to abort the current Cycle, Job, or Job Queue.

1.4. Scroll Knob and ENTER Button

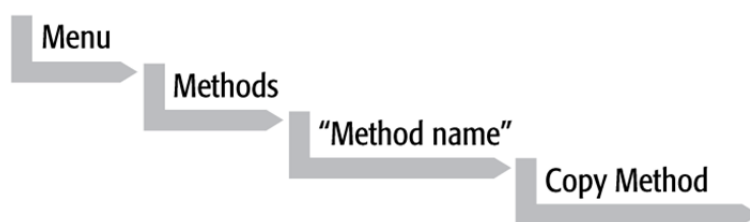
Rotate the outer knob to scroll through items in a menu list. To select a highlighted item press the central knob (**ENTER** button). Then use the outer knob to scroll through available options for that item or to change a numeric value. Then press the inner knob again to **ENTER** the displayed option. The inner knob is also used for other operations that require an **ENTER** operation to continue or complete an operation.

2. Methods

2.1. Creating Methods

Methods can be defined by the user and assigned names up to eight characters in length. **Methods** can be created, copied, edited, and viewed from the Methods menu. Methods can be viewed (but not edited) from the Job Queue menus.

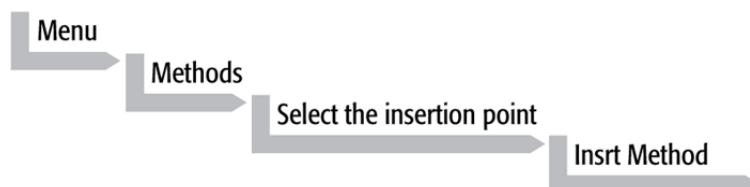
Methods are created by either copying an existing Method or creating a new Method.



To copy a **Method**, complete the sequence as follows. You will be prompted to enter a name for the new Method.

Use the scroll knob and the left-right arrow function keys (F2 and F3) to select among alphanumeric characters and spaces. Press the ENTER function key (F4) to accept the name.

To create a new Method, complete the following steps:



1. Assign and enter a new Method name as above. After a copy of the Method has been created, the Method parameters will display and can be edited. The Cycle and Syringe entries cannot be changed;
2. If the Method is new (i.e. added), select and enter a Cycle that is appropriate for the application;
3. Select the specific Syringe to be used by the Method;

note

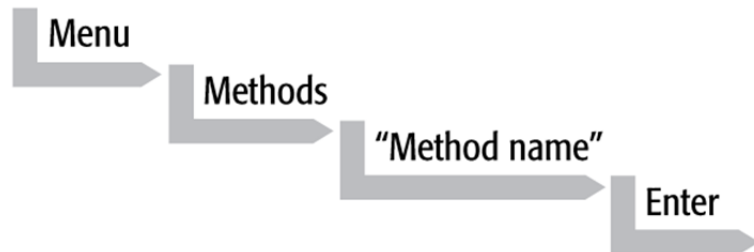
Once a Method has been created and saved, the Cycle and Syringe cannot be changed. To use a different Cycle or Syringe, a new Method must be created.

4. Assign Parameter values according to the application requirements. Consult Appendices point 3, HTC PAL "Injection Cycle Parameters" for details on specific items.

2.2. Edit / View Methods

Method parameters (excluding Cycle and Syringe) can be viewed and changed from the Method menu as follows:

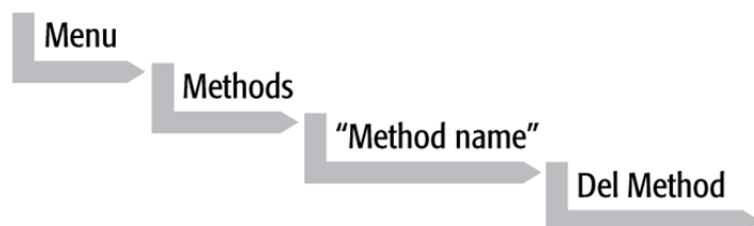
Complete the following menu selections:



1. Scroll to and select the parameter to be changed. Assign the new value and press the **ENTER** key;
2. Exit from Parameter List by pressing either the **Home** function key (F4) to return to the top-version Job Queue menu or the **ESCape** key to return to the previous menu;
3. Method contents may be viewed from the Job Queue displays by selecting the desired Job, pressing **ENTER**, followed by the View Method function key.

2.3. Delete Methods

Methods can be deleted from the Methods menu. Methods in use by an active Job cannot be deleted. Complete the following menu selections to delete a Method.



3. Job and Job Queue

A **Job** bundles the specified Tray with the designated vials (samples) and with the Method to run those samples. Another term often used for “Job” in the chromatographic field is “sequence”.

If more than one Job is prepared, the term **Job Queue** is used.

Before a Job can be activated the operator must verify that the Tray Type matches the specified Tray and vial size (type). This step is done in **Utilities** class.

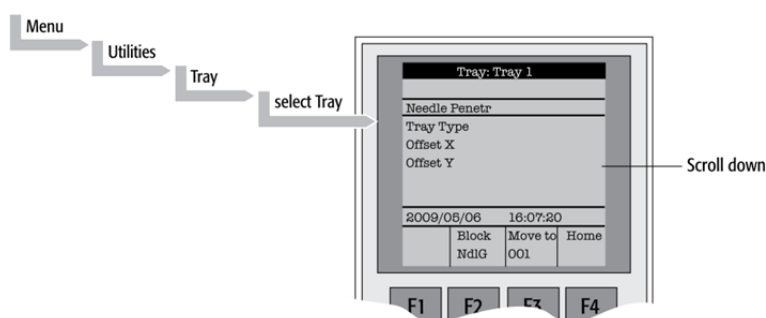


Figure 3. Verifying Tray with corresponding Tray Type

Select the corresponding Tray Type. By activating function key “F3” the injection unit can be moved to the first position and to another two corner positions to verify the correct selection of the Tray Type and teaching position.

3.1. Building and Starting a Job Queue

1. Power up the HTC PAL. The **JOB QUEUE** screen is displayed;

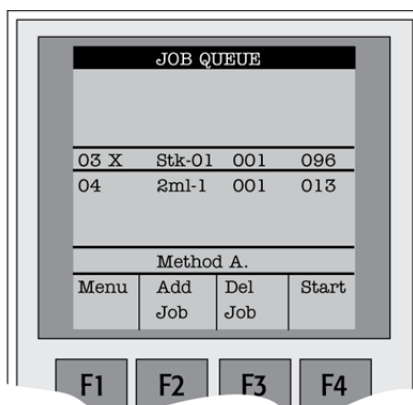


Figure 4. Example of Job Queue Screen

2. Load a sample Tray onto an available location in a Tray Holder or Stack. Note the corresponding Tray name;
3. Add a new Job for the Tray. Press the **Add Job** key to bring up the default Job;
4. For TRAY, select the Tray name (e.g. stk1-01) that corresponds to the location of the Tray that was just loaded;
5. Enter the **First** and **Last** sample number for this Job;
6. Select and enter the sample processing **Method** for this Job;
7. Press the **Home** function key (**F4**) to return to the **JOB QUEUE** screen;
8. To add additional samples to be processed, repeat steps 2 – 7;
9. If necessary, replace and/or clean the syringe (liquid versions only). Press the Menu key to see the available options for changing (**F1 Change Syringe**) and cleaning (**F2 Clean Syringe**). To completely remove air bubbles, the syringe should be primed manually. (See Section F. "Description and Installation", point 5.2, "Syringe Priming".);
10. If only one Job is to be processed, select the Job with the scroll knob. Press Start key. In the dialog box "**Select Job(s) to Process**" select one of the following options:
 - **All** (Entire Job Queue starting from the top)
 - **Selected** (Job selected with the cursor bar)
 - **Resume** (Continue with the next Job after the one aborted.)

3.2. Aborting a Job Queue

1. Press **STOP**;
2. Select one of the available options (**Continue**, **Sample**, **Job**, or **Job Queue**);
3. Select **Continue** to resume processing with the current sample;
4. Select **Sample** if there is a problem with only the current sample. Processing will resume with the next sample;

5. Select **Job** to abort processing all samples in the current Job. Processing will resume with the next Job. The aborted Job is marked with an **X**;
6. Select **Job Queue** to abort processing all Jobs. The JOB QUEUE screen will be displayed. The aborted Job is marked with an **X**.

3.3. Restarting an aborted Job Queue

1. Press the **START** key;
2. Select the **Resume** option. The Job after the last one marked as aborted will be started.

4. Utility Functions

Utility functions, selectable from the **Menu** screen, provide quick access to checking operations and parameters that may need to be changed. These functions are available for the actual Syringe, Trays, Injectors, and the Wash Station. They allow access to key functions without having to set up and execute a Method and Job.

note

If an item is used in the sample processing cycle, the appropriate Utility value will be overwritten by the Method value.

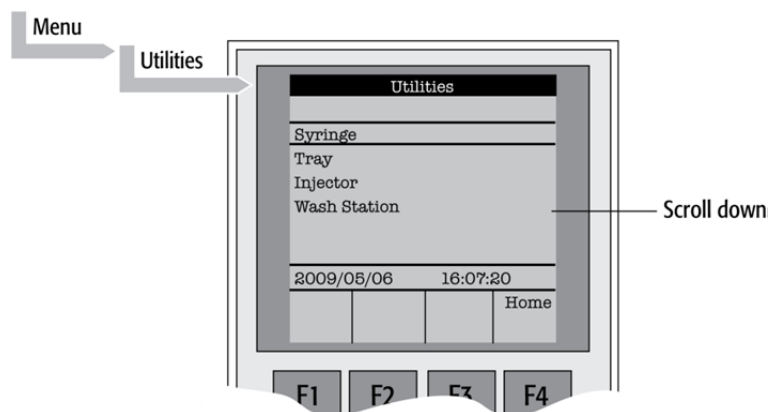


Figure 5. Selecting Utilities Functions

4.1. Syringe

The following functions are available by pressing a Function Key:

| Function Key | Description |
|---------------------|--|
| <i>F1</i> Chang Syr | The syringe is moved to a position in which the syringe assembly can be completely lowered to facilitate removal of the syringe adapter. The syringe can then be removed from the adapter and replaced. A prompt will be displayed to specify the new syringe. The syringe must be installed before pressing Enter . (See Section F. "Description and Installation", point 5 "Syringes".) |
| <i>F2</i> Clean Syr | This Function is used to clean or prime the syringe prior to use. After selecting F2 either Wash1 or Wash2 can be selected. |
| <i>F3</i> Set Pos | Set Pos is used to define the Chang Syr position. |
| <i>F4</i> HOME | The Injection Unit moves to its HOME position and the Job Queue Menu is displayed. |

The following Syringe items may be changed by selecting the particular item:

| Item | Description |
|-------------------|--|
| Actual ID | Indicates the identification number (ID) of the currently inserted syringe. If the syringe detection system is set to manual, the message "Syringe: No syringe" is displayed. |
| Fill Volume | This parameter serves to control the filling of the syringe. It can occur that air bubbles remain below the plunger after the first pull up. If the plunger is moved up and down several times (see Fill Strokes), these air bubbles are worked out. With this operation the syringe can be completely filled even when using very small sample volumes. |
| Fill Strokes | Number of fill strokes. All fill strokes, except the last one, use the selected fill volume. If the selected sample volume is greater than the fill volume, the sample volume is used for all fill strokes. If zero is selected the plunger is pulled up only once using the sample volume value. |
| Pullup Del | By using this item, a delay time can be selected between sample pullup and ejection while filling the syringe. When the plunger reaches the zero position during the fill strokes, the system waits half the Pullup Del time. This allows for an air bubble to float away from the needle tip. This feature is especially useful for removing any air bubble in the syringe and handling viscous fluids. |
| Fill Speed | Speed of plunger movement used in all syringe filling operations. |
| Eject Speed | Speed of plunger movement used in all syringe eject operations except sample injection. |
| Inject Speed | Speed of plunger movement for sample injection. Typically used for "Fill Strokes". |
| Plunger Chnge Pos | Plunger position during "Change Syringe" operation. The syringe plunger is moved to a position where the syringe can be removed and replaced. The value may be changed for different types of syringes. |

4.2. Tray

After selecting the particular Tray to be accessed, the following functions are available:

| Function Key | Description |
|----------------------|--|
| <i>F2</i> Block NdlG | F2 activates Needle Guide blocking. The option after activation is "Rel NdlG", releasing Needle Guide Blocking. It may be used to test the functionality of the solenoid that blocks the needle guide. |
| <i>F3</i> Movto nnn | This function serves as a quick check to determine if the X,Y,Z-coordinates are defined correctly for the selected Tray. To use this utility the selected Tray, including the sample vials, must be present. After pressing "Movto 001" the Injection Unit moves to sample position no.1. This procedure can be repeated for the last sample position in the first row and the last sample position. |
| <i>F4</i> HOME | The Injection Unit moves to its HOME position and the Job Queue Menu is displayed. |

The following Tray items may be changed by selecting the particular item:

| Item | Description |
|---------------|---|
| Needle Penetr | Needle penetration depth into the sample vial. The needle penetration depth for the selected Tray can be changed by entering the desired value. |
| Tray Type | The Tray Type which is selected for the Tray is shown. If the Tray enables the use of different Tray Types it can be changed at this position. |
| Tray Offset X | If necessary, a correction to the ideal X-position of "Position 1" can be made by using "Tray Offset X". |
| Tray Offset Y | If necessary, a correction to the ideal Y-position of "Position 1" can be made by using "Tray Offset Y". |
| Tray Offset Z | If necessary, a correction to the ideal Z-position of "Position 1" can be made by using "Tray Offset Z". |
| <i>dxRow</i> | Correction of any inclination of a Tray (plate) in the X-axis of a row (see Fig. 25 for details). |
| <i>dyRow</i> | Correction of any inclination of a Tray (plate) in the Y-axis of a row (see Fig. 25 for details). |
| <i>dzRow</i> | Correction of any inclination of a Tray (plate) in the Z-axis of a row (see Fig. 25 for details). |
| <i>dxCol</i> | Correction of any inclination of a Tray (plate) in the X-axis of a column (see Fig. 25 for details). |
| <i>dyCol</i> | Correction of any inclination of a Tray (plate) in the Y-axis of a column (see Fig. 25 for details). |
| <i>dzCol</i> | Correction of any inclination of a Tray (plate) in the Z-axis of a column (see Fig. 25 for details). |

Items displayed in "italic" are available beginning with PAL Firmware version 4.1.X.

note

A "staggered pattern" is selectable in firmware class "Tray Type". For details see section F. "Description and Installation", point 10.3.1 "Tray Type".

4.3. Injector

After selecting the particular Injector to be accessed, the following functions are available:

| Function Key | Description |
|---------------------|--|
| <i>F3</i> Movto Inj | The Injection Unit moves to the selected injector position. With this function, e.g. the injectors GC-Inj1, Waste, Waste2 and Flush can be accessed. By selecting the parameter "Needle Penetr" on the same screen, the Injector Needle Penetration value can be checked or changed. |
| <i>F4</i> HOME | The Injection Unit moves to its HOME position and the Job Queue Menu is displayed. |

The following Injector item can be changed by selecting the particular item:

| Item | Description |
|---------------|--|
| Needle Penetr | By selecting the parameter "Needle Penetr" the Injector Needle Penetration value can be checked and/or changed. To ensure reproducible sample injections and minimize carry-over it is critical that the needle penetration depth be accurately set. |

4.4. Wash Station

After selecting the specific Wash Station, the following functions are available:

| Function Key | Description |
|----------------------|--|
| <i>F3</i> Movto Wash | The injection unit moves to the selected Wash Station port. By selecting the Parameter "Needle Penetr" on the same screen the Wash Station Needle Penetration value can be checked or changed. |
| <i>F4</i> HOME | The injection unit moves to its HOME position and the Job Queue Menu is displayed. |

| Item | Description |
|---------------|--|
| Needle Penetr | By selecting the Parameter "Needle Penetr" the Wash Station Needle Penetration value can be checked and/or changed. |
| Rinse Time | If rinse time is activated (value > 0), the solenoid of a Fast or Active Wash Station opens for the specified time after the syringe needle has been removed from the wash port (after completion of the syringe wash cycle). The solvent flows into the wash port without the restriction of the needle; be aware of higher solvent consumption. |

The following Wash Station items may be changed by selecting the particular item:

| Item | Description |
|---------------|--|
| Needle Penetr | By selecting the parameter "Needle Penetr" the Wash Station needle penetration value can be checked and/or changed. |
| Rinse Time | If rinse time is activated (value > 0), the solenoid of a Fast or Active Wash Station opens for the specified time after the syringe needle has been removed from the wash port (after completion of the syringe wash cycle). The solvent flows into the wash port without the restriction of the needle; be aware of higher solvent consumption. |

4.5. Vial

After selecting the specific Vial type*, the following functions are available:

| Function Key | Description |
|---------------|---|
| F3 Movto Vial | The injection unit moves to the selected vial type. By selecting the parameter "Needle Penetr" on the same screen, the Wash Station Needle Penetration value can be checked or changed. |
| F4 HOME | The Injection Unit moves to its HOME position and the Job Queue Menu is displayed. |

* Available Vial types:

- Standard: Vial in Standard Wash Station for GC (front position).
- Fiber Exp: Position to block needle guide.
Mainly used for SPME application. See SPME User Manual.

| Item | Description |
|---------------|---|
| Needle Penetr | By selecting the parameter "Needle Penetr" the Wash Station needle penetration value can be checked and/or changed. |

4.6. Dilutors

After selecting the specific Dilutor, the following functions are available:

| Function Key | Description |
|---------------|--|
| F1 Prime | The Dilutor syringe is primed with solvent after activating the F1 function. |
| F2 Chang DSyr | Activating F2 moves the plunger of the Dilutor Syringe to standby position to allow easy access to change the syringe. |
| F4 HOME | The Injection Unit moves to its HOME position and the Job Queue Menu is displayed. |

The following Dilutor items can be changed by selecting the particular item:

| Item | Description |
|---------------|--|
| Syringe | Indicates the Dilutor side-port syringe inserted in the Z-axis. This function allows selecting another syringe size. |
| Syr Dilut Pos | Activating this function moves the plunger of the side port syringe up by the specified distance. This allows adjustment of the plunger tip of the side port syringe exactly above the lower side port (solvent inlet). This fine tuning is necessary after changing a side port syringe to allow unrestricted solvent flow. |
| Dilutor Syr | Indicates Dilutor Syringe is installed. If the syringe size is changed, this item must be adapted accordingly. The syringe-specific dimensions are coordinated by this function. |
| Prime Volume | A volume to prime the Dilutor Syringe can be specified. The allowed range can be fourfold higher than the actual syringe volume. This allows filling and emptying a dilutor syringe more often than just once. |
| Pullup Delay | Using this item permits selecting a delay time between solvent filling and ejection while filling (or priming) the syringe. |
| Fill Speed | Speed of plunger movement of Dilutor Syringe used in all syringe filling operations. |
| Eject Speed | Speed of Dilutor Syringe plunger movement used in all dilutor syringe eject operations. |
| Eject Delay | Using this item permits selecting a delay time between solvent ejection and filling while filling (or priming) the syringe. |

4.7. Tools

note

The Object class "Tools" is available with PAL Firmware version 3.0.X, 4.1.X. or higher.

After selecting the specific tool, the following functions become available:

| Function Key | Description |
|--------------|---|
| F1 Chk Offs | The item "Check Offset" can be used to verify the offset from the syringe needle tip to the tool tip. This item is mainly used for the MALDI tool; it is not active for the MHE tool. |
| F4 HOME | The injection unit moves to its HOME position and the Job Queue Menu is displayed. |

The following tool items may be changed by selecting the particular item:

| Item | Description |
|--------------|--|
| Teach Point | The reference point at which to teach the Object (Tool; MHETool) is selectable. In the case of the MHETool, no extra position is necessary. The Parking Station is the fix point. Select "None." |
| ToolOffset X | If necessary, a correction to the ideal X-position of the MHETool can be made by using "ToolOffsetXX". |
| ToolOffset Y | If necessary, a correction to the ideal Y-position of the MHETool can be made by using "ToolOffsetY" |
| ToolOffset Z | If necessary, a correction to the ideal Z-position of the MHETool can be made by using "ToolOffsetZ" A "ToolOffsetZ" of -48.0 mm is necessary to position the MHETool on the sample vial. |

5. Logfile

The PAL logfile cannot be read-out directly on the terminal display. However, the function key "F3" does allow a print out. A serial printer has to be connected to port "SER2" for the PAL System and to the port "SER1" for PAL-xt System. If a serial printer is not available use a serial/parallel converter.

6. Info Functions

Info functions, selectable from the Menu screen, provide quick access to information to be viewed. These info functions are available for the Hardware, Software Maintenance, Free Objects, and Free Items.

All items with the exception of "Maintenance" are read only.

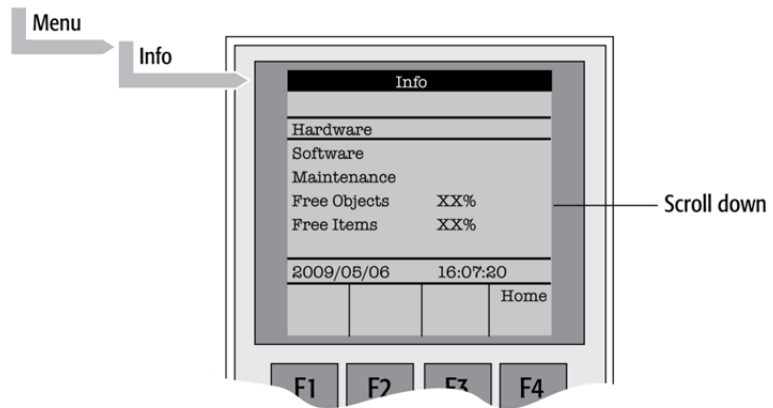


Figure 6. Selecting Info Functions

6.1. Hardware

| Item | Description |
|----------|---|
| CPU SNo | The serial number (SNo.) of the PCB "APR CPU" is displayed. |
| CPU ID | Version number of the PCB "APR CPU". |
| MOTIO ID | Version number of the PCB "APR CPU". |

6.2. Software

| Item | Description |
|-----------------|---|
| PAL Firmware | Firmware version of PAL System. |
| Head Firmware | Firmware version PAL Injection Unit. |
| Terminal FW | Firmware version PAL Terminal. |
| Altera Firmware | Firmware version of the Altera component. |

6.3. Maintenance

| Item | Description |
|--------------|---|
| PlgStrokeCnt | This is a counter for syringe plunger movements. The actual number of strokes is displayed. If the counter reaches the set limit (PlgStrkeLim) a warning is displayed at the next start of a job (run). The system continues but signals the user to verify syringe conditions. The counter can be set back to zero to restart. There is only one counter for a syringe. If syringe types are changed the system continues to count as if it were the same type. |
| PlgStrokeLim | An upper limit for the syringe plunger strokes can be set. |
| Inject Count | This counter monitors the number of injections. The number of injection valve switches is a helpful tool for the user to decide on a replacement of parts of the injector system. The actual number of injections (valve switches) is displayed. If the counter reaches the set limit (Inject Limit), a warning is displayed at the next start of a job (run) (Inject Limit). The same counter is used for injector penetrations with GC technique. |
| Inject Limit | An upper limit for the number of injections can be set. |

note

Counters for the plunger movement and injector penetrations are available with PAL Firmware version 2.5.X or higher.

6.4. Free Objects / Free Items

In addition to the core software, the PAL Firmware contains data for the "Firmware Objects". There are different classes of Objects, such as Syringes, Trays, Tray Holders, etc. Each class of Objects contains "Items". The items contain the actual data such as X-, Y-, Z-positions. The data are stored in a flash memory backed up by a battery. To optimize RAM and Flash memory use, a certain section of memory has been reserved by the software for each of the Objects and Object Items. The percentage shown in the "Info" section provides an indication as to how much of the reserved software space is still available.

7. Setup Functions

The **Setup** functions, selectable from the Menu screen, allow access to various functions for the PAL System. The "Sound", "Time" and "Objects" are basic functions used at installation or if changes have been made over time.

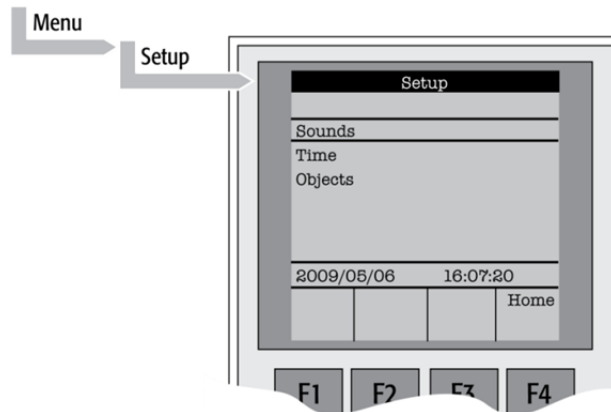


Figure 7. Selecting Setup Functions

7.1. Sounds

| Item | Description |
|-------------|--|
| Message Box | A specific dual beep tone signals that a pop-up window (Message Box) for user intervention appears on the screen. This beep signal can be turned on or off. |
| Warn Move | A beep sound is heard at the start of the PAL movement. It is advisable to keep this function turned on for safety reasons. |
| End Cycle | A beep sound is heard at the end of a cycle. Select as desired. |
| End Job | A beep sound is heard at the end of a cycle. Select as desired. |

7.2. Time

| Item | Description |
|--------------|--|
| Year | The "year" can be set for the PAL internal clock |
| Month | The "month" can be set for the PAL internal clock. |
| Day of Month | The "day" can be set for the PAL internal clock. |
| Hours | The "hours" can be set for the PAL internal clock. |
| Minutes | The "minutes" can be set for the PAL internal clock. |
| Seconds | The "seconds" can be set for the PAL internal clock. |

After setting or resetting the date and time, use the function key "F1" "Set Time" to store.

7.3. Objects

The various PAL Firmware Object classes can be selected and the functions most used by the user are directly accessible. For detailed listing see PAL Firmware overview in the appendices.

F. HTC PAL Description and Installation

1. General System Overview

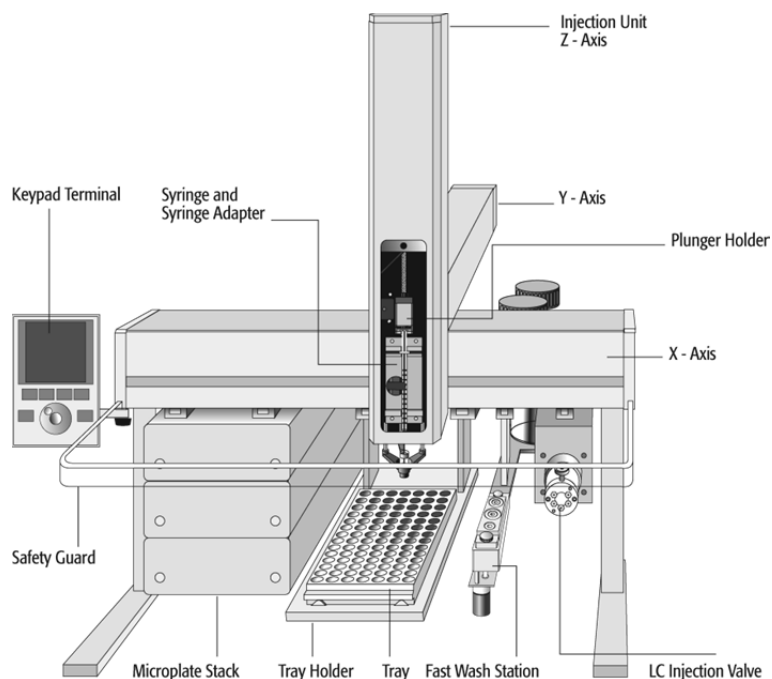


Figure 8. HTC PAL Major System Components

The standard HTC PAL includes the following hardware:

- 1 X-, Y-axes assembly;
- 1 Injection Unit, Z-axis;
- 1 Syringe kit for liquid injections;
- 1 Fast Wash Station for two different solvents;
- 1 Keypad terminal;
- 1 Safety Guard;
- 1 Standard standalone supports, 215 mm.

Optional TraySets (Tray Holder and Tray) and/or Stacks of various types and in different variations are required and can be added.

1.1. Specifications

1.1.1. Sample Capacity

- 98 x 2 mL vials per Tray
- 200 x 1 mL vials per Tray
- 32 x 10 mL / 20 mL vials per Tray
(up to three Trays can be configured)

- 108 x 2 mL vials per Stack Cooler 2 DW (2 x 54 vials 2 mL)
- 216 x 2 mL vials per Stack 4 DW (without cooling/heating)
- 2 Deepwell or microtiter plates per Stack Cooler 2 DW
- 4 Deepwell or microtiter plates per Stack 4 DW
- 6 Deepwell- or microtiter plates in Stack or Stack Cooler 6DW,
or 6 x 54 vials 2 mL
- 12 Microtiter plates in a Stack or Stack Cooler 12MT

1.1.2. Thermostatted Sample Tray

- Tray Cooler, 4 °C – 70 °C
- Stack Cooler 2 DW, 4 °C – 40 °C

1.1.3. Syringe Sizes

- 10, 25, 50, 100, 250, 500, 1000, 2500, 5000 µL

1.1.4. Liquid Injection Range

- 10 µL – 100 µL with standard 100 µL syringe
- Down to 0.1 µL with solvent sandwich technique
- Down to 0.5 µL with optional 4-port internal loop valve
- Up to 5000 µL with optional larger syringe and loop

1.1.5. Replicate Injections

- 1 – 99 from one vial

1.1.6. Minimum Sample Volume

- 1 µL from a 3 µL sample in 1 mL tapered micro vial
in liquid injection mode

1.1.7. LC Injector

- Electrically actuated fast switching Valve Drive,
6-port Injection Valve, VICI/Valco Cheminert, C2V-1006-CTC
(standard valve, other valves available on request)

1.1.6. Wash Station

- Fast Wash Station with two different wash solvents.
- Other types of Wash Stations are optionally available.

1.1.9. Standard Configuration

- Syringe Volume 100 µL
- Loop size 20 µL

1.2. Performance Specification

The performance specifications are available as part of a specific, separate document.

1.3. Electrical Specifications

| Parameter | Requirement |
|------------------------------------|---------------------------|
| Protection class ^a | Class I |
| Over voltage category ^b | Category II |
| Pollution degree ^c | 2 |
| Moisture protection ^d | Normal (IPX0) |
| Voltage | 36 VDC |
| Current | 3.2 A |
| Fuse | T6.3 A/250 V |
| PAL System Power Supply | |
| Input line voltage | Grounded AC, 100 to 240 V |
| Input line frequency | 50/60 Hz |
| Input power | 4 A |
| Output voltage | 36 VDC |
| Output current | 4.16 A |

a: Protection Class I:

Protection class describes the insulating scheme used in the instrument to protect the user from electrical shock. Class I identifies a single level of insulation between live parts (wires) and exposed conductive parts (metal panels), in which the exposed conductive parts are connected to a grounding system. In turn this grounding system is connected to the third pin (ground pin) on the electrical power plug.

b: Over Voltage Category II:

Over Voltage category II pertains to instruments that receive their electrical power from a local level such as an electrical wall outlet.

c: Pollution Degree 2:

This is a measure of pollution on electrical circuits that may produce a reduction of the dielectric strength or surface resistivity.

Degree 2 refers to normally only non-conductive pollution.

Occasionally, however, a temporary conductivity caused by condensation must be expected.

d: Moisture Protection:

Normal (IPX0) – IPX0 means that there is NO Ingress Protection against any type of dripping or sprayed water. The X is a place holder to identify protection against dust if applicable.

1.4. Physical Specifications

| Parameter | Requirements |
|------------------------|------------------------------------|
| HTC PAL Systems | |
| Height | 648 mm (25.5 in) |
| Depth | 385 mm (15.2 in) |
| Width | 545 mm (21.5 in) |
| Weight | 8 kg (18 lbs.) without accessories |

1.5. Operating and Environmental Requirements

| Parameter | Requirements |
|-----------------------------|---|
| Operating temperature range | 4 to 40 °C (39 to 104 °F) |
| Maximum relative humidity | 75%, non-condensing |
| Bench space | At least 24 cm (10 in.) at the rear. Access to power switch(es) and power cord(s). Clean, level and smooth surface. Solid bench plate. |
| Vibration | Negligible |
| Static electricity | Negligible |

1.6. Sound Pressure Level

| Parameter | Requirements |
|----------------------|--|
| Sound Pressure Level | Measured value: 62 dBA (PAL System used for measurement) One meter from the equipment in the direction of maximum sound pressure level. According to UL 610107A-1, 1 st edition, clause 12.5. Limit < 85 dBA dBA = "A weighted" sound pressure level |

1.7. Hardware and Software Requirements

1.7.1. Hardware Requirements

In order to operate a PAL System, the electronic control board must be compatible with the corresponding PAL System.

- PAL System operated with PAL Firmware version 2.X.X. or 3.0.X: the 'APR Control-HTC' boards is used.
- The PAL System can be operated with serial control only.
- PAL-xt Systems operating with PAL Firmware version 4.1.X or higher: 'APR Control-xt' board must be installed.
- The PAL-xt System can be operated through the serial or the TCP/IP protocol. See Section 8 'Establishing Communication with Computer'.

A PAL System can be upgraded to a PAL-xt System; for details contact your CTC Analytics representative.

For specific PAL hardware Modules, a minimum PAL Firmware version is required. For example, a PAL Dilutor Option requires the PAL Firmware version 2.3.X or higher, and a PAL DLW Option requires the PAL Firmware version 4.1.X or higher. Details are given either in the corresponding 'Addendum to PAL User Manual' or in the 'Addendum to PAL User Manual for PAL Object Manager Software'.

1.7.2. Software Requirements

The various PAL Software programs, such as PAL Loader or PAL Object Manager, are operated with Microsoft Windows Operating systems, such as Windows XP, Vista or Windows 7 Enterprise 32 or 64 bit. For details, see the corresponding 'Addendum to the PAL User Manual'.

The PAL System can be controlled using PAL control software, the Cycle Composer, or any data system software that controls the PAL using the Cycle Editor for PAL ICC interpretation (e.g. Analyst, ChemStation, Empower, EZChrom, MassLynx, Xcalibur).

For details on software requirements for integration of the PAL System with other data handling systems (CDS), contact your CTC Analytics representative or the manufacturer's representative of the other CDS software program.

1.7.3. Establishing Communication with Computer

The PAL System allows a serial communication protocol with a PC. As a new feature, the PAL-xt System provides LAN communication, also referred to as 'TCP/IP' or 'Ethernet'.

The PAL-xt System requires a dedicated 'APR Control-xt' board and PAL Firmware version 4.1.X or higher.

Setup within Corporate Network requires the support of the system administrator who has local administrator privileges for Windows and network setup. For the **network port 60000** the access has to be provided.

COM Port Settings

The port settings are normally defined in:
Windows\Control Panel\Device Manager\Ports.
The standard settings for the serial communication are shown in Figure 45.
It is important to understand that the application (e.g. PAL Loader Software)
does actively set the communication parameters, and the baud rate is set
for optimized use.

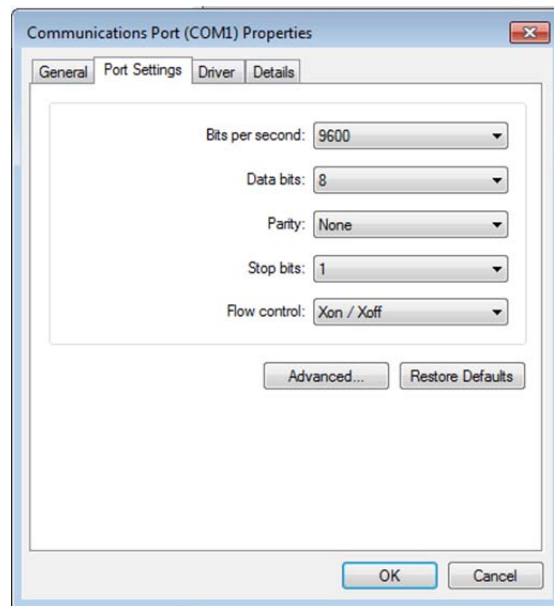


Figure 42. COM Port Settings

A quick way to check whether serial communication with the PAL System can be established is to use the PAL Loader software. For details see 'Addendum to PAL User Manual PAL Loader Software'.

1.8. Regulatory Compliance Requirements

The various regulatory compliances are described above in Section A. 'Safety Information'.

note

CTC Analytics AG reserves the right to make improvements and/or changes to the product specifications without notice.

2. Product Warranty

2.1. Statement of Limited Product Warranty

What does this Warranty cover?

CTC Analytics AG only warrants that its products comply with CTC Analytics AG's specifications.

This warranty covers defects in or failures of the PALrobot and major accessories, such as Peltier Stack and Valve Drives, occurring as a result of normal use or manufacturing defect. 'Normal use' means the use of the products in conformance with (i) all applicable local, state or federal laws, codes and regulations and (ii) the maintenance guidelines outlined in the PAL User Manual and the operating instructions provided by CTC Analytics AG.

What is NOT covered by this Warranty?

This warranty does not cover defects or failures resulting from damage caused by accidents, neglects, misuse or abuse, including (but not limited to):

- Improper or unauthorized maintenance, service or repair.
- Failure to follow the operating instructions provided by CTC Analytics AG.
- Improper or insufficient ventilation.

In addition, this warranty does not cover:

- Force Majeure: CTC Analytics AG is not liable for any events beyond reasonable control, including, but not limited to, fire, storm, flood, earthquake, explosions, riots, strikes, labor disputes, transportation embargoes or other contingencies beyond the control of CTC Analytics AG (i.e. 'acts of God' or 'Force Majeure').
- Defects and failures caused by any other circumstances on which CTC Analytics AG does not have any influence.
- Exposure to corrosive compounds.
- Parts exposed directly to liquids, such as valves, valve rotors or other valve components, tubing, syringes or any other part considered as a consumable and wear part.
- Minor defects or deviations from the product specifications, which are immaterial or negligible with respect to the value or the functioning of the product.

- Any requests, claims or whatsoever, for the reimbursement of subsequent damages, lost profits or damages as a result of an interruption in operation.

What is the Period of Coverage?

This warranty remains in effect for a period of one year from the date of installation. Additionally, the warranty request must be filed within the aforementioned warranty period.

What will CTC Analytics do to correct Problems?

CTC Analytics AG is represented by an authorized distributing or OEM partner in each respective country. These partners must be contacted by phone to request technical assistance or to diagnose the nature and possible cause of any malfunction. If we determine that the problem appears to result from a defect in the instrument or a module and if the defect is covered by this warranty, any necessary replacement module(s) will be shipped to the user's location. The replacement modules and shipping costs will be covered.

The replacement of a module does not extend the warranty period as set out under point 'What is the Period of Coverage'.

What will CTC Analytics NOT do?

A service representative will not be sent to perform service work at a customer's location before confirmation by the responsible CTC Analytics' manager that this is necessary.

Only if the problem cannot be resolved with telephone support and replacement of modules will a service representative be dispatched on site. CTC Analytics AG will not replace 'consumable' parts, as explained above under point 'What is NOT covered by this Warranty'.

How can you obtain Technical Assistance?

To obtain technical assistance, call the CTC Analytics representative from whom the instrument was originally purchased.

Please be prepared to provide the serial number of the instrument and discuss the problem in detail, and be willing to perform recommended tests and adjustments to help us determine the probable cause and find a solution to the problem.

What must you do to keep the Warranty in effect?

To keep this warranty in effect, the user must take care to avoid accidents, misuse and abuse, as described under point above 'What is NOT covered by this Warranty?'

The maintenance guidelines outlined in the PAL User Manual must be followed. Preventative Maintenance (PM) or any service or repair task on the instrument must only be carried out by authorized CTC Analytics personnel.

Normal responsibilities of the User

The user must report any problem with the equipment immediately after discovery to the representative of CTC Analytics AG and assist technical support personnel in diagnosing and attempting to resolve the instrument malfunction. It is expected that the user will cooperate by installing any replacement parts (modules) that have been sent and will return any exchanges or unused replacement parts to the representative of CTC Analytics AG, or according to prior agreement.

How do local Laws of various Countries or States relate to this Warranty?

This warranty statement from CTC Analytics AG gives the user specific rights. The user may also have other rights which vary from country to country or from state to state.

How does this Warranty relate to Warranty statements of various distributing or OEM partners?

This warranty statement from CTC Analytics AG gives the user specific rights. If the warranty statement from your retailer, distributor, or OEM is broader, the added value of that warranty may be valid for the user. This, however, is not the responsibility of CTC Analytics AG, but solely that of the specific distributor or OEM partner.

3. Installation

3.1. Unpacking the Components

A HTC PAL system is shipped in one box. The box contains the X,Y-axes assembly, the Injection Unit, the Keypad Terminal, standalone Supports, connecting cables, Power Supply, Syringe kit, Wash Station assembly, Safety Guard and miscellaneous parts.

All optional parts, such as TraySet, Stack Cooler, second valve drive assembly, etc., are shipped in a separate box.

1. Open the box and first remove the accessory boxes and the Injection Unit before attempting to remove the X-, Y-axes assembly.
2. Carefully lift the X,Y-axes assembly and remove it from the box. Hold the Y-axis in place while the assembly is being removed from the box. Set the X,Y-axes assembly on a bench.
3. Unpack the remaining small boxes and any other accessories.
4. When placing the HTC PAL onto a stable surface, make sure that no objects interfere with either the Y-axis or the Injection Unit throughout the entire range of potential movement.

3.2. Assembling the HTC PAL

Before beginning the assembly process, determine approximately where the LC injection valve and keypad terminal will be located. The terminal may be mounted on either side of the X-axis.

1. If a Stack (a Tray Holder with multiple drawers) was shipped with the HTC PAL, loosen the Torx screws on the two mounting clamps located on top of the stack;
2. Move the X/Y-Carriage to the center of the X-axis and temporarily place the X-axis assembly on top of the Stack with the mounting clamp teeth fitting into the grooves on the bottom of the X-axis;

note

For HTC PALs without a Stack, support the X/Y-Carriage in a suitable manner (a sturdy cardboard box can be used) before attempting to install the legs.

3. Install the legs near the ends of the X-axis. Loosen the Torx screws on the mounting clamps and then fit one leg into the grooves in the X-axis. Be sure that the clamps fit completely into the grooves. Tighten the Torx screws until the legs are firmly in place;
4. Double check whether the leg claws are correctly attached to the X-axis (see Fig. 9).

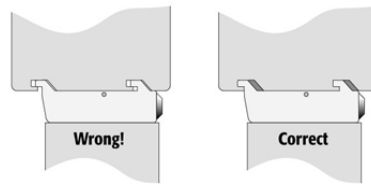


Figure 9. Attachment of Mounting Claws

3.2.1. Installing the Injection Unit

note

Installation of the Injection Unit should be done carefully. When installing it for the first time, have someone hold it in place while the mounting screws are inserted.

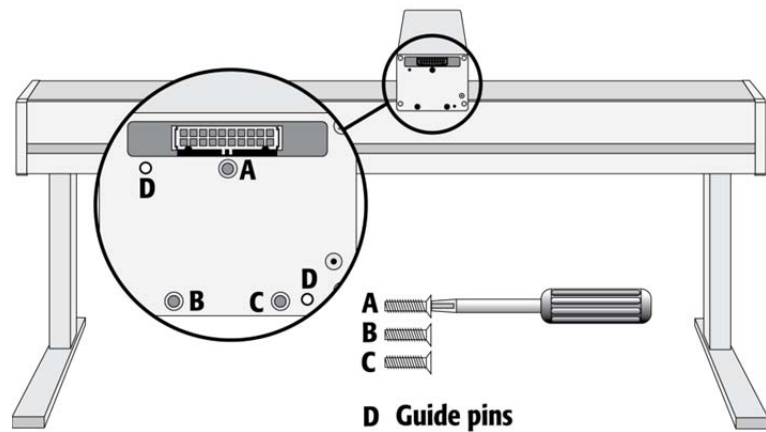


Figure 10. Attaching the PAL Injection Unit

1. Remove the three Torx mounting screws **A**, **B**, and **C**, used to fix the Injection Unit to the Y-axis;
2. Connect the ribbon cable **A** protruding from the front end of the Y-axis to the corresponding connector on the Injection Unit (see Fig. 11);

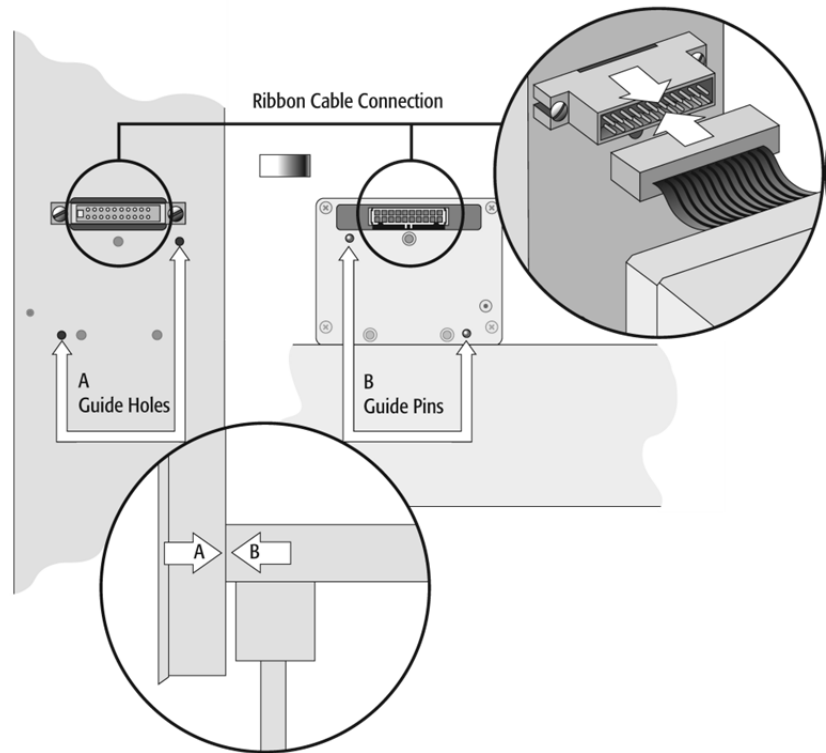


Figure 11. Connecting the Injection Unit Ribbon Cable

3. Hold the Injection Unit in place against the Y-axis. Make sure the two locating pins on the Y-axis fit into the two guide pin holes on the Injection Unit;
4. Place one of the screws onto the end of the supplied Torx driver. Slide the clear plastic cover on the Injection Unit all the way to the top. Locate the three large holes in the black anodized frame attached to the Z-axis inside the Injection Unit. Slide the frame upwards until the top hole is centered on the top threaded hole at the end of the Y-axis. Insert and securely tighten the Torx screw A (see Fig. 12);

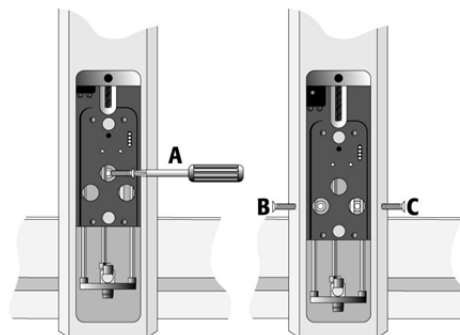


Figure 12. Inserting the Injection Unit Mounting Torx Screws

5. Install the two remaining Torx screws **B**, **C** in the left and right mounting holes, respectively. It may be necessary to move the elastic cord slightly to the left to insert the Torx screw **C** into the right-hand hole.

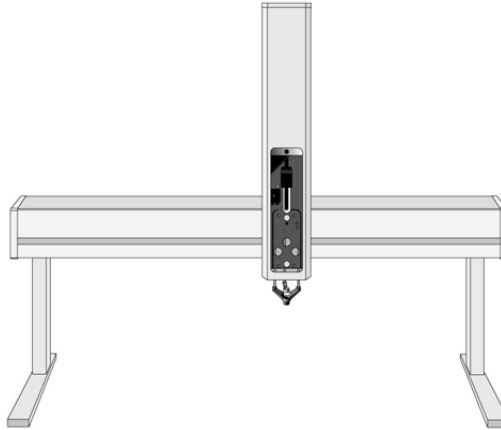


Figure 13. HTC PAL with Injection Unit and Standalone Supports

3.2.2. Installing the Keypad Terminal

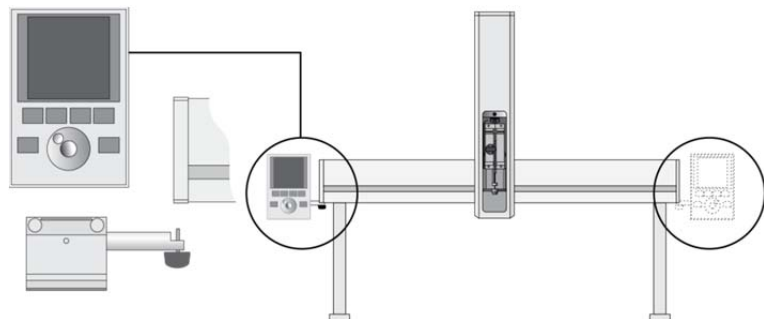


Figure 14. Installing the Keypad Terminal

1. Install the safety shield on the left and right sides to the outside of the X-axis. Use the provided, longer thumbscrew on the side where you plan to install the keypad;
2. Install the Keypad mounting bracket on either the right or left side of the X-axis;
3. Connect one end of the white coiled cable (Part No. SS8J-700) to the Keypad and the other end to the **TERMINAL (SER3)** interface jack on the rear side of the X-axis. For details see Figures 19 or 20;
4. Place the Keypad terminal onto its mounting bracket.

note

Do not interchange the Terminal with LAN cable connectors.

3.2.3. Installing the Power Supply

1. Locate the power supply, the DC power cable (Part No. RS3M-2000), and the AC power cable;
2. Set the power supply switch to the OFF position;
3. Connect one end of the DC power cable to the power supply and the other end to the POWER connector at the rear side of the X-axis;
4. Connect the female end of the AC power cable to the power supply. Then connect the male end to an AC power outlet.

3.2.4. Installing the LC Injection Valve

1. Locate the blue valve drive. It will have one clamp that is identical to other Object clamps (see Fig. 15). Loosen the clamp as described above;

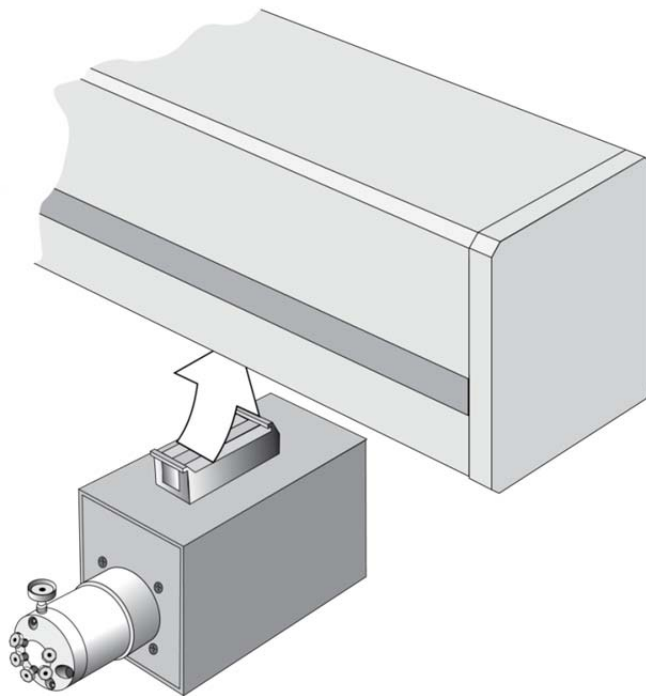


Figure 15. Installing the Injection Valve Drive

2. Attach the valve drive to the X-axis and tighten the mounting screw;

note

To avoid delay volume between sample injection point and detection, the injection valve should be located near the detection device.

3. Connect the control cable from the valve drive to AUX1;

note

The installation of another type or multiple Valve Drive(-s) is described in the Addendum to PAL User Manual "Valve Drives and Valves".

4. The injection valve and rotor are pre-installed on the valve drive.

3.2.5. Installing the Fast Wash Station

1. Attach the Wash Station assembly to the Solvent bottle holder;

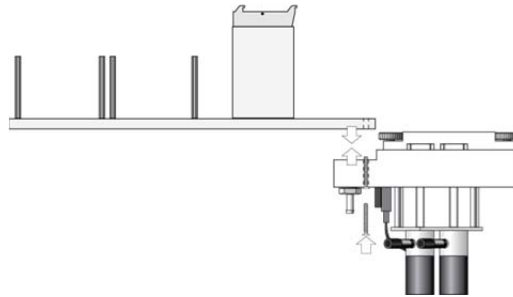


Figure 16. Installing the Fast Wash Station

2. Loosen the screw on the Fast Wash Station mounting clamp;
3. Attach the Fast Wash Station to the X-axis as close as possible to the Injection Valve. This will minimize the time required to move between the two positions;
4. Tighten the mounting screw;

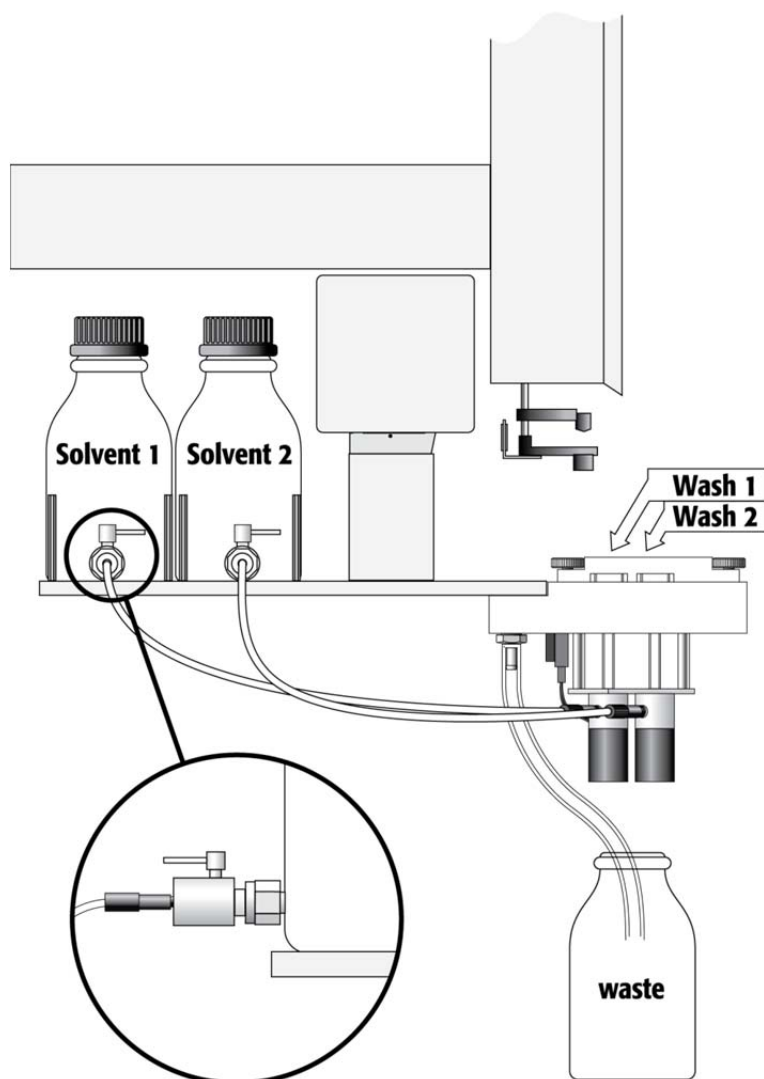


Figure 17. Fast Wash Station Assembly

5. Locate the white PTFE fittings and two lengths of PFA tubing that connect the Wash Station valves to the wash solvent reservoirs;
6. Place the reservoirs onto their holders and attach the tubing and fittings;
7. Attach one end of the supplied polyethylene tubing to the Wash Station Waste port. Place the other end of tubing into a waste reservoir (not supplied), which is positioned lower than the Wash Station assembly. Stretch the PE tubing to make sure that no used wash solvent is trapped before the Waste Reservoir;

note

The waste reservoir MUST be placed in a lower position than the Wash Station assembly.

8. Connect the control cable between PAL connector "Wash Station" and the four-pronged connector located on the Fast Wash Station assembly. See Figure 18 below and Figures 21/22 for details.

note

For a PAL HTC-xt, the cable can be connected either to the INTERFACE 2 connector or to the small round connector, labeled "Wash Station". Both connectors provide the same functionality. The cable determines the connector.

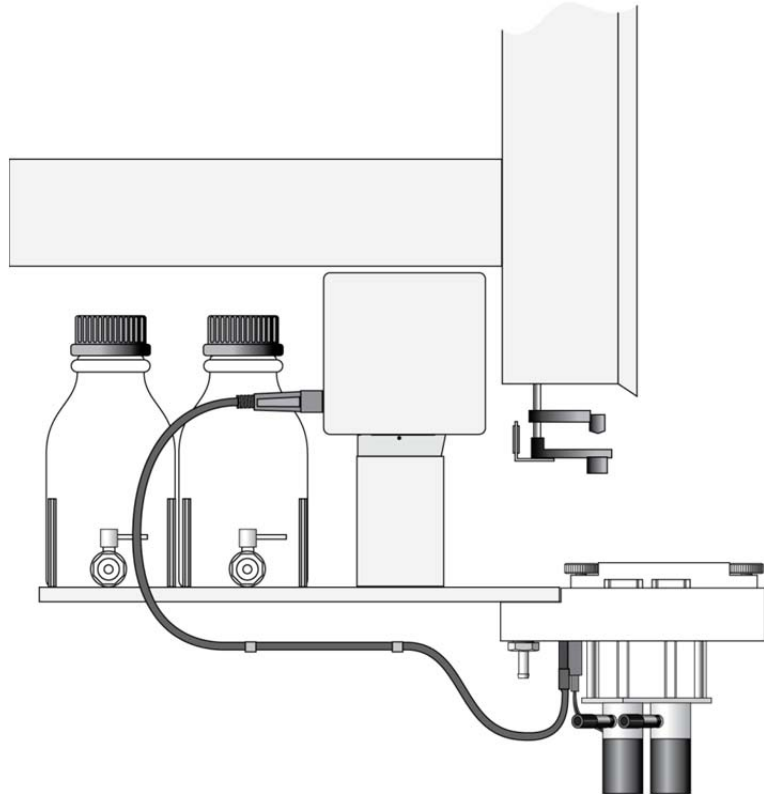


Figure 18. Electrical Connection, Fast Wash Station

note

If other types of Wash Stations are installed, such as Active Wash Station, follow the instructions in the specific Addendum of the PAL User Manual.

3.2.6. Installing a Microplate Stack

1. If a Stack (a Tray Holder with multiple drawers) was shipped with the HTC PAL, loosen the two Torx screws on the two mounting clamps located on top of the Stack. The example below shows the two stack models with 3 and 6 drawers;

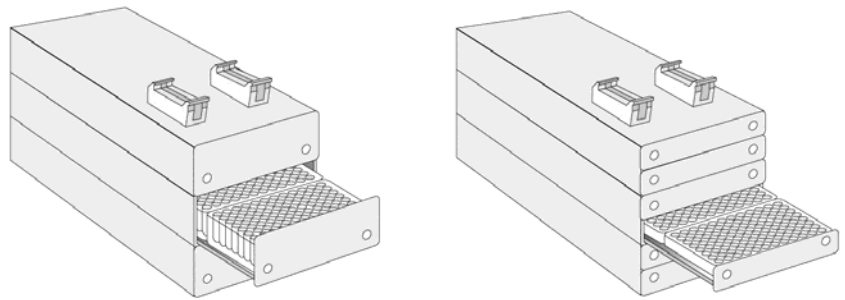


Figure 19. Installing a Microplate Stack with 3 or 6 Drawers

note

Installation of Stack and Tray Cooler is described in detail in the Addendum to the PAL User Manual "Stack and Tray Coolers".

2. Carefully lift the X-axis assembly on top of the Stack with the mounting clamp teeth fitting into the grooves on the bottom of the X-axis;
3. Be sure that the clamps fit completely into the grooves. Alternately tighten the two Torx screws until the two mounting clamps are firmly in place;
4. Double check whether the Stack clamps are correctly attached to the X-axis (see Fig. 9).

3.2.5. Installing a Tray Holder

1. If a Tray Holder was shipped with the HTC PAL, loosen the two Torx screws on the two mounting clamps located on top of the Tray Holder legs;

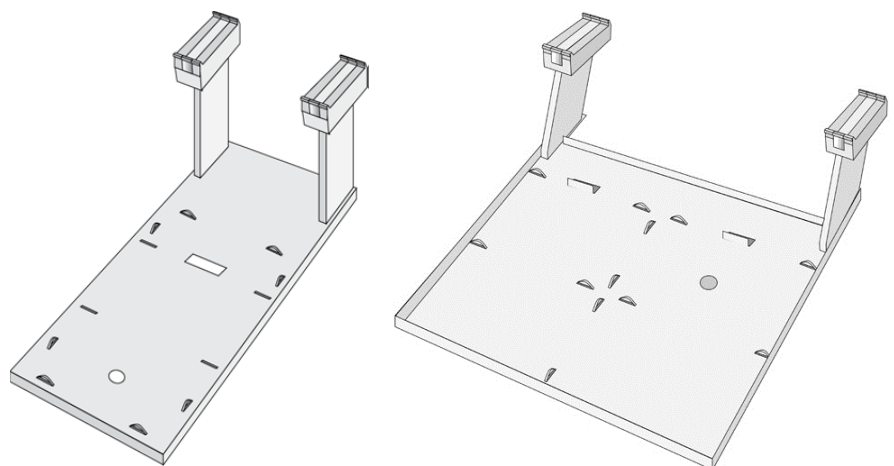


Figure 20. Installing a Tray Holder

2. Install the Tray Holder with the mounting clamp teeth fitting into the grooves on the bottom of the X-axis;
3. Be sure that the clamps fit completely into the grooves. Alternately tighten the two Torx screws until the two mounting clamps are firmly in place;
4. Double check whether the two Tray Holder clamps are correctly attached to the X-axis (see Fig. 9).

3.3. Electrical Connections

note

*Always switch OFF the PAL power supply before connecting or disconnecting any HTC PAL accessories cable!
Do not interchange the Terminal with LAN cable connectors.*

Before defining the HTC PAL Object positions, make sure the LC Injection Valve, Fast Wash Station and Keypad Terminal are correctly connected to the HTC PAL X-axis rear side. (See Figs. 21 or 22.)

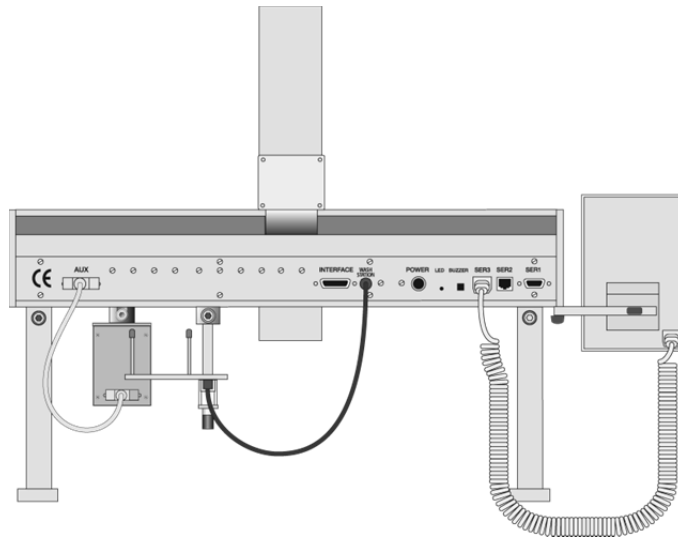


Figure 21. Electrical Connections for HTC PAL System

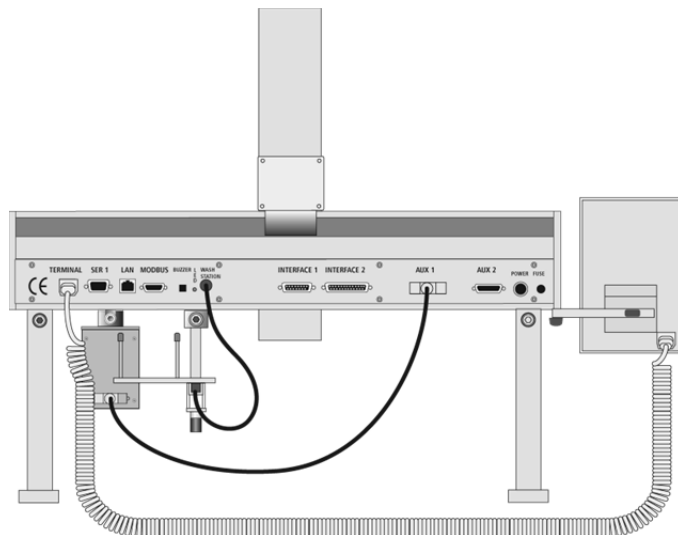


Figure 22. Electrical Connections for PAL HTC-xt System

note

For a PAL HTC-xt, the cable from the Wash Station can be connected either to the INTERFACE 2 connector or to the small round connector, labeled "Wash Station". Both connectors provide the same functionality. The cable determines the connector.

4. HTC PAL Object Positions

4.1. Defining Object Positions

note

Remove the Syringe Adapter from the Injection Unit before performing the following steps.

The objective is to define the Reference Positions for all HTC PAL Objects. Make sure the Tray Holder(s), Valve Drive(-s) and Wash Station are properly mounted to the PAL X-axis. The following description is an example of how to teach the reference position for a Tray Holder. The described procedure is **common** to all HTC PAL Objects.

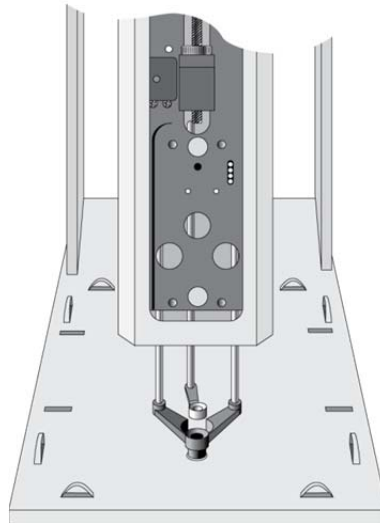
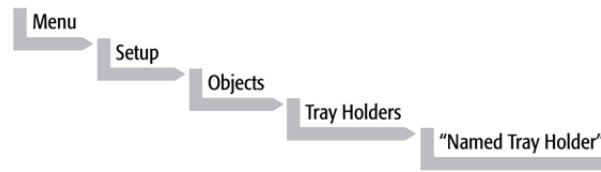


Figure 23. Object Reference Position

For a Tray Holder, the **Reference Position** is a hole (slightly larger than the lower needle guide) in the base plate of the holder. The lower needle guide should be centered in the hole with the bottom of the needle guide flush with the bottom of the base plate (see Fig. 23).

1. Switch ON the PAL power supply;
2. Observe the keypad display. The model name HTC PAL will display along with the software version number. The Job Queue menu screen will then display;

3. When the "Job Queue" menu displays, complete the following sequence (common to all objects):



where "Named Tray Holder" represents a predefined Tray Holder, (e.g. THldr1 or Stack1).

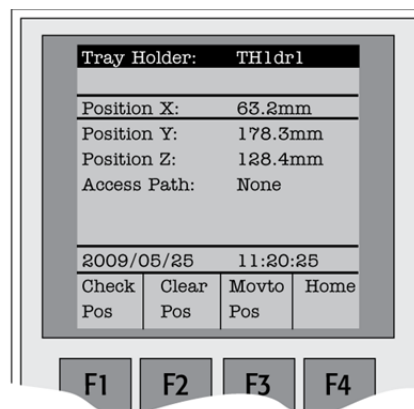


Figure 24. Menu Screen Object Tray Holder

4. After selecting "Named Tray Holder", the X-, Y-, Z- positions associated with the object will be displayed (see Fig. 24);
5. Highlight item **Position X** with the cursor bar and press **ENTER**. The Injection Unit will move to the previously defined X-axis position;
6. Rotate the outer knob to adjust the X-axis position to the Tray Holder reference position;
7. Press the inner knob to **ENTER** the **Position X** value;
8. Repeat steps 5 – 7 for **Position Y** and **Position Z**;
9. If the F3 button "**Moveto Zero**" is activated, the Injection Unit will move to the **HOME** position;
10. Verify the defined X-, Y-, Z-positions by pressing F1 "**Check Pos**".

note

PAL Firmware version 3.0.X permits correcting for an inclined surface, for example a Tray Holder or Tray where the Z-axis position in front differs from the rear position. For applications such as the PAL MALDI Option, perfect alignment of the MALDI tip is vital. This compensation for the Z-axis position is provided in the firmware class "Tool".

The release of PAL Firmware version 4.1.X makes possible the correction of all three axes, X-, Y-, Z, in the firmware class "Tray." The correction of the inclination can be made for a tilted Tray in the direction of the row and/or the column. Teaching is possible in the "Utilities" section by using the path:

Menu/Utilities/ Trays.

Figure 25 illustrates possibilities of correction. Details for teaching are given below.

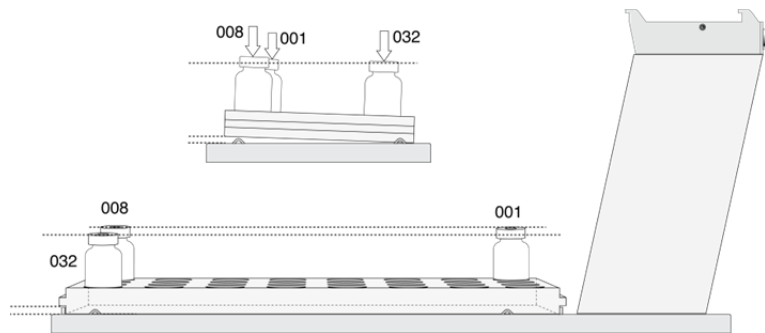


Figure 25. Inclined Tray, Corrections for X-, Y-, Z-Axes

Note that these functions are not available for the HTC PAL if operated solely on PAL Firmware version 2.4.X or higher, but neither with firmware version 3.X.X. nor with version 4.X.X.

4.2. Description of Object Positions

4.2.1. Tray Holder (e.g. THldr1)

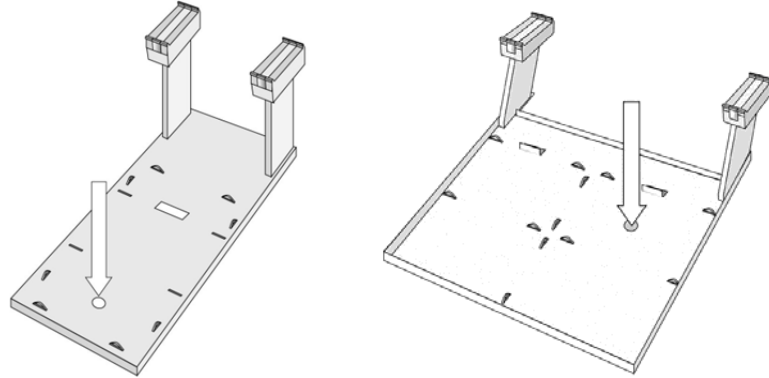


Figure 26. Tray Holder Reference Position

For a Tray Holder, the **Reference Position** is a hole in the base plate of the Holder. The lower needle guide should be centered in the hole with the bottom of the needle guide flush with the bottom of the base plate.

Figure 26 shows the example of a Tray Holder for a single Tray (e.g. "THldr1" for "Tray 1") and a Tray Holder for four Trays (e.g. "Tray 1" with Tray Type "VT54", "DW96" or "MT96", etc.).

4.2.2. Tray Holders Stack or Stack Cooler with 3 or 6 Drawers

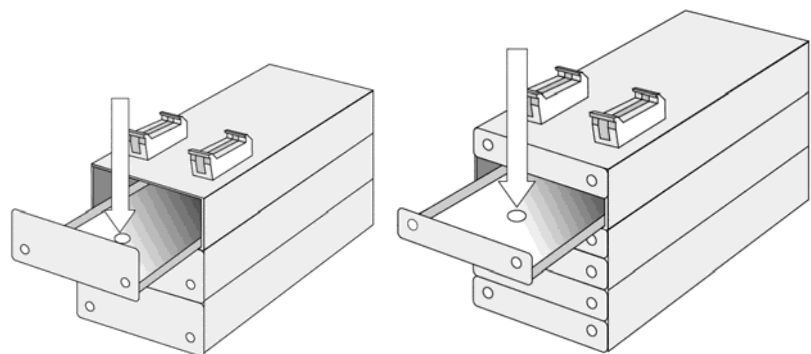


Figure 27. Stack Reference Position

The **Reference Position** for a Stack or Stack Cooler is identical. The reference position in the case of a 3-Drawer Stack is a hole in the upper drawer and in a 6-Drawer Stack in the second drawer from the top (same height level), as shown in Figure 27.

4.2.3. Trays

In general it is not necessary to teach a Tray position. The Tray Holder has a teaching position, as described above. A Tray is assigned to the Tray Holder. The numbers (values) for the relevant items are stored in the firmware object "Tray". To complete the combination of a Tray Holder and a Tray, it is necessary to assign the corresponding "Tray Type" to the "Tray." The "Tray Type" contains the geometric data for the Tray and information, such as how many samples are in a row and a column in the Tray. A Tray Type defines the pattern and sampling sequence of sample location within a Tray. For details, see below.

As described above, the Tray is physically placed in the Tray Holder, the firmware assigns the Tray to the Tray Holder and the Tray Type to the Tray. This is routine procedure as long as no special circumstances need be considered, such as customized Trays or Tray Types.

PAL Firmware version 4.1.X now makes a correction possible if the Tray surface is not exactly horizontal and planar but is inclined in one or more axes. At version 4.1.X this is standard and a dialog window pops up the moment the Tray has been checked-out at the corners to verify vial positions and heights. How to correct a possible inclination is explained below.

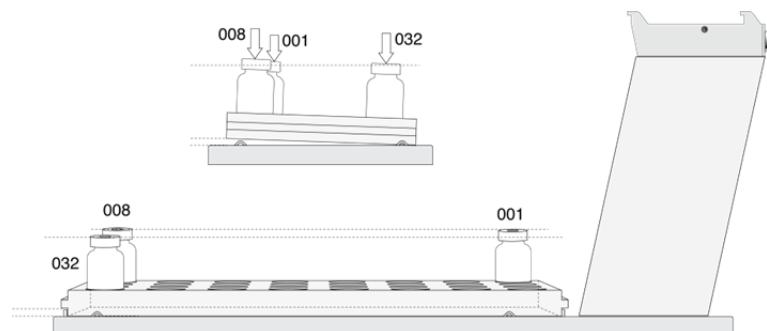


Figure 28. Demonstrating a possible Inclination of Tray in X-, Y-, Z-Axes.

4.2.3.1. Definition of a Tray Row and Column

The PAL System defines **Rows** and **Columns** by the order in which samples are treated. A "Row" is not associated with an X- or Y-axis. The definition is visualized below with Tray Type VT32 and DW96:

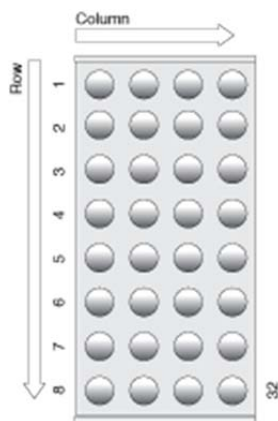


Figure 29. Tray Type VT32

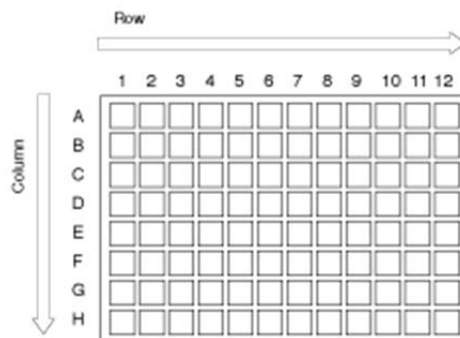


Figure 30. Tray Type DW96

4.2.3.2. Correction for Sample Position in X-, Y- or Z-Axes PAL Firmware version 2.X.X.

The following description of the correction is done by using the path to the "Utilities" section.

After selecting the Utilities function "Trays", verify whether the Tray Type assigned corresponds to the Tray placed into the Tray Holder. If this is verified, the vial positions can be checked at the three corners of the Tray. This is activated by the "F3" function key.

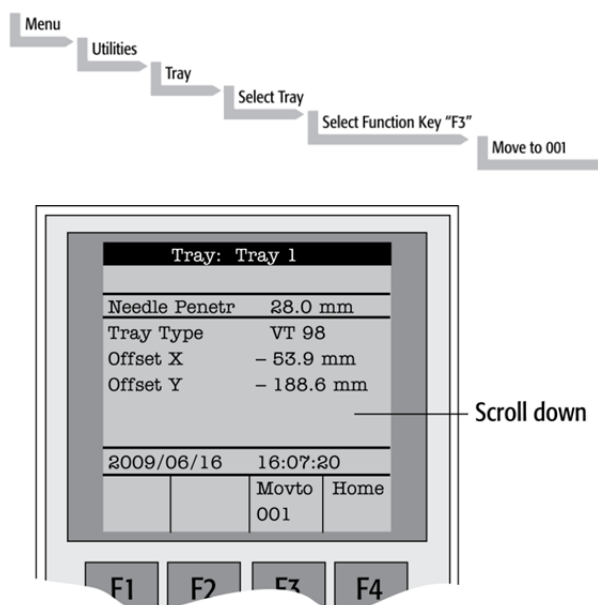


Figure 31. Utilities Function "Trays"

The Injection Unit moves to Tray position no. 001. With the help of the inserted syringe it is possible to check the optimized position of the needle tip matching with the vial or well position.

In case the position is off, make corrections in X-, Y- or Z-positions.

Continue with function key "F3" to move to the next corner to verify this position. If the position matches, continue with function key "F3" to move the unit to the third corner position.

If a deviation of the ideal position is observed in second or third corner, the corrections have to be made on the position no. 001. The offset is bound to position no. 001.

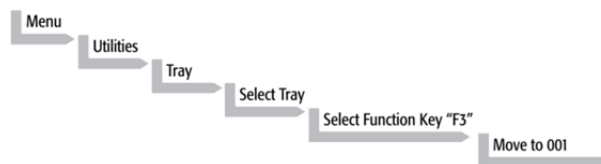
note

Activating one of the parameters Offset X-, Y-, or Z-axis at the positions of second or third corner can bend the syringe needle.

**4.2.3.3. Correction for Inclination in X-, Y- or Z-Axes
PAL Firmware version 4.1.X or higher**

The following description of the correction is done by using the path to the "Utilities" section.

After selecting the Utilities function "Trays", verify whether the Tray Type assigned corresponds to the Tray placed into the Tray Holder. If this is verified, the vial positions can be checked at the three corners of the Tray. This is activated by the "F3" function key.



A dialog window opens, displaying a note to "Adjust offset X-, Y-, Z for Position 001". Continuing in this dialog will provide the user the opportunity to adjust all three axes perfectly by the top of the vial. Please note that this step is only valid for position number 001.

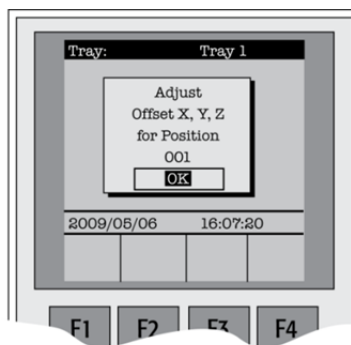


Figure 32. Adjusting "Offset X,Y,Z" for Tray Position 001

To check the next corner of the Tray, activate function key “F3” again, example Tray Type “VT32”, position 008.

The next information provided by the pop-up window asks whether to correct a possible inclination of the “Row”. Continuing the dialog provides the user the opportunity to adjust the three axes perfectly to match the vial top – or in case of a well-plate, the top of the plate.

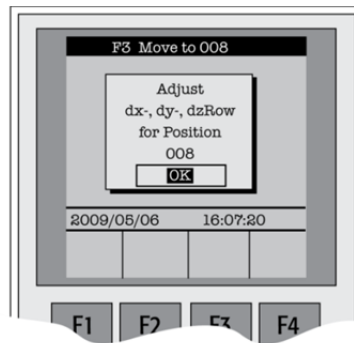


Figure 33. Adjusting Row Inclination at second Tray corner position

The last step will be to move to the next corner of the Tray by again activating function key “F3”. This will be position 32 in the example of Tray Type “VT32”.

A possible inclination of the Tray column can be corrected in the same manner as described above.

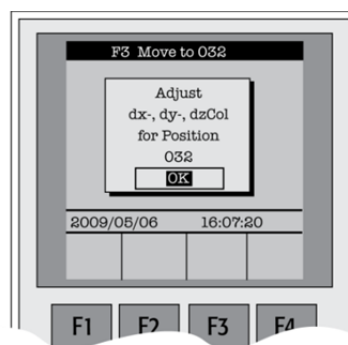


Figure 34. Adjusting Column Inclination at Third Tray Corner Position

The three corner points are now adjusted for a possible inclination of the Tray in any axis. A possible deviation from an ideal axis position for the other vials, caused by variance from the horizontal, is interpolated by the system without further teaching.

note

For routine work using standard vials it is not necessary to compensate for a possible inclination as long as the vial detection is within the “Z-Tolerance” range.

4.2.4. Wash Station: Wash1/Wash2 Reference Point

note

If positions of other types of Wash Stations, such as Active Wash Station, have to be taught, follow the instructions in the specific Addendum of the PAL User Manual.

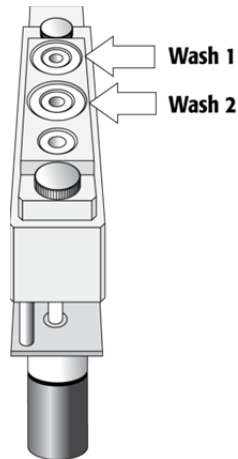


Figure 35. Wash Station Wash1/Wash2 Reference Point

For a Fast Wash Station, the reference positions are the two holes in the wash vial caps (see Fig. 35, Wash1 and Wash2). The lower needle guide should be centered in these holes with the bottom of the lower needle guide lightly touching the surface of the Wash Station assembly.

4.2.5. Wash Station: Waste/Waste2 Reference Point

Injectors (Waste)

note

The Waste positions represent an "Injector" within the PAL software. It is defined in the Object class "Injectors".

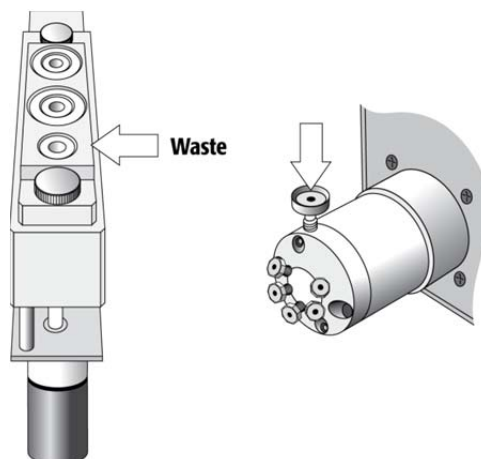


Figure 36. LC Valve and Waste Reference Position

For an **LC Valve** the reference position for the valve needle guide fitting is mounted on the top valve port (see Fig. 36). The lower needle guide of the Injection Unit should be centered in the valve needle guide fitting. Adjust the Z-Position so that the bottom of the lower needle guide just touches the surface of the valve needle guide fitting. **Then reduce the value by 2.0 mm.** See Figure 37.

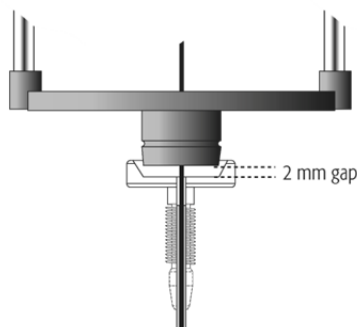


Figure 37. Positioning Z-Axis Needle Guide on Valve Needle Guide

For the **Waste Port** the reference position is a hole (slightly larger than the needle guide) placed in front of Wash2 (see Fig. 36). The lower needle guide should be centered in this hole with the bottom of the lower needle guide lightly touching the surface of the Wash Station assembly.

note

To adjust the Valve Needle penetration value, see below point 6.2.6. "Injection Valve Needle Penetration".

5. Syringes

5.1. Selecting Syringes

The HTC PAL is shipped with

- 1 PAL SyrLCX100µl; Kit LC Syringe X-Type 100 µL for HTC PAL, consisting of:
 - 1 pc syringe adapter;
 - 1 pc plunger holder;
 - 2 pc syringe SYRX G100-22S-3.

The SYRX G100-22S-3 Syringe gastight 100 µL for HTC PAL, equipped with 22S Gauge needle, is appropriate for injection into the standard CTC injection valve. However, certain applications may require different syringe sizes. Consult the PAL Accessories Catalog in Appendices for details. Gauge "22S" refers to small internal needle diameter. The "X-type" syringe stands for inertness and for a high number of duty cycles.

5.2. Syringe Priming

It is critical that syringes be primed before beginning sample preparation. Prime every liquid syringe first manually before inserting into the PAL system. Afterwards, the syringe can be primed and tested by using the Utility function "Clean Syr".

5.3 Installing a Syringe

note

Before a syringe is inserted, the position "Change Syr" should first be verified. The position "Change Syringe" should not be located above an object where the needle could collide with a vial, as for example.

Path:

Menu/Utilitites/Syringe/function key "F3" "Change Pos".

Move the PAL Injection Unit to a location where a collision cannot occur by selecting the X- and Y- axes. The value for the Z-axis is given as a default and a change of this position is not necessary in standard operation.

1. Select Menu and press F1/Chang Syr. The Injection Unit will move to a location that will facilitate installation of the syringe;
2. Place the blue plunger holder into the injection unit;
3. Place the syringe in the appropriate syringe adapter. Pull the plunger out to approximately 20% of its length (See Fig. 37);

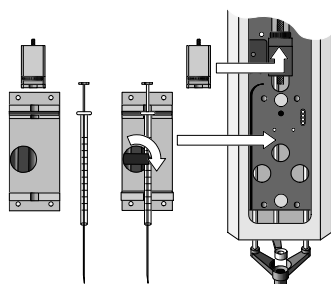


Figure 38. Syringe and Syringe Adapter for Liquid Injections

4. If necessary, loosen the plunger retaining screw in the plunger holder;
5. Move the syringe, installed in the syringe adapter, partially into the Injection Unit. First, guide the needle into the upper needle guide and then into the lower needle guide (See Fig. 38);
6. Insert the plunger button into the plunger holder. Allow the syringe adapter to "click" into place by magnetic force against the syringe carrier;
7. Tighten the plunger retaining screw against the plunger button;

8. Press **"Home"**. The plunger moves down until it hits the mechanical stop. This position is stored as the syringe's zero volume position. The Injection Unit then returns to the HOME position.

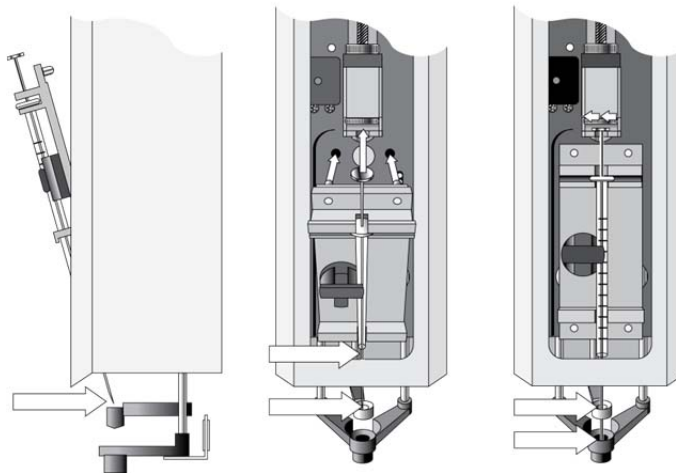


Figure 39. Installing and Removing a Syringe for Liquid Injections

5.4. Removing a Syringe

1. Select "Menu" and press **F1/Chang Syr**. The Injection Unit will move to a location that facilitates removal of the syringe;
2. Loosen the plunger retaining screw. Move the plunger slightly out of the plunger holder;
3. Pull the syringe adapter out and then carefully upward to remove the syringe adapter, with the syringe, from the Injection Unit.

6. Injection Valve

6.1. Valve Drives and Valves – General Remarks

A HTC PAL can be equipped with 1 LC Injection valve connected and controlled via the **Auxiliary Interface (AUX)**. If more than one valve has to be configured, or if an auxiliary Interface is occupied by another module, such as a Dilutor, then Multi Position or Serial Valve Drives are required. The Serial Valve Drives are connected at "SER2" interface with the PAL System or interface "MODBUS" with the PAL-xt system.

The PAL model HTC-xt is equipped with the control board "APR Control-xt" which provides two auxiliary interfaces, "AUX1" and "AUX2". The choice to connect one more valve drive is provided.

The standard LC injection valve is a six-port Cheminert valve (Valco/VICI). On customer demand, CTC Analytics can also supply other valve types, such as Valco W-type, or valves with various ports, 4-port valves (with internal loop) and 10-port valves.

The six-port valve is connected to the detection system according to the flow path shown below. Plumbing diagrams for other available six-port injection valves are provided below as well.

Details are described in the Addendum of PAL User Manual "Valve Drives and Valves". See also poster "Tips and Hints for PAL Systems".

6.2. Injection Valve Flow Path

The six-port valves are connected to the detection system according the flow paths as shown in Figures 40 to 42.

6.2.1. Standard LC Injection Valve, Cheminert 6-Port

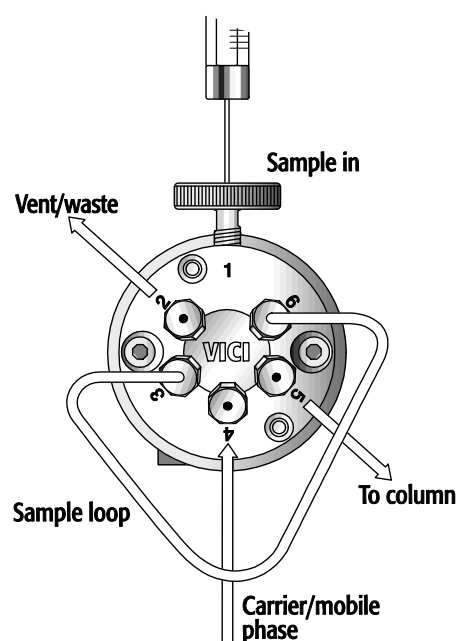


Figure 40. Flow Path LC Injection Valve Cheminert Type

The standard LC Injection Valve is a six-port two-way switching Valve with a flat rotary plate and has a special needle guide.

| | |
|------------------------|---|
| Valco / VICI Cheminert | Flat Plate Rotary Valve |
| Stator Material: | Stainless steel 316 |
| Rotor Material: | Valcon H (inert mix-polymer) |
| Port Size: | 1/16 inch |
| Fittings: | Valco 1/16 inch Ferrules and Nuts |
| Actuator: | PAL Valve Drive (Micro-Electric Actuator) |
| Loop Size: | 20 μ L (shipped), other loop sizes available |
| Bore Size: | 0.25 mm |
| Port to Port Volume: | 320 nL for vertical port, 75 nL for standard ports, 75 nL for engraving |

note

Sample loops of the different valve types are not interchangeable.

6.2.2. Valco W-Type 6-Port Injection Valve

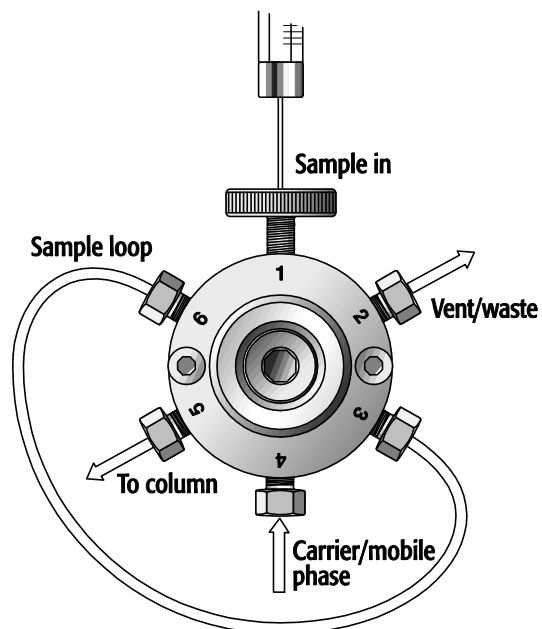


Figure 41. Flow Path LC Injection Valve W-Type

The LC Injection valve, Valco Type W, is a six-port two-way switching valve with a conical rotor and a the special needle guide.

| | |
|----------------------|--|
| Stator material: | Stainless steel 316 |
| Rotor material: | Valcon H (inert mix-polymer) |
| Port size: | 1/16 inch |
| Fittings: | Valco 1/16 inch Ferrules and Nuts |
| Actuator: | PAL Valve Drive (Micro-Electric Actuator) |
| Loop size: | 20 µL (shipped) |
| Bore size: | 0.40 mm |
| Port to port volume: | 155 nL for all ports, 390 nL for engraving |

note

Sample loops of the different valve types are not interchangeable.

6.2.4. Rheodyne 6-Port Injection Valve PD7991

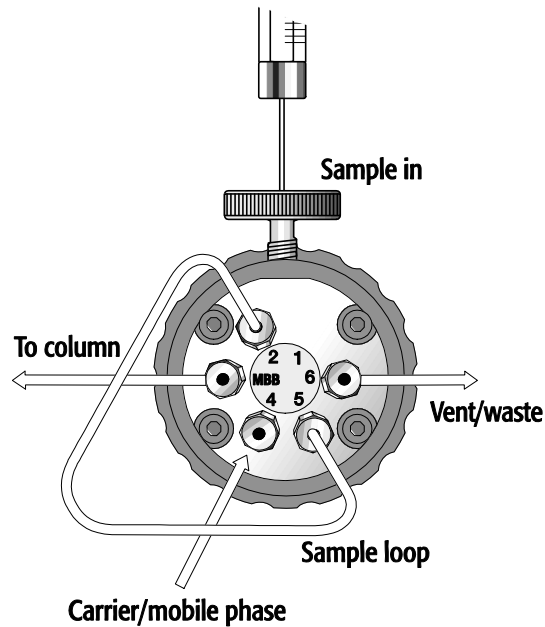


Figure 42. Flow Path LC Injection Valve 'Rheodyne PD7991'

The Rheodyne PD 7991 six-port two-way switching valve is delivered with a CTC Needle Guide and Needle Seal. Valve pod diameter 27 mm.

| | |
|----------------------|--|
| Rheodyne Valve | Flat Plate Rotary Valve |
| Stator material: | SPC-4 (special plating on Titanium) |
| Rotor material: | RPC-10 (proprietary PEEK blend) |
| Bore size: | 0.20 mm (0.008"); Vertical Port 0.25 (0.010") |
| Port size: | 1/16 inch |
| Port ferrules: | Swagelok Front- and Back Ferrules |
| Needle seal ferrule: | Rheodyne |
| Nuts: | Rheodyne nuts |
| Loop sizes: | 5, 10, 20, 50, 100 µL |
| Maximum pressure: | 1034 bar, 15,000 psi |
| Port to port volume: | 294 nL for vertical port; 195 nL for standard ports |

note

Sample loops of the different valve types are not interchangeable.

6.2.4. Rheodyne 6-Port Injection Valve PD718-313

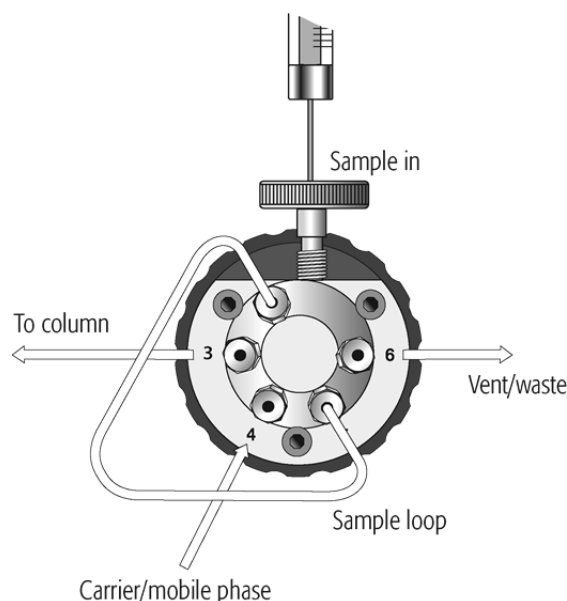


Figure 43. Flow Path LC Injection Valve 'Rheodyne PD718-313'

The Rheodyne Injection Valve PD718-313 is a SupraLife™ 2-position, 6-port Rapid Replacement Pod equipped with a vertical inlet port, delivered with CTC Needle Guide and Needle Seal. Valve pod diameter 32 mm.

| | |
|----------------------|---|
| Valve Stator: | Coated stainless stator |
| Rotor: | RPC-13 Polyimide based rotor seal |
| Bore Size: | Vertical Port: 0.25 mm (0.010") Ports 2 to 6: 0.20 mm (0.008") |
| Volume for | Vertical Port: 0.75 µL |
| Ports and Engraving: | Ports 2 to 6: 0.07 µL Engraving: 0.05 µL (standard engraving) |
| Valve Volume | Full Loop: 0.87 µL Partial Loop: 0.82 µL |
| Connections: | 10-32 male threaded fittings, 1/16" tubing OD |
| Port Nut/Ferrules | Swagelok Nut and Front-Back Ferrule |
| Maximum Pressure: | 1200 bar (18000 psi; 120 MPa) |
| Standard Loop: | 2 µL; Loop ID: 0.13 mm (0.005") |

note — *Sample loops of the different valve types are not interchangeable.*

note — The Agilent specific Rheodyne Valve with Agilent PNo. 5067-412 is connected in the same way to the HPLC system as shown in Figure 43.

6.2.5. Valve Needle Guide and Needle Seal

All valves are equipped with a special valve needle guide fitting. This fitting has a wide diameter to mate with the syringe needle guide on the injection unit. The valve needle guide also has a countersunk hole to facilitate insertion of the syringe needle into the injection port.

Figure 44 shows the example of the setup with the standard valve, Cheminert type.

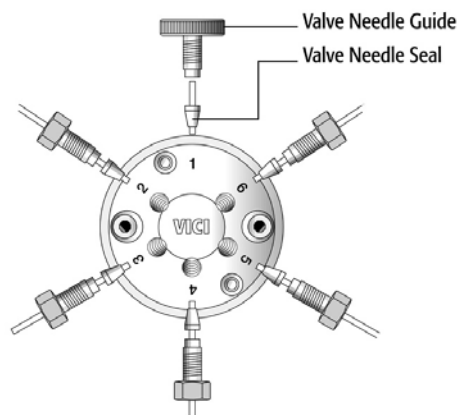


Figure 44. Valve Needle Guide and Valve Needle Seal

The valve needle guide holds the needle seal. The needle seal, which is a short length of FEP tubing, forms the seal around the syringe needle. A stainless steel ferrule is tightened around the FEP sleeve to ensure a leak-proof fit.

note

To ensure reproducible sample injection and minimize carry-over it is critical that:

- *The valve needle guide and the valve needle seal be installed properly,*
- *The valve needle seal be changed on a regular interval, details see below,*
- *The needle penetration depth be set accurately, (see point 6.2.6. "Injection Valve Needle Penetration").*

To specify a limit number of maximum penetrations into the Needle Seal is not practicable. It is advised to check the tightness of the seal daily or weekly when first using the PAL System to gain experience with the specific use in the laboratory related to the application.

The following simple test provides assurance of tightness:

- Take the Needle Seal out of the valve port.
- Manually insert a syringe needle gauge 22 (or Gauge 22S) from top down into the tube, passing the sealing point of the ferrule.

- If a restriction is observed, continue to use the Needle seal. If not, replace the Needle Seal.

6.2.5.1 Interval to Replace Needle Seal

The interval to replace the Needle Seal depends on the number of penetrations. Two factors may be considered for the decision to replace the Needle seal:

- Leak, seal not reliable.
Remove the Needle Seal from the inlet port and insert a syringe manually with the corresponding needle gauge (standard Gauge 22 OD 0.72 mm). Move the needle below the seal point of the ferrule. If no resistance is observed at this point, replace the Needle seal.
- Carry-over
In case of any doubt of possible contamination of the Needle Seal with a compound, replace the Needle Seal.
Contamination can occur if the sample solution is accidentally dispensed too fast into the valve system. The restriction of valve and loop may cause backpressure and the sample solution can be forced backwards into the inlet port of the valve.

note

PAL Firmware (version 2.4.X or higher) provides a counter for the number of injections performed with the PAL System. This counter monitors the valve switches and not the number of penetrations into the injection port, e.g. for cleaning the valve an extra penetration is required. It is advisable to monitor this counter in conjunction with the test for the tightness of the Needle Seal as described above.

- *After running routinely a few weeks, the warning limit for the “Inject Counter” gradually becomes more evident and will be a valuable tool for the user in routine work.*
- *Path: Menu/Info/Maintenance/Inject Limit (“Inject Counts” reflects the actual number of injections).*

6.2.5.2. Part Numbers for Replacement Needle Seals

| PNo. | Description |
|----------------|--|
| PAL NdlSeal | Standard Needle Seal, pkg of 10. FEP Tubing transparent, Ferrule sst., Needle Gauge 22 (OD 0.72 mm), for Valco/VICI sst Valves Cheminert and W-type. |
| PAL NdlSealP | Needle Seal, pkg of 10. FEP Tubing transparent, Ferrule PEEK., Needle Gauge 22 (OD 0.72 mm), for Valco/VICI PEAK Valves Cheminert-type. |
| PAL NdlSeal-19 | Needle Seal, pkg of 10. FEP Tubing blue, Ferrule sst., Needle Gauge 19 (OD 1.06 mm), for Valco/VICI sst Valves Cheminert and W-type with bore size 0.75 mm (large volume injection application). |
| PAL NdlSealR | Needle Seal, pkg of 10. FEP Tubing transparent, Ferrule sst., Needle Gauge 22 (OD 0.72 mm), for Rheodyne Valve 6-port, PD 7991-type. |

6.2.6. Injection Valve Needle Penetration

note

Before performing the following steps, make sure the Object Positions X-, Y-, Z- for LC Vlv1 (LC Vlv2) are properly defined and a syringe adapter, including a syringe, is inserted in the Injection Unit (see points above).

Complete the following steps to define the Valve Needle Penetration Depth:

1. In the Object Class **Injectors** choose the Object **LC Vlv1**. The following screen is displayed;

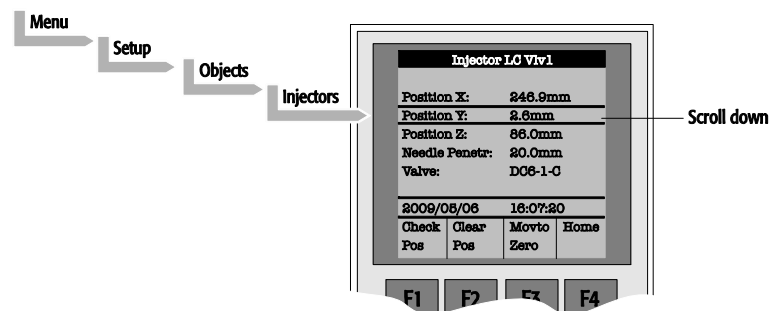


Figure 45. Menu Screen Valve Needle Penetration Depth

2. Press the F1 button **Check Pos**. The Injection Unit moves to the previously defined **LC Vlv1** position;
3. Highlight the item **Needle Penetr:** with the cursor bar and press **ENTER**;
4. **Slowly** rotate the outer knob to adjust the Needle Penetration Depth. The syringe moves down stepwise into the Injection port;
5. When the syringe needle tip enters the valve needle guide, **slow down** the Z movement again. Always observe the syringe needle during this operational step;
6. Move down stepwise until you notice a "**click**" sound inside the Injection Unit. **STOP** the Z down movement immediately;
7. Rotate the outer knob **two steps** in the opposite direction and press **ENTER** to save the Needle Penetration Depth value;
8. Press Function Key **F3** "Movto Zero";
9. Verify the defined Needle Penetration Depth value by repeating Step 2 and 3.

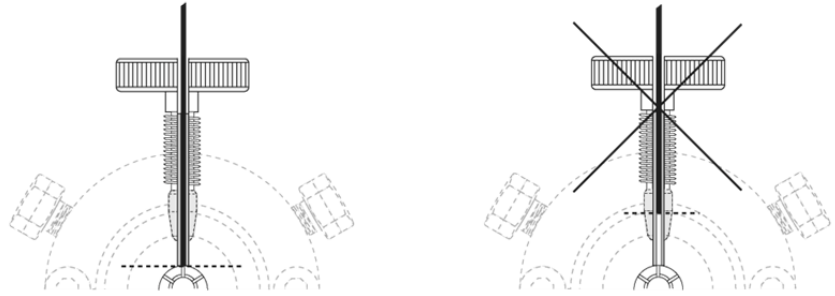


Figure 46. Needle Penetration in Valve Inlet Port

note

The setting of the Needle Penetration can also be done in the "Utilities" section.

*Path: **Menu/Utilities/Injector/LCVlv1***

*Select function key **F3** "Moveto Inj" and activate "**Needle Penetr**"
Continue as described above.*

note

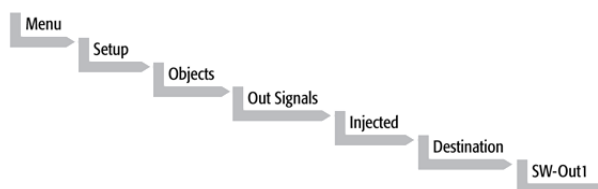
After all positions have been set and the Valve Needle Penetration has been adjusted, perform a backup of the existing configuration (see point 8 below, "PAL Software Program").

7. Interfacing the HTC PAL to Other Devices

7.1. Synchronization and Output Signals

Synchronization Signals (**Sync Signals**) are inputs that tell the HTC PAL when to wait or proceed with a sample-processing step. Output Signals (**Out Signals**) are sent from the PAL to external devices to indicate status or completion of particular processing steps. These signals are classified as Objects. Physical Events (e.g. TTL-In1) are also Objects and may be assigned to named signals. PAL Cycles require that certain signals such as **"Start"**, **"Inject"**, and **"Injected"** be defined. See the next table below for the PAL Events and signal assignments associated with the standard PAL **"LC-Inj"** and **"LC-Cut"** cycles.

Certain types of integration of the PAL system into data handling or control software, such as ChemStation, Xcalibur, Galaxie or Chromeleon, accomplish synchronization of the Ready/Start signal directly via software control (RS232/LAN). A synchronization cable is not required and the Sync Signal "Start" must be set to "Immediat".



To assign a physical Event (e.g. SW-Out 1) to an existing signal Object (**"Injected"**), complete the following menu selections:

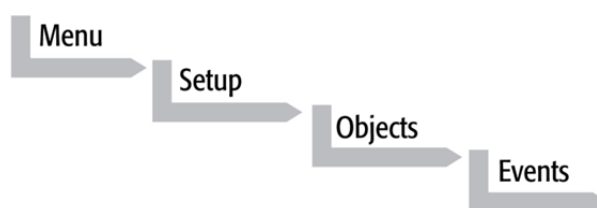
PAL Systems are shipped with all Cycle events pre-defined, as shown in the table below. If a different physical signal needs to be used, then it will be necessary to assign a new Event to the Object signal.

If a signal is to be ignored, then its corresponding Event must be set to "Immediat".

| Standard Assignment for HTC PAL Injection Cycles | Description | Default Events | INTERFACE 1 Pin # |
|--|--|-----------------------|-------------------|
| Start JobQueue (Sync Signal) | Start a Job Queue (Job). Prerequisite is a defined "Job" with a method assigned. Useful for automated, unattended, timed sampling. | Immediat | |
| Start (Sync Signal) | Start a cycle (Input from GC or data system) | Immediat ¹ | 7 8(GND) |
| Start2 (Sync Signal) | Continue the cycle "GC-Dual" for the second sample | Immediat (Ignore) | |
| Inject (Sync Signal) | Inject READY to INJECT | Immediat (Ignore) | |
| Inject2 (Sync Signal) | Inject the second sample for "GC-Dual" cycle | Immediat (Ignore) | |
| Injected (Out Signal) | Activated at the moment the sample has been injected | SW-Out1 | 3 4 |
| Injectd2 (Out Signal) | Activated at the moment the second sample has been injected | Off | |
| Running (Out Signal) | Active as long as the Job Queue is being processed and the PAL is not in an error state | Off | |

1) If used to synchronize with Sync cable, change setting to "TTL-In1"

If an item of the class "Sync Signal" is assigned to an output signal, such as "TTL-In1", then this TTL contact must be defined as either "Active High" or "Active Low", as expected by the HPLC system. This is defined in the PAL Firmware class "Events".



Select the corresponding item and set the mode accordingly.

The setting is provided with the schematic description of the LC Sync Cable if a dedicated cable is ordered.

Normally, a non-specific LC Sync Cable is supplied which has the PAL "INTERFACE " or PAL-xt "Interface 1" connector mounted and the HPLC system side has four open leads.

8. PAL Software Program

8.1. PAL Loader Program

The purpose of PAL Loader Software is to create a backup file of the complete PAL System Firmware. The core software (firmware) and all PAL Firmware Objects, including all settings (Items), the local methods, and jobs are saved in one file.

The PAL Loader software has a second function of loading the firmware or a complete backup file to a PAL system.

The PAL Loader software has always been a part of the PAL System. The following PAL Loader Software versions are in use:

- PAL Loader Version 1.0.1
- PAL Loader Version 1.1.1

A new PAL Loader software, "Loader" version 2.1.1 (or higher) has been developed for the PAL-xt system.

The PAL-xt system requires PAL Firmware 4.1.X or higher, which calls for the new "Loader" software.

The new PAL Loader Software is backwards compatible. The software can be used for all PAL Firmware versions.

The name of the *.exe file has been changed intentionally to avoid conflicts when old and new versions are installed on the same computer:

- PAL Loader version 1.1.1: PALLOAD.exe
PAL Firmware version up to and including 3.X.X
- PAL Loader version 2.1.X: Setup PALloader (.exe)
PAL Firmware version as of 4.1.X
but backwards compatible with lower versions

Details are described in: "Addendum to PAL User Manual, PAL Loader Software Version 2.1.X, Installation and Operation".

8.2. PAL Object Manager Software

The PAL Object Manager software is used to load a new PAL Firmware Object to a system after a new module (hardware module) has been added to the PAL System.

The PAL Object Manager software is the software used to handle the so-called PAL Object Lists.

The software version 2.2.1 or higher has been developed for the PAL-xt System that, in addition to serial communication, also permits LAN communication (TCP/IP). The software is backwards compatible and can be used for all PAL Firmware versions.

The PAL Object Lists have to match the corresponding PAL Firmware version, as shown in the list below:

- PAL System Firmware Versions 2.X.X
PAL Object Lists Rev. K (or higher)
- PAL System Firmware Version 3.0.X
PAL Object Lists Rev. K (or higher)
See specific Object Lists for this FW Version 3.0.X.
- PAL-xt System Firmware Version 4.1.X (or higher)
PAL-xt Object Lists Rev. B (or higher)

The two Object Lists for the PAL and PAL-xt Systems can be loaded with the same PAL Object Manager software. This simplifies the handling in cases where the PAL and PAL-xt Systems are in use within the same working environment.

Detailed information is available in the 'Addendum to PAL User Manual PAL Object Manager Software'.

9. Establishing Communication with Computer

The PAL System allows a serial communication protocol with a PC. As a new feature, the PAL-xt System provides LAN communication, also referred to as "TCP/IP" or "Ethernet".

The PAL-xt System requires a dedicated "APR Control-xt" board and PAL Firmware version 4.1.X or higher.

9.1 COM Port Settings

The port settings are normally defined in:

Windows\Control Panel\Device Manager\Ports.

The standard settings for the serial communication are shown in Figure 47. It is important to understand that the application (e.g. PAL Loader Software) does actively set the communication parameters, and the baud rate is set for optimized use.

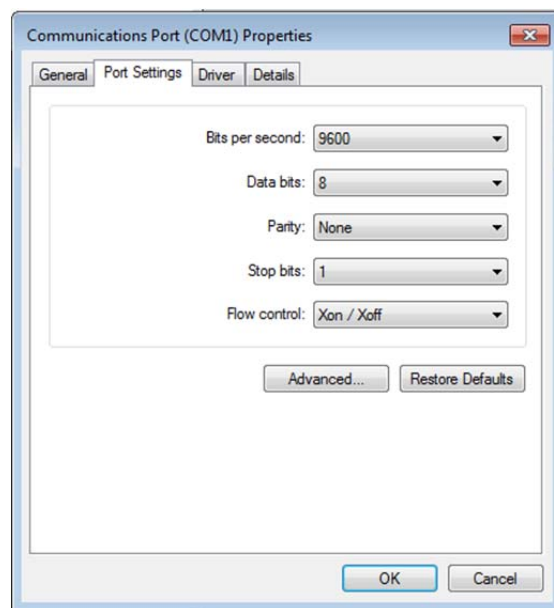


Figure 47. COM Port Settings

A quick way to check whether serial communication with the PAL System can be established is to use the PAL Loader software. For details see "Addendum to PAL User Manual PAL Loader Software".

9.2 Setting up LAN Communication

Select the firmware “Communication” class by the following path:

Menu/ F3-Setup/Communication

note

*Menu/ F3-Setup/Communication
See detailed description below under point 10.*

The system automatically searches for the MAC address when the “Setup Communication” window is accessed.

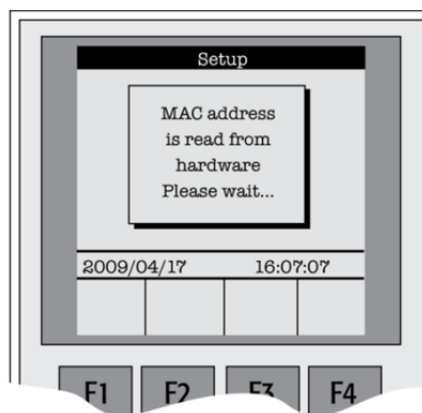


Figure 48. Reading the MAC Address from the Ethernet Communication Port

This search for and reading of the MAC address takes approximately 10 to 15 seconds. If successful, the MAC Address is stored in the system firmware and can be viewed on the terminal as follows.

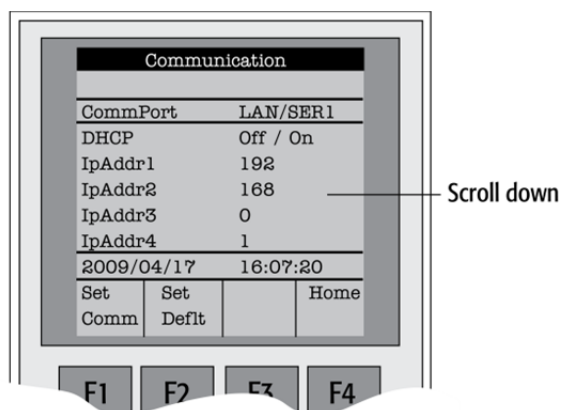


Figure 49. PAL-xt Communication Settings

note

The standard IP Address has been changed starting with PAL-xt Firmware Version 4.2.1 to: 192.168.0.100.

Pressing function key "F1", "Set Comm" sets the selected communication mode. The same is achieved by pressing "ESC" or "Home".

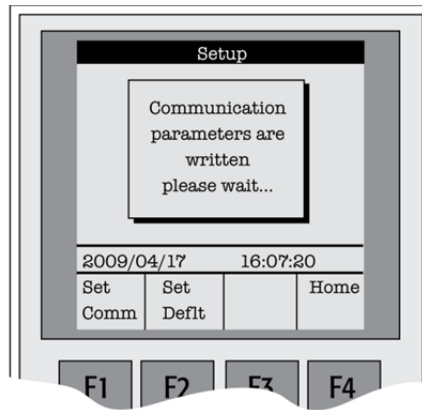


Figure 50. Setting Communication Mode

9.2.1. Explanations for the various settings for the Communication Protocol

| Parameter | Explanation | Remarks |
|-------------------|--|---|
| CommPort | Setup for serial (SER1) or LAN communication. | If serial communication is selected, all other parameters in PAL- <i>xt</i> Firmware "Communication" class are ignored. |
| DHCP | = Dynamic Host Configuration Protocol. If set to "Off", the IP address is provided by the user, see IPAddr1 to 4. The user can ask the network administrator for a suitable IP address. If set to "On", an IP address is dynamically sought throughout the provided network. | It is advisable to use a fixed IP address, set the "DHCP" parameter to "Off". In this mode the PAL- <i>xt</i> System always has the same fixed IP address. Troubleshooting is easier for the network administrator. See also special remarks below. |
| IPAddr1 to 4 | Enter the IP address divided into four blocks, example IP default Address: 192.168.0.1. | The IP address is a fixed PAL- <i>xt</i> System address. The IP address is often provided by the network administrator. |
| SubNet1 to 4 | SubNet mask for network configuration. | The SubNet mask must be provided by the network administrator. |
| TCPPort | This parameter is read only, no changes possible. | The network administrator must be informed about this setting. The port must be cleared of firewall protection to enable communication. |
| StdGateway 1 to 4 | If Gateway is used in network, the Gateway IP address (switch, hub) has to be entered. | Gateway is used if independent networks need to communicate interactively. Communication within the network is provided by a hub or switch, defined as "Gateway". |
| MACAddr1 to6 | The unique MAC Address for the PAL- <i>xt</i> System is read and entered into this PAL- <i>xt</i> communication protocol. This is a read only parameter field. | The MAC address is provided by the Ethernet communication hardware. The address is also visible beside the read-out from the terminal on the label affixed to the Ethernet module on the PCB "APR Control- <i>xt</i> ". |

9.2.2. Special Remarks to the above listed Parameters

DHCP:

If "DHCP" mode is active, an automatic search for the IP address is activated. If a free IP address is found, the communication between the PAL-xt System and the network becomes established. The new IP address (found through "DHCP" search) is immediately entered into the PAL-xt Communication protocol as seen from the local terminal. The parameters "IPAddr1 to 4" are not updated until one opens the communication menu again.

The Setup for the PAL Loader software requires entering the IP address or hostname. The dynamically provided IP address is displayed on the local terminal. As an alternative, the following setup procedure can be used:

Prerequisite: PAL-xt setting in "Communication" class: DHCP = On.

Open the "Setup" window and enter the following name in the "Hostname or IP Address" field: CXXXXXX. The "Xs" being the last six characters of the MAC address, which is known from the parameters "MacAddr4, MacAddr5, and MacAddr6 for the PAL-xt System.

If a MAC address only consists of one character, insert a = in front of it. If, for example, MacAddr4=BA, MacAddr5=35 and MacAddr6=3, enter CBA3503 and not CBA353.

9.3 Troubleshooting for Serial or LAN Communication

Both communication protocols are described in detail in the "Addendum to PAL User Manual PAL Loader Software".

note

Default setting of a PAL Firmware backup file is "Serial Communication".

10. Special Functions

This section describes special functions which can be activated by the “PAL Extended User Mode”.

The purpose of having two software access levels is to display discrete items and sections of the firmware at each level. Settings which need to be done rarely, perhaps at the time of installation of the PAL System, are hidden at level 1 (User Level) and revealed at level 2 (Extended User Level). This also protects the PAL System in group use. Nevertheless, the important points should be known by the user and are described below.

10.1. How to Access “Extended User Mode”

Extended User Mode can be accessed by the following path:



The above path as shown is an abbreviation for the following steps:

- Menu/ scroll the cursor to “Setup” /
- press function key “F3” /
- activate “Setup” by pressing the center of the selector knob.

In this PAL User Manual or in technical notes, only the following will be referred to:

Menu/F3-Setup/.

10.2. Section "F3-Setup"

The path to access this section is shown below. This "Setup" section at the Extended User Level provides various options to access other classes which are not visible at the User level. Some classes are known but may show some new items. Details are described below.

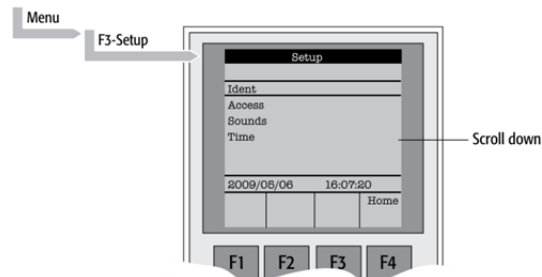


Figure 51. Selecting "Setup" in Extended User Mode

| Object | Description |
|----------------------|--|
| Ident | The "Identification" of the system provides the opportunity to assign Users, site, and system names. The serial number of the PAL System can be entered at this level. Remark: After loading a fresh PAL Firmware Backup file, the SNo. is displayed as "XXXXXX". |
| Access | Access can be selectively opened or limited to different users for the "Job", "Method" or "Setup". |
| Sounds | The "Beep" sound can be adjusted to specific needs. For safety reasons it is advisable to keep the default settings, especially the "Warn Move", turned ON to signal the start of the PAL System to the user. |
| Time | The PAL internal clock can be set. Remark: If the clock is fast, reset all items, from "Year" to "Seconds" and use the mandatory function key "F1" "Set Time". |
| <i>Communication</i> | The communication mode, serial or LAN, can be selected and conditions are defined. For details see Addendum PAL Loader Software. |
| System | Basic parameters can be predefined for specific needs. Details see below. |
| Service | Basic service tests can be activated. Details see below. |
| Objects | Accessing the PAL Firmware class "Objects" in the Extended User mode provides more detailed possibilities for object items. At this level an Object can be copied or deleted by using the specific function keys. This provides quick access to add e.g. a second or third injector. |

Items displayed in *"italic"* are available beginning with PAL Firmware Version 4.1.X.
Items displayed in **"bold"** are explained in detail below.

10.2.1. System

The following "System" Items can be changed by selecting the particular item. Beginning with PAL Firmware version 4.1.X, an intermediate step was added. After selecting "System", the new "Settings" level follows. Activating "Settings" opens up the described Items below.

| Item | Description |
|---------------------|---|
| Syr Detect | The syringe detection can be turned off in cases of sensor failure or if a special syringe with unknown ID is installed. Turning OFF the syringe identification sensor automatically displays a dialog box enabling the selection of syringe identification manually. |
| Start Ref | This item provides the choice of referencing all axes at the start of the system or suppressing the referencing. It is advisable to use this function actively to detect a possible loss of steps. |
| Stop XY Error | This function allows turning off the automatic recovery of the PAL system after detection of a collision (loss of steps of a stepper motor). Stop XY Error = ON: Automated recovery turned OFF Stop XY Error = OFF: Automated recovery turned ON In PAL Firmware version 2.3.X the new feature that recovers automatically after detecting a collision has been implemented. Firmware version 2.6.2 provides the possibility of disabling automated recovery. If recovery is turned OFF, the PAL system always checks its position before moving to the injection port for injection. This can lead to an extra move, crossing over the X-,Y-axes sensors – if the injection port is at the opposite end of the X-axis relative to the sample location, (zero X-axis position in-between sample location and injection port). For critical application fields, e.g. clinical analyses, it is advisable to turn off the automated recovery; Stop XY Error= ON. |
| <i>PlgPathCheck</i> | The plunger travel path is monitored to ensure that the plunger tip reaches the syringe zero point in all cases – compared to original plunger referencing and defining the syringe zero point. If an error is detected, the PAL System stops operation. This feature is useful if sample solutions with particles need to be handled, or if the syringe type is not adequate for the solution composition, or if the syringe plunger is blocked or even bent, such an error will be recognized and the system will come to an emergency stop. |
| PlgChnge Pos | Changing a syringe using the Menu function "Chnge Syr" moves the plunger up to the position specified by this item. For normal use, accept the default values. |
| Init Syr at | The syringe plunger can be initialized (referenced) at "Home" or "Waste" position. If samples with a high danger of toxicity are treated, it is advisable to use the "Waste" position for referencing. |
| Inj Signal | An Autosampler is usually the master in a total chromatographic system. The other components send a "Ready" signal to enable a start of the Autosampler. At the moment of injection a Start signal is sent from the PAL System to the other component(-s) of the entire system. With this "Inj Signal" item the status at which the signal is sent out can be defined. The syringe is filled with the defined sample volume. PlgUp = Start signal at the moment the plunger starts moving down for injection. PlgDown = Start signal at the moment the plunger reached zero point from syringe. (recommended for large volume injection, but not in combination with Agilent Chemstation.) ValveSw = Start signal sent at the moment the injection valve is switched, HPLC technique. PreInj = Start signal sent at a time before injection, as with a sample preparation device started before a GC or LC system. Minus time relative to chromatographic start time. |

| | |
|---------------|--|
| Vial PrePress | This item can be activated to avoid a vacuum if a relatively large amount of sample is taken out of a small volume vial. If e.g. a volume of 50 µL is specified for injection, the PAL system first takes 50 µL ambient air and “injects” this volume into the sealed vial, causing overpressure in the vial. After this step, the sample volume can be aspirated without forming a vacuum. This functionality is only valid for liquid sampling, not for the Headspace technique. Starting with PAL Firmware version 4.1.X, this item is also active in combination with Cycle Composer. |
| LC-Inj | Standard cycle for HPLC technique. Details on method parameters see Appendices, point 3, “Injection Cycles” and point 4, Flow Chart “Firmware Overview” |
| LC-Cut | Cycle for column switching with two valves, HPLC technique. Both valve drives have to be controlled through “AUX” interfaces. Details on method parameters see Appendices, point 4, Flow Chart “Firmware Overview” |
| GC-Inj | Standard cycle for GC technique. Details on method parameters see Appendices, point 3, “Injection Cycles” and point 4, Flow Chart “Firmware Overview”. |
| GC-InS | Standard cycle covering GC Sandwich technique. Details on method parameters see Appendices, point 3, “Injection Cycles” and point 4, Flow Chart “Firmware Overview”. |
| GC-Dual | Cycle for GC technique which allows injecting two samples in two different injectors. The start signal is sent after injection of both sample solutions. Details on method parameters see Appendices, point 3, “Injection Cycles” and point 4, Flow Chart “Firmware Overview”. |
| HS-Inj | Standard cycle for GC headspace technique. Details on method parameters see Appendices, point 3, “Injection Cycles” and point 4, Flow Chart “Firmware Overview” |
| SPME | Standard cycle for GC SPME technique, Solid Phase Micro Extraction, Fiber technique. Details on method parameters see Appendices, point 4, Flow Chart “Firmware Overview” |
| TTS Sotax | The two cycles are dedicated cycles for “dissolution applications”. TTS cycle is used for transdermal patches and the Sotax cycle is used for tablet dissolution |

Items displayed in *“italic”* are available beginning with PAL Firmware Version 4.1.X.

- note** — *Standard injection cycles are selectable and activated directly from the PAL System. Any deviation from a standard cycle, a Cycle Composer Macro, or Cycle Editor (ICC-CE) Cycle must be programmed for customized requirements.*
- note** — *In PAL Firmware versions < 4.0 the standard cycles are grouped in Item “Cycles”.*

10.2.2. Service

The following “Service” items may be changed by selecting the particular item:

| Item | Description |
|------------------------|---|
| Check Motors | Every stepper motor can be moved separately. This function is useful to check out a specific motor or to perform an endurance test after a repair. The Start and Stop positions of the test path can be selected. The motor Current, Speed, and Acceleration are selectable (accept default value to be sure). A Pause time can be specified. A Cycle Limit and Actual Cycle Counter are useful tools for endurance tests. |
| Test Head ¹ | This tests the functionality of the PAL Injection Unit (“ Head ”). Two tests can be activated by the function keys: “F1” Check Plg: The stepper motor of the plunger drive is tested. Sensor check. “F2” Check Z: The vial detection sensor and “Needle Guide Blocking” function is tested. These tests are only required if any erratic behavior of the PAL System is observed. In such cases contact a representative of CTC Analytics AG. |
| Test Switches | X-Limit = Actual status of X-axis sensor. Move the X-Y-Carriage manually across the limit switch to verify activation of the sensor. Y-Limit = Actual status of X-axis sensor. Move the Y-axis manually to the Y-zero point (at X-axis), crossing over the limit switch to verify activation of the sensor. Z-Limit = Actual status of Z-axis sensor. Move the syringe slider assembly manually up to the zero Z-axis point, crossing over the limit switch to verify activation of the sensor. Aux1 Limit = Actual status of Aux1 limit sensor Aux2 Limit = Actual status of Aux2 limit sensor Plg -Pos = Actual status of Plg -Pos Needle Guide = Actual status of needle guide sensor |

Items displayed in “*italic*” are available beginning with PAL Firmware version 4.1.X.

¹ Please note that the service test “Test Head” is executed in the same way, independent of the PAL Firmware version. However the test evaluation is different between firmware versions 2 - 3 and version 4.

The updated PAL Service Manual, Edition 1.1, will include the PAL-*xt* System and will explain these differences.

10.3. Section “F3-Setup” / Objects

The same as is described above applies for the section “Objects” opened in Extended User Mode. New classes are visualized and known classes may contain new items accessible only on the level of the Extended User Mode. To open this level, use the following path:

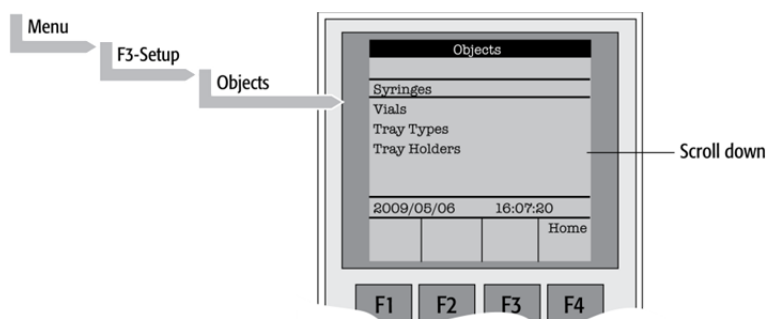


Figure 52. Selecting “Objects” in Extended User Mode

| Object | Description |
|---------------|--|
| Syringes | At this level all loaded syringes are selectable. At the “Utilities” user level only the active syringe is visible. |
| Vials | The Firmware Objects accessed on the PAL Extended User Mode have more specific items selectable than at the User level. Tolerances or ranges such as, e.g. “Maximum Penetration” can be defined and limited for the user such that this value cannot be exceeded. In the Object “Tray Types”, details for the various Items are described more closely. |
| Tray Types | The object class “Tray Type” is only accessible via the PAL Extended User Level. All loaded Tray Types are visible and selectable. Details, see below. |
| Tray Holders | The Firmware Objects accessed on the PAL Extended User level have more specific items selectable than at the User level. Depending on the type of Tray Holder, e.g. an Access and Restore Path or a Heater and Agitator (motor) is assigned. Typical example, the Tray Holder “Agitator”. |
| Trays | All loaded Trays are visible and accessible. A Tray must be assigned to a Tray Holder. A “TrayTypeGroup” identification checks if the specified Tray Type is allowed in this combination. The offsets X-,Y-, Z and the inclination corrections for a row or column are explained in the “Utilities Functions” section. The “Path Offset X-,Y-, Z” is used only if a “Path” is assigned to the specified Tray Holder, typically a Stack or Agitator uses a Path. |
| Wash Stations | The Wash Station and its positions “Wash1” and “Wash2” are visible and selectable. Details, see below. |
| Injectors | The Firmware Objects accessed on the PAL Extended User Mode have more specific items selectable than at the User level. Tolerances or ranges such as “Maximum Penetration” can be defined and limited for the user so that this value cannot be exceeded. In the “Tray Types” Object, details for the various Items are described. Furthermore, in this Firmware Object class a “Valve” and/or a “Heater” can be assigned. Note that the Wash Station Positions “Waste” and “Waste2” are listed in this “Injectors” class. |
| Valves | The Valves and Valve Drives connected and controlled by an “AUX” interface are listed in this Object class. For more details, see the Valves and Valve Drives Addendum. Note that the valves controlled by serial communication (Serial Valves or Multiposition Valves) are in the PAL Firmware Object class “Serial Valves”. |

| | |
|---------------|---|
| Agitators | At this level items such as "Motor Drive", " Minimum Speed " and "Maximum Speed" are selectable for the "Agitator" Object. The range can be set for the speed. The other items are available directly as Method parameters. |
| Dilutors | The Firmware Objects accessed in the PAL Extended User Mode have more specific items selectable than at the User level. Tolerances or ranges such as " Maximum Fill Speed " can be defined and limited for the user so that this value cannot be exceeded. Items such as " Prime Volume ", " Waste to ", " Motor Drives ", or " Scale Length " are specific items that remain hidden at the User level. |
| Tools | The Object class " Tools " is used to handle another device, such as the MHE-Tool (Multiple Headspace Extraction Tool) or MALDI Tool . For details, see the specific Addendum for the PAL User Manual. |
| Positions | The various positions used with the PAL System are selectable at this level. Positions such as " Home ", " Change Syringe ", or a Path Point, reference the Paths for a specified Tray Holder directly, such as " Agitator " or " Stack ". Selecting an item, e.g. " Home " will provide the function key " F1 ", Check Pos " on the screen. Activating this function provides the possibility of verifying X-, Y-, Z-axes values for this particular position. |
| Paths | A Path defines specific movements for the Injection Unit, which represent a repetitive task assigned to a Tray Holder. Typical examples are opening and closing a drawer from a Stack or opening the lid of an Agitator. The Path is composed of several steps (points) which are added up in a sequence. Each individual step (point) can be positioned by teaching X-, Y-, Z-axes. In most cases the return path is in the reverse order of the starting path. Example " AgiOpnL " and " AgiClsL ". If one setting of a point is changed, this change will be valid for the return path as well. |
| Sync Signals | The various synchronization signals are described above in Section F. "Description and Installation", point 6.1. At this level no other functionality, as shown at the user level, is provided. |
| Out Signals | The various Out-Signals are described above in Section F. "Description and Installation", point 6.1. At this level no other functionality, as shown at the user level, is provided. |
| Events | The various synchronization signals are described above in Section F. "Description and Installation", point 6.1. At this level no other functionality, as shown at the user level, is provided. Three events are newly available at this extended user level: Pwr-Out1 , Pwr-Out2 and FlushVlv . The main purpose of these three power-out signals is to activate a solenoid, such as for the Wash Station or the Gas Flush Valve. At this level the functionality of the signal can be tested. |
| Serial Valves | Serial valves, or "Multiposition Valve Drives" are powered and controlled by the serial (RS232) control and not through the "AUX" interface. With firmware level 4.1.X a " Mode " is now selectable. The mode refers to the setting of the Valve Drive, whether the current for the motor is set to " High Speed " or " High Torque ". For more details, see Addendum to PAL User Manual "Valve and Valve Drive". |
| Out Exp Box | The "Out Expansion Box" provides 8 TTL contacts and 8 relay contacts (24 V contact closure). The optional module (box) is connected and controlled by "Interface 2". For more details, see Out Expansion Box Addendum to PAL User Manual. |
| RS232 | This Object allows selecting the serial ports for the specific needs. Choices are: Remote, Terminal, Printer, Barcode, ExtDev, VICI-Vlv (for serial valve drives), or None. |

Motors

In the class '**Motors**', the Objects '**Motor-Y**' and '**Motor-Z**' are accessible, to enable the user to select specific motor parameters in case a specific application requires an adjustment.

Motor-Y**Strategy**

Three different settings are selectable for the Y-Motor movement strategy:

Rectang = normal movement as used for PAL system.

(In firmware version < 4.1.X this mode was called "Auto".)

XY-Simul = X, Y-axes move simultaneously, which allows movement in a diagonal direction. Do not use this mode for routine work.

(At firmware version < 4.1.X this mode was called "Rectang", but it was not active at lower versions.)

Retract = Y-axis moves from any point first to zero Y (back to the X-axis) before the X-movement is started. This mode allows bypassing an object (such as a large GC detector) which may be in the travel path if the default mode "Rectang" is used.

Path Speed = Y-axis motor speed in conjunction with a "Path", example: Opening and closing a drawer of a Stack. In certain situations it is necessary to slow down the speed to open and close a drawer. Typical application example is fraction collection, collecting directly into a well plate. If the liquid level is high, the liquid can wash over into the next row if drawer movement is too fast.

Remark: At PAL Firmware version 4.1.X these items of the Y motor have been made available at the Extended User Level.

Motor-Z

For the 'Motor-Z', following speeds are selectable:

Penetr Speed = This is the speed used to penetrate the syringe needle into any object, with the exception of the injector. Example: Vial penetration.

Inj Penetr Spd = Injector Penetration Speed. With PAL Firmware version 2.X and 3.0 the injector penetration speed is identical to the injector retraction speed.

Inj Retr Spd = Injector Retract Speed. With PAL Firmware version 4.1.X, the injector speed was separated into a penetration and a retraction speed. This allows safe penetration of a vial by any type and diameter of syringe needle without bending through the septum of the GC injector. The needle retraction speed can be increased to speed up the entire injection process. This new feature enables the user to avoid uncontrolled evaporation of any remaining sample solution in the needle.

The visibility of the Motor-Z parameters at the Extended User Level was introduced with PAL Firmware version 4.1.3.

Items displayed in "*italic*" are available beginning at PAL Firmware Version 4.1.X.
Items displayed in "**bold**" are explained in detail below.

10.3.1. Tray Type

The following object "Tray Type" Items may be changed by selecting the particular item. First select the desired **Tray Type**, such as "VT32-20".

note

The definition of Row and Column is given above in Section F. "Description and Installation, point 4.2.3.1.

By reversing the first six entries, the order of injection can be changed.

Example: Tray Type "VT32-20" has a "Row Length Y" and a "Col Length X" defined. Reversing to "Row Length X" and "Col Length Y" would start with sampling from left to right, as used e.g. with Tray Type "DW96".

The values of the items "Spl Per Row" and "Spl Per Col" must also be reversed.

| Item | Description |
|----------------------|---|
| Row Length X | Defines the Row length in the X-direction from the center of the first to the center of the last vial position, measured in mm. |
| Row Length Y | Defines the Row length in the Y-direction from the center of the first to the center of the last vial position, measured in mm. |
| Col Length X | Defines the Column length in the X-direction from the center of the first to the center of the last vial position, measured in mm. |
| Col Length Y | Defines the Column length in the Y-direction from the center of the first to the center of the last vial position, measured in mm. |
| Spl Per Row | Number of samples per Row. |
| Spl Per Col | Number of samples per Column |
| <i>Pattern</i> | The pattern of the Row or Column arrangement has to be defined. Regular = square arrangement (standard) Staggrd+ = Rows are arranged in staggered pattern. Offset of second Row is shifted by +50% of hole pattern. Staggrd- = Rows are arranged in staggered pattern. Offset of second Row is shifted by -50% of hole pattern. See Graphics below. |
| TrayTypeGroup | Software protection so that not every Tray Type can be placed on any Tray Holder. Example: VT32-20 cannot be fit into a Stack. |
| Plate Thickn | Thickness of Tray plate bottom (not the total height of the Tray). Measured in mm. |
| Vial Height | Total height of the vial including cap to seal if applicable. Measured in mm. Remark: The sum of the plate thickness and vial height adds up to the total height This is the point where the Injection Unit expects an object. |
| Vial Tmsprt | The mode to transport a vial is defined by: None = No transport required. Example liquid sampling. Magnet = Magnetic Transport. Requires magnetic vial caps. The Injection Unit moves to the side to slide the vial off when moved away. Needle = Device is transported with the syringe needle inserted. Example: special vials where a magnetic cap cannot be crimped, e.g. "Vacutainer". Remark: This item became active beginning at PAL Firmware version 2.5.X. |
| <i>ZSlideOffRetr</i> | If magnetic transport is selected, the distance can be defined to move the syringe slider up (Z-direction), lifting up the vial by magnetic force. Measured in mm. |
| <i>YSlideOffDist</i> | If magnetic transport is selected, the distance can be defined to move the Injection Unit to the side, Y-direction, to slide the vial off. Measured in mm. |
| Barcode | If a Barcode Reader is installed, the mode has to be set for " AutoFix ". None = No Barcode Reader option requested for this Tray Type. |

| | |
|---------------|---|
| Z Tolerance | A tolerance window to give a plus/minus range (expressed in mm) where the Injection Unit must expect an object. If the value of this item is > 0, this is a relative detection mode and the sensor from the Injection Unit needle guide is active. If the value of this item is set to "0" the sensor of the needle guide is turned off and the syringe slider moves to an absolute value, Z-axis position as specified in the object. |
| Z Retract | The distance to lift up the syringe slider before the Y-, Z-axes assembly moves across the unit can be specified, expressed in mm. |
| Max Penetr | The maximum allowed Needle Penetration can be defined as a safety so that the user cannot destroy the needle tip by going too far down. The Tray Type is prepared for a specific vial size; this value is therefore unique to this combination. The maximum needle penetration must not exceed the length of the syringe needle, considering the loss due to needle guide, etc.. Typical needle length is 51 mm, maximum penetration must not exceed 48 mm. |
| Needle Penetr | This item is identical to that used on the User level or, if available, as a method parameter of a local cycle. The value defined on these levels is mirrored to the Extended User level. |
| Spl1 Offset X | The "X" offset is defined as the distance from the outer edge of the Tray in the X-direction to the center of the vial position 1. Measured in mm. |
| Spl1 Offset Y | The "Y" offset is defined as the distance from the outer edge of the Tray in Y-direction to the center of the vial position 1. Measured in mm. |
| Spl1 Offset Z | The "Z" offset can be selected for special cases where, e.g. the syringe needle has to reach a deeper point before penetration into a vial. A "Z" offset value = 0 considers the Tray surface or vial top as the reference point. Measured in mm. |

Items displayed in *"italic"* are available beginning with PAL Firmware Version 4.1.X.

note

The dimensions used for Row/Column Length or X-, Y-, Z-Offsets for Sample Number 1, are specific for a particular Tray Type. If a general adjustment for a Tray from a specific vendor – e.g. for a Deepwell Plate – has to be made, this should be done in the "Tray Type" class of Object. For fine tuning, the Offset items from the class "Trays" can be used.

Explanation for various Patterns in Tray Type:

1. Pattern Type "Regular".
The sample or well positions are equal distributed.

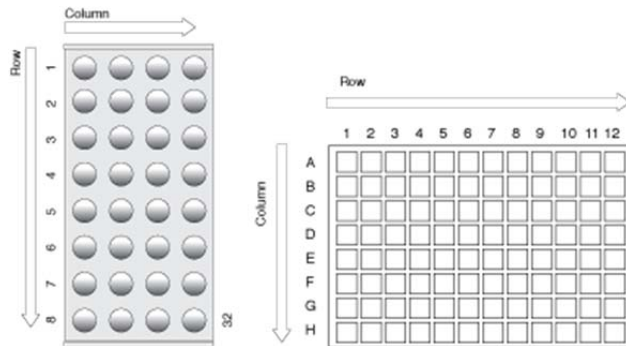


Figure 53. Pattern Tray Type "Regular"

2. Pattern Type "Staggrd+."
The sample or well positions are arranged in a staggered pattern.
Offset of second Row is shifted by + 50% of hole pattern.

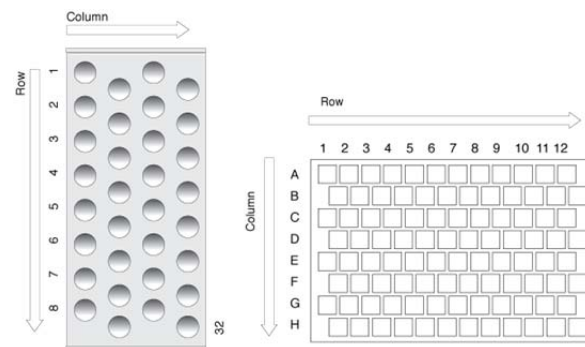


Figure 54. Pattern Tray Type "Staggered+"

3. Pattern Type "Staggrd-".
The sample or well positions are arranged in a staggered pattern.
Offset of second Row is shifted by - 50% of hole pattern.

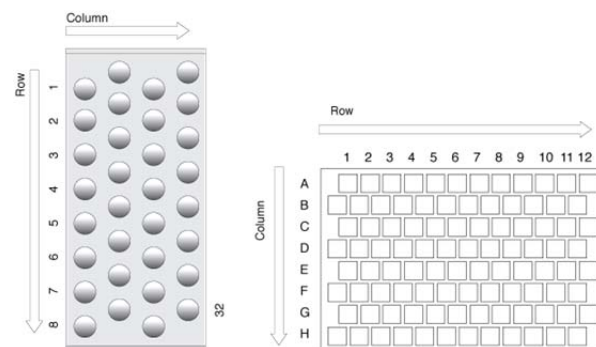


Figure 55. Pattern Tray Type "Staggered-"

10.3.2. Trays

The following object “Tray” Items can be changed by selecting the particular item. First select the desired Tray, such as “Tray1”.

| Item | Description |
|---------------|---|
| Tray Holder | The Tray Holder to which the Tray is assigned is specified. |
| TrayTypeGroup | All Tray Type Groups which are allowed for this particular combination of Tray and Tray Holder are displayed. The “TrayTypeGroup” for the Tray Type itself is specified for each Tray Type. |
| Tray Type | The Tray Type to be used is linked to the Tray. This item is usually set at User level in “Utilities/Trays”. See above. |
| Offset X | The “X” offset is defined as the distance from the center of the teaching position from the Tray Holder to the edge of the Tray in X-direction. Measured in mm. This item is available at User level in section “Utilities/Tray” and can be used for fine tuning a Tray installed in a Tray Holder. Important for well-plates 384 installed in a Stack. Remark: Position#1 is the only correction point. |
| Offset Y | The “Y” offset is defined as the distance from the center of the teaching position from the Tray Holder to the edge of the Tray in Y-direction. Measured in mm. This item is available at User level in section “Utilities/Tray” and can be used for fine tuning a Tray installed in a Tray Holder. Important for well-plates 384 installed in a Stack. Remark: Position#1 is the only correction point. |
| Offset Z | The “Z” offset is defined as the distance from the plate surface of the Tray Holder to the teaching point, black needle guide flush underneath plate of Tray Holder (which corresponds to plate thickness of Tray Holder). Measured in mm. This item is available at User level in section “Utilities/Tray” and can be used for fine tuning a Tray installed in a Tray Holder. Important for well-plates 384 installed in a Stack. Remark: Position#1 is the only correction point. |
| Path Offset X | The Path Offset “X” can be specific for a Tray, adjustment in X-direction. Expressed in mm. Remark: This item is only valid if a Path is assigned to the Tray Holder as specified in this combination. |
| Path Offset Y | The Path Offset “Y” can be specific for a Tray, adjustment in Y-direction. Expressed in mm. Remark: This item is only valid if a Path is assigned to the Tray Holder as specified in this combination. |
| Path Offset Z | The Path Offset “Z” can be specific for a Tray, adjustment in Z-direction. Expressed in mm. Remark: This item is only valid if a Path is assigned to the Tray Holder as specified in this combination. |
| <i>dxRow</i> | Correction for inclination of a Tray in X-row direction. For details, see Section 4.2.3.2 above. |
| <i>dYRow</i> | Correction for inclination of a Tray in Y-row direction. For details, see Section 4.2.3.2 above. |
| <i>dzRow</i> | Correction for inclination of a Tray in Z-row direction. For details, see Section F. “Description and Installation”, point 4.2.3.2 above. |
| <i>dxCol</i> | Correction for inclination of a Tray in X-column direction. For details, see Section F. “Description and Installation”, point 4.2.3.2 above. |
| <i>dyCol</i> | Correction for inclination of a Tray in Y-column direction. For details, see Section F. “Description and Installation”, point 4.2.3.2 above. |
| <i>dzCol</i> | Correction for inclination of a Tray in Z-column direction. For details, see Section F. “Description and Installation”, point 4.2.3.2 above. |

Items displayed in “*italic*” are available beginning with PAL Firmware Version 4.1.X.

10.3.3. Wash Stations

The following object “Wash Station” items may be changed by selecting the particular item. First select the desired Wash Station, such as “Wash1”.

| Item | Description |
|---------------|--|
| Position X | X-axis position for Wash Station. |
| Position Y | Y-axis position for Wash Station. |
| Position Z | Z-axis position for Wash Station. |
| Z Tolerance | A tolerance window for a plus/minus range (expressed in mm) where the Injection Unit has to expect an object. If the value of this item is > 0 , this is a relative detection mode and the sensor from the Injection Unit needle guide is active. If the value of this item is set to “0” the sensor of the needle guide is turned off and the syringe slider moves to an absolute value, Z-axis position as specified in the object. |
| Z Retract | The distance to lift up the syringe slider before the Y-, Z-axes assembly moves across the unit can be specified, expressed in mm. |
| Max Penetrat | The maximum allowed Needle Penetration can be defined as a safety so that the user cannot destroy the needle tip by going too far down. The maximum needle penetration must not exceed the length of the syringe needle, considering the loss due to needle guide, etc.. Typical needle length is 51 mm, maximum penetration must not exceed 48 mm. |
| Needle Penetr | This item is identical to that at the User level. The value defined at this level is mirrored to the Extended User Level. |
| Type | The specific mode for the Wash station in use has to be defined: Standard = Standard Wash Station. Syringe is filled with wash solvent and expelled into Waste. Pulse = A pulsed signal is sent to activate the device. Used for the “Fast Wash Station” and “Active Wash Station”. See Type ‘Active’ for details. Flow = Continuous flow of liquid by gravity. No electrical contact required for a solenoid. DLW = Dynamic Load & Wash. Item used to activate specific solenoid for DLW Wash Station. Active = Used for Active Wash Station in conjunction with the Wash Station Print with PNo. ‘APR WASHPUMP B.A.’ (Revision B). Simplified print, activation of pumps is controlled by PAL Firmware. Requires Object Lists ‘PAL WashActive_Rev. B’. Remark: Type ‘Active’ is not used for Fast Wash Station operation and cannot be used for first generation Active Wash Station with print Revision A installed. For these cases is the type ‘Pulse’ required. |
| Flow Control | The power source to activate a Wash Station is specified. For the Fast, Active Wash Station and DLW the Event “Power-Out1” and “Power-Out2” are used. |
| Ndl Cln Path | A Path can be assigned to the Wash Station. |
| Waste to | The Waste position is assigned to the Wash Station. |
| Clean Volume | A percentage of the syringe maximum volume is defined for the cleaning step. |
| Clean Count | The counter monitors the number of wash cycles. The setting in the method has the same functionality and the value is mirrored to the Extended User Level. |
| Max Fill Spd | The fill speed for the syringe is defined with this item. If the maximum value of the Fill Speed (10.0 mL/s) is selected, the system takes the injection syringe Fill Speed as defined in the method. |
| Max Eject Spd | The Eject Speed is the speed used to eject the wash solvent during the wash cycle. This speed is usually higher than the Fill Speed. If the maximum value of the Eject Speed (10.0 mL/s) is selected, the system takes the injection syringe Eject Speed as defined in the object class “Syringe”. |
| Rinse Time | Rinse is the time to rinse the wash port with wash solvent after the wash cycle of the syringe has been finished. In the case of a Fast/Active Wash Station, the syringe needle is pulled out of the wash port. The wash solvent flows without restriction. As a result, higher solvent consumption has to be taken into consideration. |

Items displayed in “*italic*” are available beginning with PAL Firmware Version 4.1.X.

G. Troubleshooting PAL and PAL-xt System

note

The HTC PAL always represents one of several total components in a chromatography system. The following Troubleshooting Guide is limited to the HTC PAL or PAL-xt only.

| Symptom or Error Message | Possible Cause | Recommended Action |
|--|---|---|
| No or very low detector signal is observed. | Clogged syringe. | Remove syringe and aspirate/dispense liquid manually. Clean syringe. |
| | Bent needle. | Inspect and/or change syringe. |
| | No sample liquid is injected. | Check and/or adjust Needle Penetration into sample vial (see section F, point 6.2.). |
| | Sample volume too low. | Increase sample volume. |
| | The valve needle guide and/or needle seal are not properly installed. | Check valve needle guide and seal (see section F, point 6.2.5.). |
| | The valve ports are not plumbed correctly to the pump and/or detection system. | Check plumbing connections (see section F, point 6.2.). |
| | Wrong valve type specified. | Check valve type by selecting path: Menu/setup/Objects/Injectors/LCVlv1/valve. |
| Mobile phase and/or sample flows out of the wrong ports on LC injection valve. | The valve rotor is reversed (180 ° out of alignment). | Remove the rotor and reinstall in the correct position. In case of a Cheminert valve, check for marking points. In case of a W-type valve look for a letter (e.g. "H") stamped on the rotor. The letter must be on the lower half of the rotor. See section F, point 6.2.). |
| Sample is backing up on the valve needle guide. | Syringe OD too small. | Check the syringe needle for correct Gauge. Gauge 22 = OD 0.72 mm Gauge 19 = OD 1.06 mm |
| | Valve needle seal leaks. | Change valve needle seal, see section F. point 6.2.5.) |
| | The needle penetration depth for the injection valve is not set correctly. | Adjust the Injection Valve Needle Penetration (see section F, point 6.2.6.). |
| | The syringe Plunger speed is too high resulting in excessive pressure in inlet. | Reduce Inject Speed in method. |
| Syringe does not fill properly. | Air bubbles below Syringe plunger. Air bubbles may remain below the plunger after the first pull up. If the plunger is moved up and down several times, these air bubbles are worked out. | Increase method parameter "Fill Strokes". Check syringe parameter "Eject Speed". |
| Sample peaks or responses are not reproducible. | Dirty syringe. | Increase Pst Cln Slv1/Slv2 values in method. Use PreClnSlv1/Slv2 and PreClnSpl. |
| | Syringe pressure differences. | Increase Pullup Delay value. |
| | Vacuum created in sample vial. | Reduce sample volume in sample vial. Use setting under "F3-Setup/System/PrePressureVial". |
| | Method Parameters | Check recommended Method Parameters in Flow Chart "Firmware Overview", Appendices, point 4. The following parameters are crucial and should be verified first: - Fill speed - Pullup delay - Injection Speed - Post Inj Delay |

| | | |
|--|--|--|
| Peak distortion or tailing. | Method Parameters. | See recommended actions above. |
| | Solvent for analytical solution not suitable. | Change solvent composition to a lower polarity (in case of reversed phase chromatography). |
| | Tubing internal diameter | Check tubing internal diameters for connection tubings and injection loop. See recommendations as given with poster 'Tips&Hints for HPLC Technique' (CTC Analytics). |
| | Bad connections | Connection tubing's not square cut or wrong type of nuts/ferrules installed. See recommendations as given with poster 'Tips&Hints for HPLC Technique' (CTC Analytics). |
| Excessive carryover between samples. | HPLC related problems | Any parameter like flow rate, composition of mobile phase or wash solvent, column selection (diameter, pore size, etc.) can contribute to BAD PEAK SHAPE. Check troubleshooting guide from the HPLC manufacturer or any other source. |
| | Dirty syringe and/or valve injection port. | Increase Pst Inj Slv1/Slv2 values in method. Use PreClnSlv1/Slv2 and PreClnSpl. |
| | Inappropriate wash solvent(s). | Use appropriate wash solvent(s). |
| | Waste tubing ID at injection valve is too small, causing waste liquid to be pulled back, by capillary action, into rotor groove. | Replace the waste tubing with larger ID tubing. |
| | Damaged or grooved valve rotor. | Replace valve rotor, see section H, point 4. |
| | Valve needle seal leaks. | Change valve needle seal, see section F, point 6.2.5. |
| | Inappropriate wash solvent composition. | Use appropriate wash solvent. Observe also the order of use for biological samples. First wash is always an aqueous solution followed by organic solvents. |
| Unexplained collisions of the Injection Unit. | Object(s) not defined correctly. | Define Object(s) correctly. (See section F. "Describing and Installing", point 4.1.) |
| Error Message "Object Not Detected". | Incorrect Z value for the affected Object (e.g. LCVlv1, THldr1 or CStk1-01). | Redefine Z value for the affected Object. (See section F. "Describing and Installing", point 4.1.) |
| | Missing sample vial, Deepwell- or Microtiter plate. | Check position and insert, if necessary, vial, deepwell- or microtiter plate. |
| Error Message "Object collision before Z Tolerance" ("Object" e.g. Tray1, LCVlv1, CStk1-01). | Incorrect Z value for the affected object. | Redefine value for the affected object. (See section F, point 4.1.) |
| Error Message "Invalid Motor Status Motor AUX1". (AUX2) | Injection valve not connected. | Switch OFF PAL and check connection between PAL and Valve Drive. |
| | Defective LCVlv Connection cable. | Change connection cable. |
| | MOTIO Board defective. | Replace MOTIO or Control-xt Board. |

H. Replacing Parts

note*Safety Warning*

Always disconnect the power cord(s) from the power supply or from the various power supplies if optional devices are installed before attempting any type of maintenance.

Capacitors inside the instrument may still remain charged even if the instrument is turned off.

To avoid damaging electrical parts, do not disconnect an electrical assembly while power is applied to the PAL system. Once the power is turned Off, wait approximately 30 seconds before you disconnect an assembly.

1. Control Board

PNo.: APR Control-HTC

1. Follow the sequence shown in Figure 56 to detach and release the Control board from its position inside the X-axis;
2. Carefully pull the two ribbon cable connectors upwards to free them from the board;
3. Install the replacement board in the reverse order.

note

After reconnecting the two ribbon cables to the board, ensure that the cables are folded flat and can slide inside the X-axis without damage.

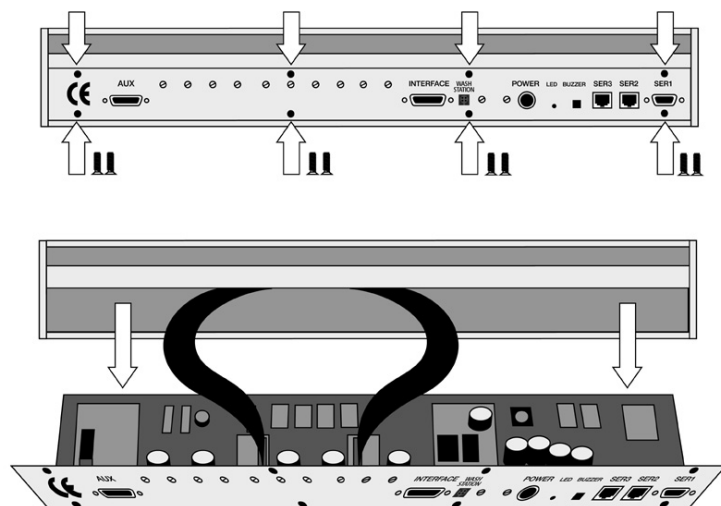


Figure 56. Replacing Control-HTC Board

2. Control-xt Board

PNo.: APR Control-xt

note

The Control-xt board replaces the control Board "APR Control-HTC". This board is required for the PAL HTC-xt System and operates only at PAL Firmware version 4.1.X or higher.

1. Follow the sequence shown in Figure 57 to detach and release the Control-xt board from its position inside the X-axis. As shown, remove the dummy cover first;
2. Carefully pull the two ribbon cable connectors upwards to free them from the board;
3. Install the replacement board in the reverse order.

note

After reconnecting the two ribbon cables to the board, ensure that the cables are folded flat and can slide inside the X-axis without damage.

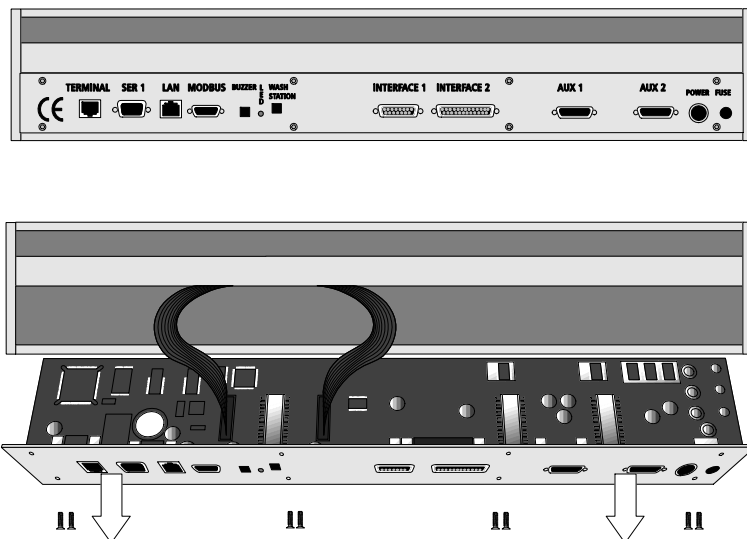


Figure 57. Replacing Control-xt Board

3. Injection Valve and Valve Rotor

note

This section describes the commonly used injection valves with 6-ports described. For more details or information on other valve types, such as a 10 port valve, see Addendum to PAL User Manual "Valve drives and Valves".

3.1. Injection Valve

3.1.1. Cheminert Type Valve

To replace and/or clean the injection valve, Cheminert type, follow the steps shown in Figure 58.

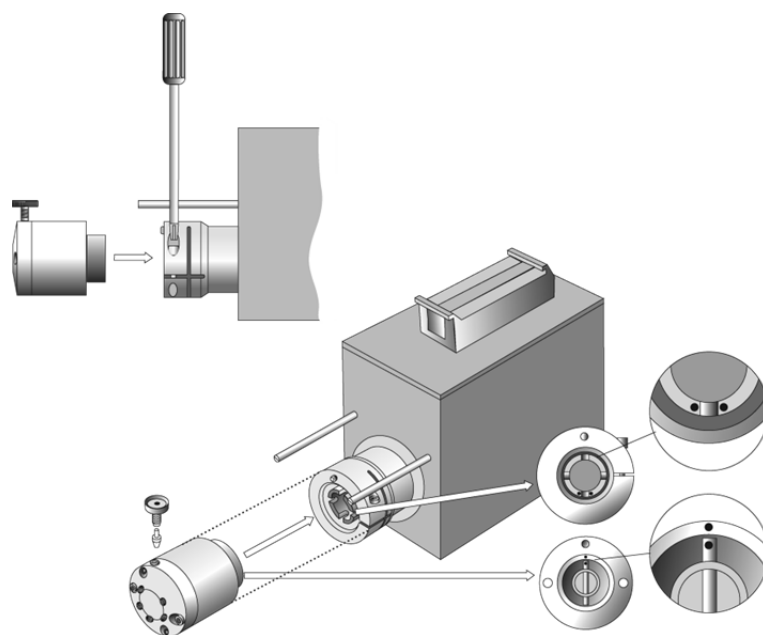


Figure 58. Replacing the Injection Valve VICI/Valco Cheminert Type

1. Remove the sample loop, needle guide fitting and connection tubes from the valve body;
2. Unscrew the Torx screw at the valve adapter, which holds the valve to the valve drive;
3. Check that the valve guide pin remains at its position and observe the guide marks as shown in Figure 58;
4. Install the replacement valve in the reverse order.

3.1.2. W-Type Valve.

To replace and/or clean the injection valve, W type, follow the steps shown in Figure 59.

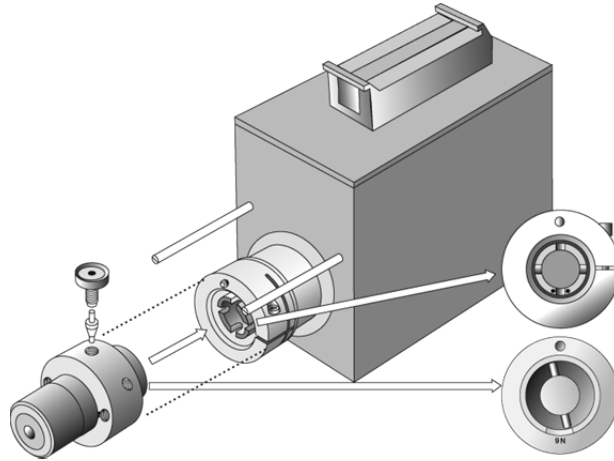


Figure 59. Replacing the Injection Valve Valco W-Type

1. Remove the sample loop, needle guide fitting and connection tubes from the valve body;
2. Unscrew the Torx screw at the valve adapter, which holds the valve to the valve drive;
3. Check that the valve guide pin remains at its position;
A guiding mark is not stamped in, in doubt check the orientation of the rotor as shown below in Figure 63;
4. Install the replacement valve in the reverse order.

3.1.3. Rheodyne Valve PD7991 (Diameter Valve Pod 27 mm)

To replace and/or clean the injection valve, Rheodyne PD7991 type, follow the steps shown in Figure 60.

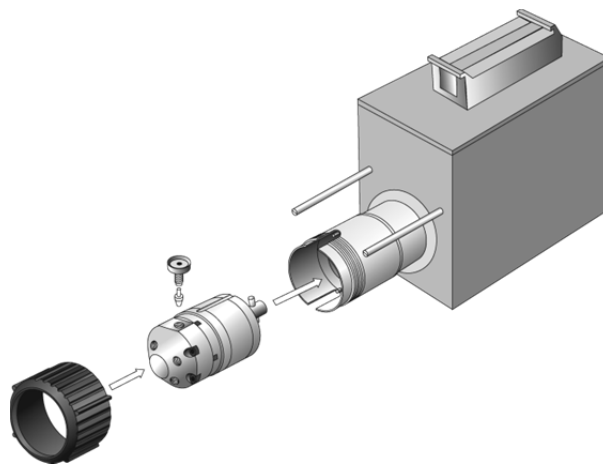


Figure 60. Replacing the Injection Valve Rheodyne PD7991-Type

1. Remove the sample loop, needle guide fitting and connection tubes from the valve body;
2. Unscrew the plastic threaded sleeve at the valve adapter, which holds the valve to the valve drive. Pull out the valve body from the drive sleeve;
3. Check that the valve guide pin remains at its position. Observe the correct orientation of the guiding pin as shown below in Figure 64 and Figure 65 for the Valve Drive position;
4. Install the replacement valve in the reverse order.

3.1.4. Rheodyne Valve PD718-313 (Diameter Valve Pod: 32 mm)

To replace and/or clean the injection valve, Rheodyne PD718-313 type, follow the steps shown in Figure 61.

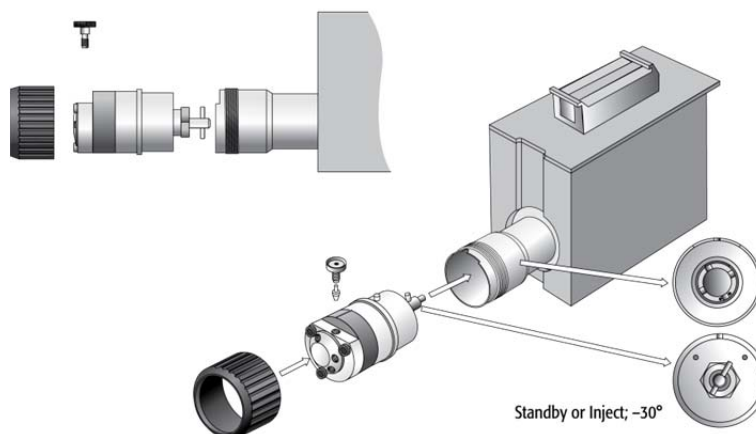


Figure 61. Replacing the Injection Valve Rheodyne PD719-313

1. Remove the sample loop, needle guide fitting and connection tubes from the valve body;
2. Unscrew the threaded plastic sleeve at the valve adapter, which holds the valve to the valve drive. Pull out the valve body from the drive sleeve;
3. Check that the valve guide pin remains at its position; Observe the correct orientation of the guiding pin as shown below in Figure 66 and Figure 67 for the Valve Drive position;
4. Install the replacement valve in the reverse order.

3.2. Replacing Valve Rotor

3.2.1. Cheminert Valve

To replace and/or clean the valve rotor of a VICI/Valco Cheminert type valve, follow the steps shown in Figure 62.

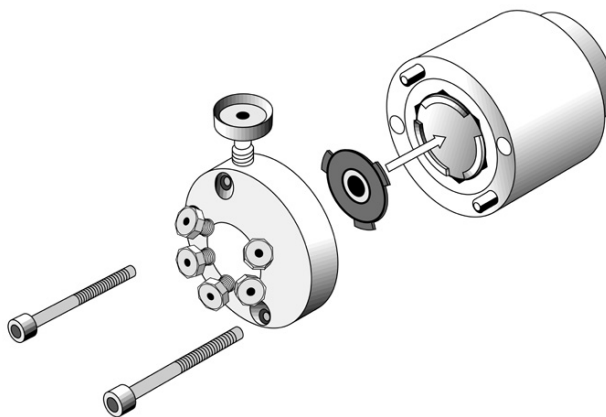


Figure 62. Rotor Replacement of Cheminert Type Valve

1. Do not remove the valve from the valve drive. For reasons of improved access, all tubing or the loop may be removed;
2. Unscrew the two hex screws which hold valve stator to the valve body;
3. Carefully lift out the rotor disk with a protected tool (tips protected to avoid scratching the surface);
4. Insert the new rotor. The positioning tabs are size coded. Incorrect insertion upside down is not possible;
5. Tighten the hex screws carefully and evenly to reach a parallel seat of valve stator and body.

3.2.2. Replacing W-Type Valve Rotor

To replace and/or clean the valve rotor of a Valco W-type valve, follow the steps shown in Figure 63.

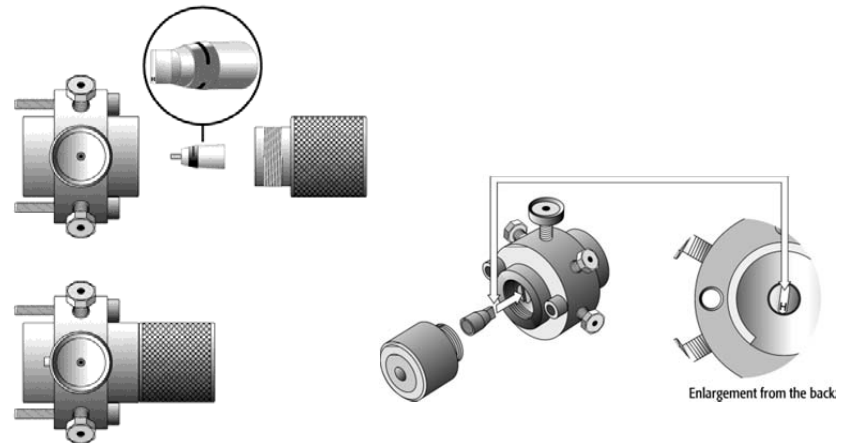


Figure 63. Rotor Replacement of W-Type Valve

1. Do not remove the valve from the valve drive. For reasons of improved access all tubing or the loop may be removed;
2. Unscrew the knurled pre-load assembly. Do not tamper with the preset socket adjustment screw;
3. Engage the end of the rotor with a magnet or a pair of tweezers (tips protected to avoid scratching the surface);
4. Locate the letter (e.g. "H") stamped on the new or cleaned rotor and orient the letter to the lower half of the valve;
5. Insert the new or cleaned rotor. Make sure the rotor tab fits into the slot in the valve drive;
6. Replace the knurled pre-load assembly;
7. Tighten the pre-load assembly. It must end up fully bottomed-out.

3.2.3. Replacing Rheodyne PD7991-Type Valve Rotor

To replace and/or clean the valve rotor of a Rheodyne PD7991-type valve, follow the steps shown in Figure 60.

note

The Rheodyne Valve PD7991 can be maintained in a similar way as the Cheminert valve type. Replacing the rotor has to be done carefully, it is possible to insert it upside down. Below, the correct orientation of the Rotor guide pin is illustrated.

Rotor position, view from backside of valve body, actuator side:

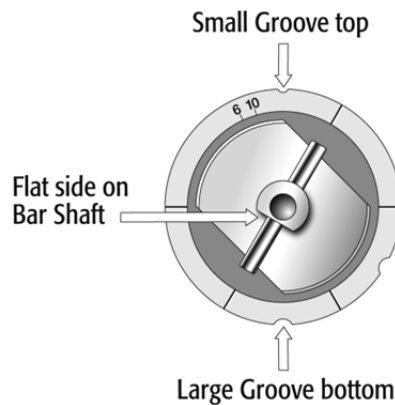


Figure 64. Rheodyne Valve PD 7991, Rotor Position

Valve Drive position in “Home” or “Standby” position:

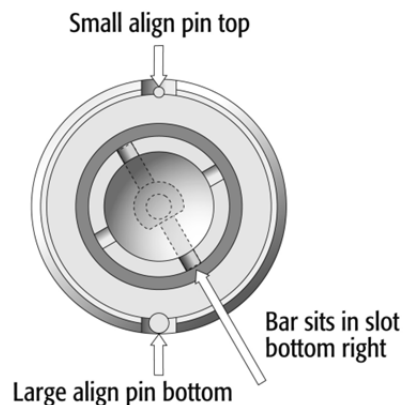


Figure 65. Valve Drive Settings for Rheodyne Valve PD7991

3.2.4. Replacing Rheodyne PD718-313-Type Valve Rotor

To replace and/or clean the valve rotor of a Rheodyne PD718-313-type valve, follow the steps shown in Figure 62.

note

The Rheodyne Valve PD718-313 can be maintained in a similar way as the Cheminert valve type. Replacing the rotor has to be done carefully, as it is possible to insert it incorrectly, upside down. Below, the correct orientation of the Rotor guide pin is illustrated.

Rotor position, view from backside of valve body, actuator side:

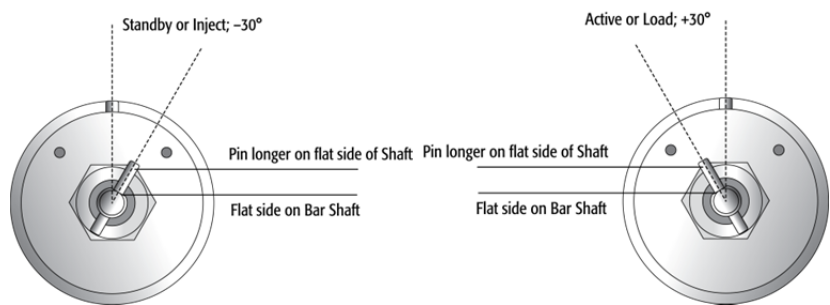


Figure 66. Valve Position 'Standby' and 'Active'

Valve drive Actuator, View from front of Actuator



Figure 67. Actuator Position 'Standby and 'Active'

4. Injection Unit

Follow the sequence of steps shown in section F. "Description and Installation", point 3.2, "Assembling the HTC PAL".

5. Wash Station

Follow the sequence of steps shown in section F. "Description and Installation", point 3.2, "Assembling the HTC PAL".

I. Maintaining the PAL System

Regularly performing maintenance helps ensure accuracy and precision of the PAL System. Suggested intervals for maintenance procedures are given below to ensure uninterrupted operation.

If you use the system extensively (for example, nights and weekends), or if you use corrosive solvents, you may need to perform the maintenance procedure more frequently.

| Maintenance Step | Interval |
|--|--|
| Clean the outside of the instrument. Use only a soft lint-free cloth dampened with mild soap and water. | Weekly or as needed |
| Clean Instrument, syringe and surfaces | Weekly or as needed. |
| Replace the syringe plunger | Syringe Plunger for a gas tight syringe (polymer tip) has to be replaced on a regular basis. The interval is highly dependent on the application, throughput, quality of sample solution (particles, etc.) washing solvent. It is advisable to check the tightness of the plunger on a regular basis to gain experience with the application. |
| Replace the Valve Needle Seal | Check the tightness of the needle in the needle seal. See section F, point 6.2.5. |
| Replace the Valve Rotor | Annually or more often, depending on the throughput and quality of sample solution and mobile phase. |
| Wash and Waste Solvent reservoirs | Weekly or as needed. Replace the Septum as well to avoid carry-over. |

The other steps are described in the "Preventative Maintenance Procedure". Specific kits for the GC or the HPLC techniques are available. The kits include the parts which must be changed annually.

The Kit PMKitDLW includes all parts from the PM Kit1 but additionally the specific parts for the PAL DLW Option.

- PNo.: PAL PM Kit1; Description: PM Kit for HPLC technique
- PNo.: PAL PMKitDLW;
Description: PM Kit for HPLC Systems including PAL DLW Option.
- PNo.: PAL PM Kit2; Description: PM for GC technique.

Contact your CTC Analytics representative to perform an annual preventative maintenance on the PAL System.

note

There are no operator-serviceable or replaceable parts inside the power supply(ies) or the PAL System. In case of a failure, contact a representative of CTC Analytics.

J. Appendices

1. Definition of Terms

Job Queue

A Job Queue is a list of sample processing Jobs. Jobs are executed in the order displayed on the JOB QUEUE menu screens. New Jobs may be added to the queue while samples are being processed.

Job

A Job contains the information needed by the PAL to process multiple samples by the same processing steps. The elements of a Job are a Method and a Tray that define the location of the samples to be processed. For identification, Jobs are automatically numbered from 01 to 99 and then restarting with 01 when they are added to the Job Queue.

Cycle

A Cycle consists of the specific operations necessary to process one sample. The Cycle operations are repeated for each sample within a Job. Cycles are designed for specific applications.

Method

A Method defines how the samples are processed. The elements of a Method are a Cycle, a Syringe and a Parameter List. Methods have names with up to eight characters and can be edited, copied, and deleted.

Method Parameters

Method Parameters are associated with the Cycle operations. User-assigned Parameter values define how a processing operation is performed. A zero Parameter value will disable a Cycle operation. Cycle Parameters are application-specific.

Tray Holder

A Tray Holder can hold one or more trays. Each Tray Holder has a reference position (X-, Y-, Z-coordinates) that defines its location.

Tray

A Tray holds multiple samples. Trays are defined by designating the Tray Type (see below) and the Tray Holder. Tray names are used to identify the sample source within a PAL Job.

Tray Type

A Tray Type defines the pattern and sampling sequence of sample locations within a Tray.

Stack

A Stack is a particular type of Tray Holder that is designed to hold micro-plates. A six-drawer Stack holds 12 standard microplates, two in each drawer. A three-drawer Stack holds six deep-well micro-plates, two in each drawer.

PAL Object Manager

Software to load a PAL Object List to an instrument if a Module (hardware module) has been added to the PAL System. In a special mode Object Manager can also be used to create and maintain Object Lists.

PAL Object List

If a PAL Module (hardware) is added to an instrument, several Objects have to be loaded into the firmware. These Objects are collected in an Object List and stored in a file with the extension "*.pol".

Object Lists are delivered together with Object Manager Software and are grouped into folders for the different kind of Modules (e.g. Syringes, Tray Holders, Valve Drives). The name of an Object List starts with the Module part number with variants added (e.g. first or second Stack). The name of the root folder includes the revision which is dependent on the firmware version (e.g. "Object Lists Rev. K" for firmware 2.X and 3.X).

Object Class

Each Object belongs to an Object Class (e.g. Syringes, Trays, Injectors). The Object Class defines the Items of an Object.

Object Item

An Object contains several Items which can be numerical values with a physical unit (e.g. X-, Y-, Z-Position, Penetration, Syringe Scale Length, Syringe Volume) or references to other objects.

Note that the term "Parameter" is reserved for "ATOM Parameter" (PAL Firmware commands to be used for a PAL Cycle or Macro).

Objects

Objects are data structures describing the properties of physical modules. Certain modules (e.g. a Stack) require several objects.

Module

PAL hardware module, either part of a standard PAL configuration (e.g. COMBI PAL, HTS PAL) or an optional addition (e.g. Cooled Stack, MALDI Tool, Dilutor). The term "Module" is intentionally used to differentiate from "Object", which is reserved for the PAL Firmware Object.

2. Naming Convention

This section recommends the standard naming convention for HTC PAL Trays, Tray Types, and Tray holders. Following these conventions will allow the HTC PAL to be pre-configured for certain applications, will simplify software backups and application development, and will improve technical support and training.

| Tray Type | Tray Description |
|-----------|--|
| VT200 | Vial Tray, 200 positions (10 x 20) For 7 mm micro-vials, 1 mL |
| VT98 | Vial Trays, 98 positions (7 x 14) For 12 mm vials, 2 mL |
| VT78 | Vial Tray, 78 positions (6 x 13) For 7 mm micro-vials, 1 mL (opposite side of 98 positions Tray) |
| VT54 | Vial Tray, 54 positions (6 x 9) For 12 mm vials, 2 mL |
| VT21 | Vial Tray, 21 Positions (7 x 14) For 12 mm vials, 2 mL (opposite side of 32 positions Tray) |
| VT32-10 | Vial Tray, 32 positions (4 x 8) For 23 mm headspace vials, 10 mL |
| VT32-20 | Vial Tray, 32 positions (4 x 8) For 23 mm headspace vials, 20 mL |
| MT96 | Standard 96-position shallow microplate |
| DW96 | Deep well 96-position microplate |
| MT384 | High density 384-position shallow microplate |

3. HTC PAL and -xt Injection Cycles

3.1. HTC PAL and -xt "LC-Inj" Cycle

| No. | Processing Step | Method Parameter | Object (Class) | Used Object Value |
|-----|--|---|---|--|
| 1 | Reference X, Y, Z axes and syringe plunger | | (System) | Start Ref = ON |
| 2 | Wait for start signal | | Start (Sync Signals) | |
| 3 | Read Barcode if enabled | | TRAY (Tray Type) | Barcode • None |
| 4 | Syringe wash strokes with solvent from Wash1 | Pre Cln Slv1 | SYRINGE (Syringes) Wash1 (Wash Stations) | Fill Speed Eject Speed Needle Penetr Clean Volume Max Fill Speed Max Eject Speed |
| 5 | Syringe wash strokes with solvent from Wash2 | Pre Cln Slv2 | SYRINGE (Syringes) Wash2 (Wash Stations) | Fill Speed Eject Speed Needle Penetr Clean Volume Max Fill Speed Max Eject Speed |
| 6 | Rinse syringe with sample selected number of times | Pre Cln Spl Sample Volume Fill Speed Pullup Delay | SYRINGE (Syringes) TRAY (Tray Type) Waste (Injectors) | Eject Speed Fill Volume Needle Penetr Needle Penetr |
| 7 | Fill syringe with sample using several filling strokes; aspirate air outside of vial if Air Volume > 0 | Sample Volume Air Volume Fill Speed Fill Strokes Pullup Del | SYRINGE (Syringes) TRAY (Tray Type) | Eject Speed Overfill Fill Volume Needle Penetr |
| 8 | Move to injection valve | Inject to | | |
| 9 | Wait for Inject signal | | Inject (Sync Signals) | |
| 10 | Drive needle to penetration depth | Inject to | (Injectors) | Needle Penetr |
| 11 | Delay | Pre Inj Del | | |
| 12 | Switch valve to Active position | | | |
| 13 | Activate Injected signal | | Injected (Out Signals) | Pulse Time |
| 14 | Activate Injectd+Signal | | Injectd+ (Out Signals) | Pulse Time |
| 15 | Dispense syringe contents into sample loop | Inject Speed | | |
| 16 | Delay | Pst Inj Del | | |
| 17 | Switch valve to Standby position | | | |
| 18 | Retract needle from injector | | | |
| 19 | Clean syringe and needle with solvent from Wash1 | Pst Cln Slv1 | SYRINGE (Syringes) Wash1 (Wash Stations) | Fill Speed Eject Speed Needle Penetr Clean Volume Max Fill Speed Max Eject Speed |
| 20 | Clean syringe and needle with solvent from Wash2 | Pst Cln Slv2 | SYRINGE (Syringes) Wash2 (Wash Stations) | Fill Speed Eject Speed Needle Penetr Clean Volume Max Fill Speed Max Eject Speed |
| 21 | Rinse valve inlet with solvent from Wash1 | Vlv Cln Slv1 | SYRINGE (Syringes) Wash1 (Wash Stations) | Fill Speed Inject Speed Needle Penetr Clean Volume Max Fill Speed Max Eject Speed |
| 22 | Rinse valve inlet with solvent from Wash2 | Vlv Cln Slv2 | SYRINGE (Syringes) Wash1 (Wash Stations) | Fill Speed Inject Speed Needle Penetr Clean Volume Max Fill Speed Max Eject Speed |
| 23 | Move to Home position | | Home (Positions) | |

3.1.1.1. "LC-Inj" Cycle Method Parameter Description

| Parameter | Description |
|---------------|---|
| CYCLE | LC-Inj Cycle |
| SYRINGE | Selected syringe |
| Sample Volume | Selected sample volume |
| Air Volume | Volume aspirated after the syringe needle is moved out of the sample liquid |
| Pre Cln Slv1 | Pre injection syringe wash strokes with solvent from Wash1 |
| Pre Cln Slv2 | Pre injection syringe wash strokes with solvent from Wash2 |
| Pre Cln Spl | Pre injection syringe rinse cycles with sample |
| Fill Speed | Speed of plunger movement used to aspirate sample |
| Fill Strokes | Number of filling strokes to aspirate sample |
| Pullup Del | Delay time between sample pull-up and ejection |
| Inject to | Name of Injector used for injection |
| Inject Speed | Speed of plunger movement used during sample injection |
| Pre Inj Del | Delay time prior to sample injection |
| Pst Inj Del | Delay time after sample injection |
| Pst Cln Slv1 | Post injection syringe wash strokes with solvent from Wash1 |
| Pst Cln Slv2 | Post injection syringe wash strokes with solvent from Wash2 |
| Vlv Cln Slv1 | Valve rinse cycles with solvent from Wash1 |
| Vlv Cln Slv2 | Valve rinse cycles with solvent form Wash2 |

3.2. HTC PAL and -*xt* "LC-Cut" Cycle

| No. | Processing Step | Method Parameter | Object (Class) | Used Object Value |
|-----|--|---|---|---|
| 1 | Reference X, Y, Z axes and syringe plunger | | (System) | Start Ref = ON |
| 2 | Initialize injection valve: If SplTrnsfDel = 0 then switch to STANDBY (INJECT) else switch to ACTIVE (LOAD) | Inject to SplTrnsfDel | (Injectors) | |
| 3 | Initialize cut valve: If Cut Time > 0 then switch to STANDBY | Cut Valve Cut Time | (Injectors) | |
| 4 | Start timer "MinCondTime" | MinCondTime | | |
| 5 | Wait for Start signal | | Start (Sync Signals) | |
| 6 | Read Barcode if enabled | | TRAY (Tray Type) | Barcode None |
| 7 | Syringe wash strokes with solvent from Wash1 | Pre Cln Slv1 | SYRINGE (Syringes) Wash1 (Wash Stations) | Fill Speed Eject Speed Needle Penetr Clean Volume Max Fill Speed Max Eject Speed |
| 8 | Syringe wash strokes with solvent from Wash2 | Pre Cln Slv2 | SYRINGE (Syringes) Wash2 (Wash Stations) | Fill Speed Eject Speed Needle Penetr Clean Volume Max Fill Speed Max Eject Speed |
| 9 | Rinse syringe with sample selected number of times | Pre Cln Spl Sample Volume Fill Speed Pullup Delay | SYRINGE (Syringes) TRAY (Tray Type) Waste (Injectors) | Eject Speed Fill Volume Needle Penetr Needle Penetr |
| 10 | Wait for timer "MinCondTime" elapsed to Zero | MinCondTime | | |
| 11 | Fill syringe with sample using several filling strokes; aspirate air outside of vial if Air Volume > 0 | Sample Volume Air Volume Fill Speed Fill Strokes Pullup Del | SYRINGE (Syringes) TRAY (Tray Type) | Eject Speed Overfill Fill Volume Needle Penetr |
| 12 | Move to injection valve | Inject to | (Injectors) | |
| 13 | Wait for Inject signal | | Inject (Sync Signals) | |
| 14 | Drive needle to penetration depth | Inject to | (Injectors) | Needle Penetr |
| 15 | If SplTrnsfDel = 0 then switch injection valve to ACTIVE (LOAD) position | Inject to SplTrnsfDel | (Injectors) | |
| 16 | Wait for Pre Injection Delay | Pre Inj Del | | |
| 17 | Dispense syringe contents into sample loop | Inject Speed | | |
| 18 | Wait for Post Injection Delay | Pst Inj Del | | |
| 19 | Switch Valve to STANDBY (INJECT) position. If SplTrnsfDel > 0 then switch valve back to ACTIVE (LOAD) after time SplTrnsfDel has expired. | Inject to SplTrnsfDel | (Injectors) | |
| 20 | Activate Injected Signal (System InjSignal = ValveSw) | | Injected (Out Signals) | If Pulse Time =0, min. Pulse Time of 300 ms. is used. Can be extended with "Pulse Time" |
| 21 | Start timer "Cut Delay" | | | |
| 22 | Retract needle from injector | | | |

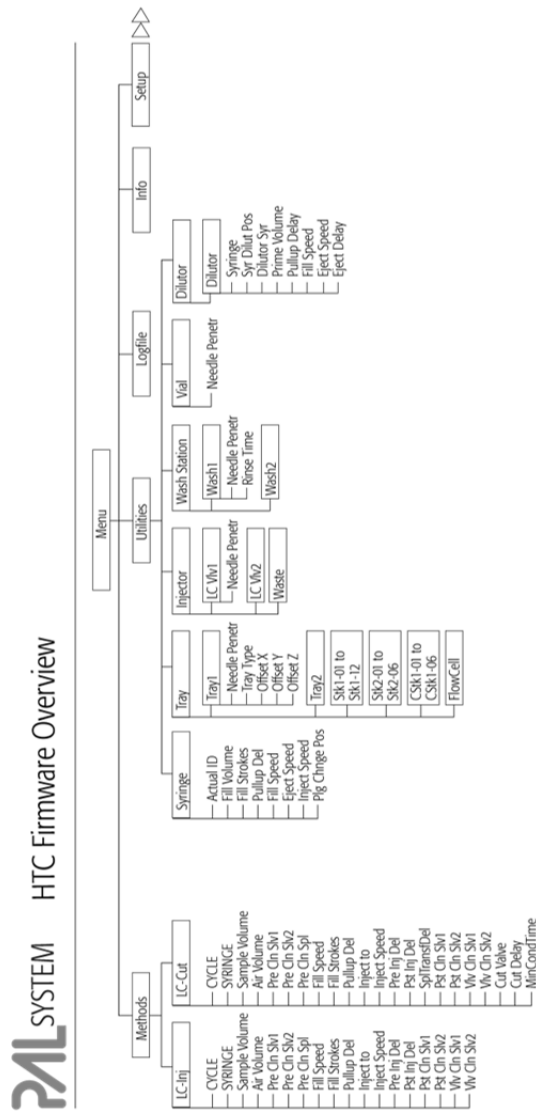
| No. | Processing Step | Method Parameter | Object (Class) | Used Object Value |
|-----|---|-----------------------|---|--|
| 23 | Clean syringe and needle with solvent from Wash1 | Pst Cln Slv1 | SYRINGE (Syringes) Wash1 (Wash Stations) | Fill Speed Eject Speed Needle Penetr Clean Volume Max Fill Speed Max Eject Speed |
| 24 | Clean syringe and needle with solvent from Wash2 | Pst Cln Slv2 | SYRINGE (Syringes) Wash2 (Wash Stations) | Fill Speed Eject Speed Needle Penetr Clean Volume Max Fill Speed Max Eject Speed |
| 25 | Rinse valve inlet with solvent from Wash1 | Vlv Cln Slv1 | SYRINGE (Syringes) Wash1 (Wash Stations) | Fill Speed Inject Speed Needle Penetr Clean Volume Max Fill Speed Max Eject Speed |
| 26 | Rinse valve inlet with solvent from Wash2 | Vlv Cln Slv2 | SYRINGE (Syringes) Wash1 (Wash Stations) | Fill Speed Inject Speed Needle Penetr Clean Volume Max Fill Speed Max Eject Speed |
| 27 | Wait for timer "Cut Delay" elapsed to Zero | Cut Delay | | These two steps are executed concurrent with the wash steps. |
| 28 | If Cut Time = 0 then toggle Cut Valve position else Switch Cut Valve to ACTIVE Wait for time Cut Time Switch Cut Valve to STANDBY | Cut Time Cut Valve | (Injectors) | |
| 29 | Move to Home position | | Home (Positions) | |

3.2.1. LC-Cut" Cycle Parameter Description

| Parameter | Description |
|---------------|---|
| CYCLE | LC-Cut Cycle |
| SYRINGE | Selected syringe |
| Sample Volume | Selected sample volume |
| Air Volume | Volume aspirated after the syringe needle is moved out of the sample liquid |
| Pre Cln Slv1 | Pre injection syringe wash strokes with solvent from Wash1 |
| Pre Cln Slv2 | Pre injection syringe wash strokes with solvent from Wash2 |
| Pre Cln Spl | Pre injection syringe rinse cycles with sample |
| Fill Speed | Speed of plunger movement used to aspirate sample |
| Fill Strokes | Number of filling strokes to aspirate sample |
| Pullup Del | Delay time between sample pull-up and ejection |
| Inject to | Name of Injector used for injection |
| Inject Speed | Speed of plunger movement used during sample injection |
| Pre Inj Del | Delay time prior to sample injection |
| Pst Inj Del | Delay time after sample injection |
| SplTransfDel | Time needed to transfer sample from Loop onto 2 nd valve (pre- or analytical column) |
| Pst Cln Slv1 | Post injection syringe wash strokes with solvent from Wash1 |
| Pst Cln Slv2 | Post injection syringe wash strokes with solvent from Wash2 |
| Vlv Cln Slv1 | Valve rinse cycles with solvent from Wash1 |
| Vlv Cln Slv2 | Valve rinse cycles with solvent form Wash2 |
| Cut Valve | Specify name of 2 nd valve, switching valve |
| Cut Delay | Time needed for clean-up. Switch to backflush sample, to analytical column or detector |
| MinCondTime | Minimum Conditioning Time: Time needed to condition pre-column on 2 nd valve |

4. PAL Firmware Overview

4.1. HTC PAL Flow Chart based on PAL Firmware Version 2.5.X (or higher within version 2.X.X).

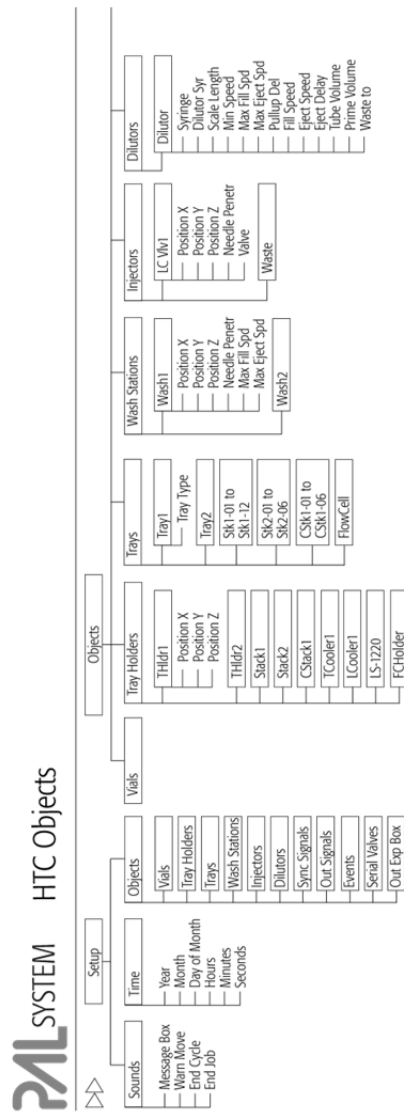


Notes:
Plunger Stroke and Valve Switch Counter
Menu/info/Maintenance

The standard software does not include every object as shown in the overview. The layout depends on the hardware configuration for each individual PAL-System

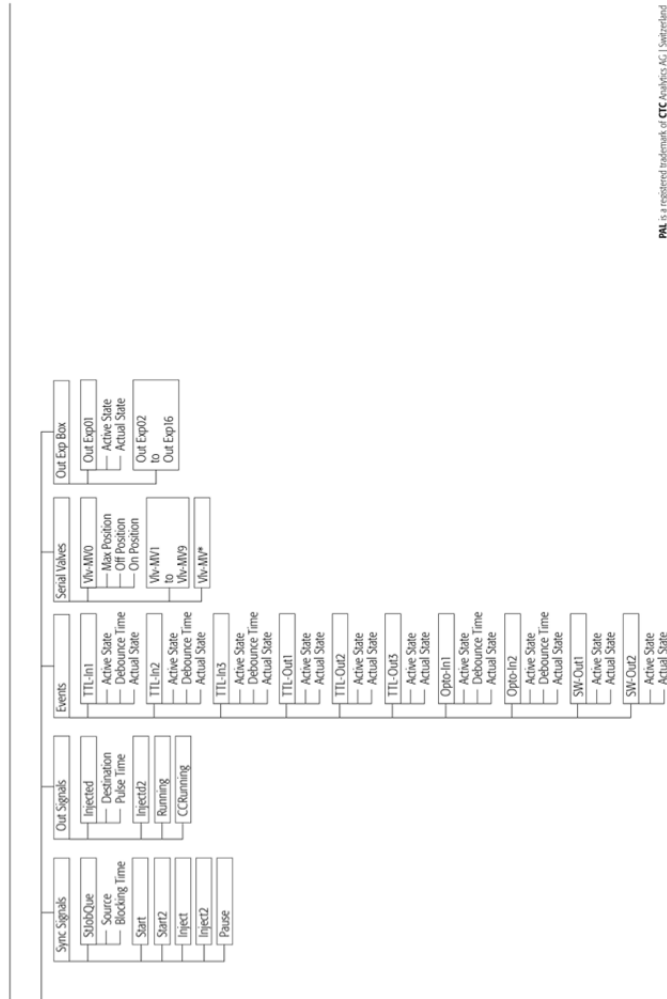
Revision C / Firmware 2.5.2 / June 2009

Figure 68. HTC PAL- Firmware Overview, Page 1



Note:
The standard software does not include every object as shown in the overview.
The layout depends on the hardware configuration for each individual PAL-System
Revision G / Firmware 2.5.2 / June 2009

Figure 69. HTC PAL- Firmware Overview, Page 2



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Figure 70. HTC PAL - Firmware Overview, Page 3

| Method Cycle | Recommended PAL Method Parameters | Remarks | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
|-----------------------|--|---------|---------|---------|--------|---------------|-------|------------|------|------------|---|------------|---|------------|---|------------|---------|--------------|---|------------|--------|-----------|-------|--------------|---------|-------------|--------|--------------|--------|-----------------------|---|------------|---|------------|---|------------|---|-----------|-------|-----------|---|------------|---|--|
| LC-Loop | <table border="1"> <tr><td>CYCLE</td><td>LC-Loop</td></tr> <tr><td>SYRINGE</td><td>100 µl</td></tr> <tr><td>Sample Volume</td><td>80 µl</td></tr> <tr><td>Air Volume</td><td>0 µl</td></tr> <tr><td>Pre-Ch SW1</td><td>1</td></tr> <tr><td>Pre-Ch SW2</td><td>0</td></tr> <tr><td>Pre-Ch SW3</td><td>2</td></tr> <tr><td>Fill Speed</td><td>10 µl/s</td></tr> <tr><td>Fill Strokes</td><td>3</td></tr> <tr><td>Pullup Del</td><td>3-10 s</td></tr> <tr><td>Inject to</td><td>LC-W1</td></tr> <tr><td>Inject Speed</td><td>10 µl/s</td></tr> <tr><td>Pre-Inj Del</td><td>500 ms</td></tr> <tr><td>Post-Inj Del</td><td>500 ms</td></tr> <tr><td>Pre-Ch SW1</td><td>2</td></tr> <tr><td>Pre-Ch SW2</td><td>0</td></tr> <tr><td>Pre-Ch SW3</td><td>2</td></tr> </table> | CYCLE | LC-Loop | SYRINGE | 100 µl | Sample Volume | 80 µl | Air Volume | 0 µl | Pre-Ch SW1 | 1 | Pre-Ch SW2 | 0 | Pre-Ch SW3 | 2 | Fill Speed | 10 µl/s | Fill Strokes | 3 | Pullup Del | 3-10 s | Inject to | LC-W1 | Inject Speed | 10 µl/s | Pre-Inj Del | 500 ms | Post-Inj Del | 500 ms | Pre-Ch SW1 | 2 | Pre-Ch SW2 | 0 | Pre-Ch SW3 | 2 | | | | | | | | | |
| CYCLE | LC-Loop | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| SYRINGE | 100 µl | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Sample Volume | 80 µl | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Air Volume | 0 µl | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Pre-Ch SW1 | 1 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Pre-Ch SW2 | 0 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Pre-Ch SW3 | 2 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Fill Speed | 10 µl/s | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Fill Strokes | 3 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Pullup Del | 3-10 s | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Inject to | LC-W1 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Inject Speed | 10 µl/s | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Pre-Inj Del | 500 ms | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Post-Inj Del | 500 ms | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Pre-Ch SW1 | 2 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Pre-Ch SW2 | 0 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Pre-Ch SW3 | 2 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| LC-Cut | <table border="1"> <tr><td>CYCLE</td><td>LC-Cut</td></tr> <tr><td>SYRINGE</td><td>100 µl</td></tr> <tr><td>Sample Volume</td><td>80 µl</td></tr> <tr><td>Air Volume</td><td>0 µl</td></tr> <tr><td>Pre-Ch SW1</td><td>1</td></tr> <tr><td>Pre-Ch SW2</td><td>0</td></tr> <tr><td>Pre-Ch SW3</td><td>2</td></tr> <tr><td>Fill Speed</td><td>5 µl/s</td></tr> <tr><td>Fill Strokes</td><td>3</td></tr> <tr><td>Pullup Del</td><td>3-10 s</td></tr> <tr><td>Inject to</td><td>LC-W1</td></tr> <tr><td>Inject Speed</td><td>5 µl/s</td></tr> <tr><td>Pre-Inj Del</td><td>500 ms</td></tr> <tr><td>Post-Inj Del</td><td>500 ms</td></tr> <tr><td>Sample Transfer Delay</td><td>2</td></tr> <tr><td>Pre-Ch SW1</td><td>0</td></tr> <tr><td>Pre-Ch SW2</td><td>0</td></tr> <tr><td>Pre-Ch SW3</td><td>2</td></tr> <tr><td>Cut Value</td><td>LC-W2</td></tr> <tr><td>Cut Delay</td><td>0</td></tr> <tr><td>MinConfirm</td><td>0</td></tr> </table> | CYCLE | LC-Cut | SYRINGE | 100 µl | Sample Volume | 80 µl | Air Volume | 0 µl | Pre-Ch SW1 | 1 | Pre-Ch SW2 | 0 | Pre-Ch SW3 | 2 | Fill Speed | 5 µl/s | Fill Strokes | 3 | Pullup Del | 3-10 s | Inject to | LC-W1 | Inject Speed | 5 µl/s | Pre-Inj Del | 500 ms | Post-Inj Del | 500 ms | Sample Transfer Delay | 2 | Pre-Ch SW1 | 0 | Pre-Ch SW2 | 0 | Pre-Ch SW3 | 2 | Cut Value | LC-W2 | Cut Delay | 0 | MinConfirm | 0 | <p>Time needed to transfer sample from Loop onto 2nd valve (pre- or analytical column)</p> <p>Specify name of 2nd valve, switching valve time needed to clean-up, switch to load fresh sample, to analytical column or detector</p> <p>Minimum Conditioning Time: time needed to condition pre-column on 2nd valve</p> |
| CYCLE | LC-Cut | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| SYRINGE | 100 µl | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Sample Volume | 80 µl | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Air Volume | 0 µl | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Pre-Ch SW1 | 1 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Pre-Ch SW2 | 0 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Pre-Ch SW3 | 2 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Fill Speed | 5 µl/s | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Fill Strokes | 3 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Pullup Del | 3-10 s | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Inject to | LC-W1 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Inject Speed | 5 µl/s | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Pre-Inj Del | 500 ms | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Post-Inj Del | 500 ms | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Sample Transfer Delay | 2 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Pre-Ch SW1 | 0 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Pre-Ch SW2 | 0 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Pre-Ch SW3 | 2 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Cut Value | LC-W2 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Cut Delay | 0 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| MinConfirm | 0 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |

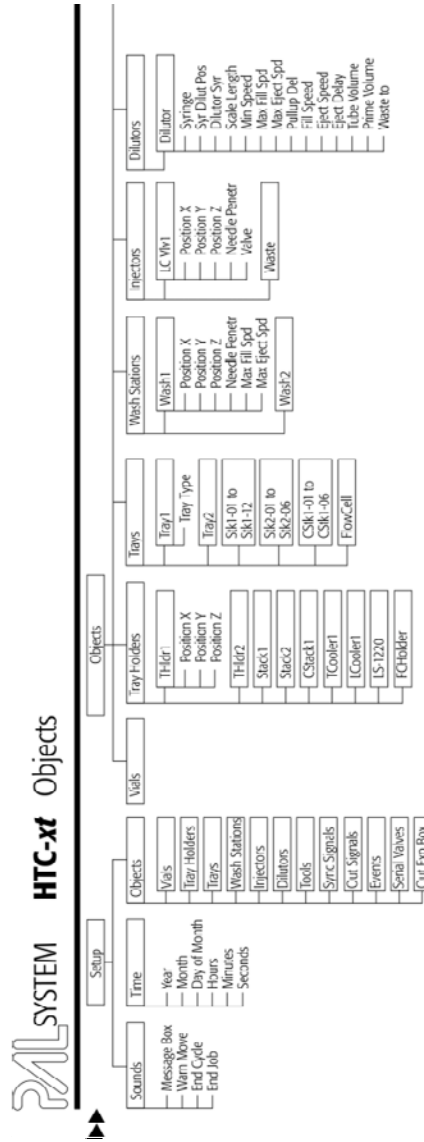
| Method Cycle | Recommended PAL Method Parameters | Remarks | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
|----------------|--|---------|---------|---------|--------|---------------|-------|------------|------|------------|---|------------|---|------------|---|------------|---------|--------------|---|------------|--------|-----------|-------|--------------|---------|-------------|--------|--------------|--------|------------|---|------------|---|------------|---|--|
| LC-Loop | <table border="1"> <tr><td>CYCLE</td><td>LC-Loop</td></tr> <tr><td>SYRINGE</td><td>150 µl</td></tr> <tr><td>Sample Volume</td><td>80 µl</td></tr> <tr><td>Air Volume</td><td>0 µl</td></tr> <tr><td>Pre-Ch SW1</td><td>1</td></tr> <tr><td>Pre-Ch SW2</td><td>0</td></tr> <tr><td>Pre-Ch SW3</td><td>2</td></tr> <tr><td>Fill Speed</td><td>10 µl/s</td></tr> <tr><td>Fill Strokes</td><td>3</td></tr> <tr><td>Pullup Del</td><td>3-10 s</td></tr> <tr><td>Inject to</td><td>LC-W1</td></tr> <tr><td>Inject Speed</td><td>10 µl/s</td></tr> <tr><td>Pre-Inj Del</td><td>500 ms</td></tr> <tr><td>Post-Inj Del</td><td>500 ms</td></tr> <tr><td>Pre-Ch SW1</td><td>2</td></tr> <tr><td>Pre-Ch SW2</td><td>0</td></tr> <tr><td>Pre-Ch SW3</td><td>2</td></tr> </table> | CYCLE | LC-Loop | SYRINGE | 150 µl | Sample Volume | 80 µl | Air Volume | 0 µl | Pre-Ch SW1 | 1 | Pre-Ch SW2 | 0 | Pre-Ch SW3 | 2 | Fill Speed | 10 µl/s | Fill Strokes | 3 | Pullup Del | 3-10 s | Inject to | LC-W1 | Inject Speed | 10 µl/s | Pre-Inj Del | 500 ms | Post-Inj Del | 500 ms | Pre-Ch SW1 | 2 | Pre-Ch SW2 | 0 | Pre-Ch SW3 | 2 | |
| CYCLE | LC-Loop | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| SYRINGE | 150 µl | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Sample Volume | 80 µl | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Air Volume | 0 µl | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Pre-Ch SW1 | 1 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Pre-Ch SW2 | 0 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Pre-Ch SW3 | 2 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Fill Speed | 10 µl/s | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Fill Strokes | 3 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Pullup Del | 3-10 s | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Inject to | LC-W1 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Inject Speed | 10 µl/s | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Pre-Inj Del | 500 ms | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Post-Inj Del | 500 ms | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Pre-Ch SW1 | 2 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Pre-Ch SW2 | 0 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Pre-Ch SW3 | 2 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| LC-Cut | <table border="1"> <tr><td>CYCLE</td><td>LC-Cut</td></tr> <tr><td>SYRINGE</td><td>100 µl</td></tr> <tr><td>Sample Volume</td><td>80 µl</td></tr> <tr><td>Air Volume</td><td>0 µl</td></tr> <tr><td>Pre-Ch SW1</td><td>1</td></tr> <tr><td>Pre-Ch SW2</td><td>0</td></tr> <tr><td>Pre-Ch SW3</td><td>2</td></tr> <tr><td>Fill Speed</td><td>10 µl/s</td></tr> <tr><td>Fill Strokes</td><td>3</td></tr> <tr><td>Pullup Del</td><td>3-10 s</td></tr> <tr><td>Inject to</td><td>LC-W1</td></tr> <tr><td>Inject Speed</td><td>10 µl/s</td></tr> <tr><td>Pre-Inj Del</td><td>500 ms</td></tr> <tr><td>Post-Inj Del</td><td>500 ms</td></tr> <tr><td>Pre-Ch SW1</td><td>2</td></tr> <tr><td>Pre-Ch SW2</td><td>0</td></tr> <tr><td>Pre-Ch SW3</td><td>2</td></tr> </table> | CYCLE | LC-Cut | SYRINGE | 100 µl | Sample Volume | 80 µl | Air Volume | 0 µl | Pre-Ch SW1 | 1 | Pre-Ch SW2 | 0 | Pre-Ch SW3 | 2 | Fill Speed | 10 µl/s | Fill Strokes | 3 | Pullup Del | 3-10 s | Inject to | LC-W1 | Inject Speed | 10 µl/s | Pre-Inj Del | 500 ms | Post-Inj Del | 500 ms | Pre-Ch SW1 | 2 | Pre-Ch SW2 | 0 | Pre-Ch SW3 | 2 | |
| CYCLE | LC-Cut | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| SYRINGE | 100 µl | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Sample Volume | 80 µl | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Air Volume | 0 µl | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Pre-Ch SW1 | 1 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Pre-Ch SW2 | 0 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Pre-Ch SW3 | 2 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Fill Speed | 10 µl/s | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Fill Strokes | 3 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Pullup Del | 3-10 s | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Inject to | LC-W1 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Inject Speed | 10 µl/s | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Pre-Inj Del | 500 ms | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Post-Inj Del | 500 ms | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Pre-Ch SW1 | 2 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Pre-Ch SW2 | 0 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Pre-Ch SW3 | 2 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |

Example for the following conditions:

- Loop Size 20 µl, overfill 1 - 5 times
- Partial Loop filling: Allowed sample volume range 20 - 60% of loop content for loops ≤ 100 µl
- Larger Loops: 20 - 60% of loop content
- Syringe: 100 - 225 µl, Gauge 225 limits, fill speed to max 20 µl/s (5-20 µl/s depends on viscosity of solvent)
- Syringe 225 - 300 µl, Gauge 225 allows fill speed up to 200 µl/s (depends on viscosity of solvent)
- Eject speed for 100 µl Syringe: 50 to 150 µl/s (lubricity/Syringe)
- Pre- and post Wash:
- Use Solvent Wash 2 for samples with components of extremely different polarities.
- Samples containing proteins should not contact organic solvents.
- Wash Steps for biological samples:
- 1st Wash Cycle: Aqueous solvent
- 2nd Wash Cycle: Organic solvent
- 1st Wash Cycle before next sample:
- Pre-wash with aqueous solvent (eliminate organic solvents in Syringe and Valve)

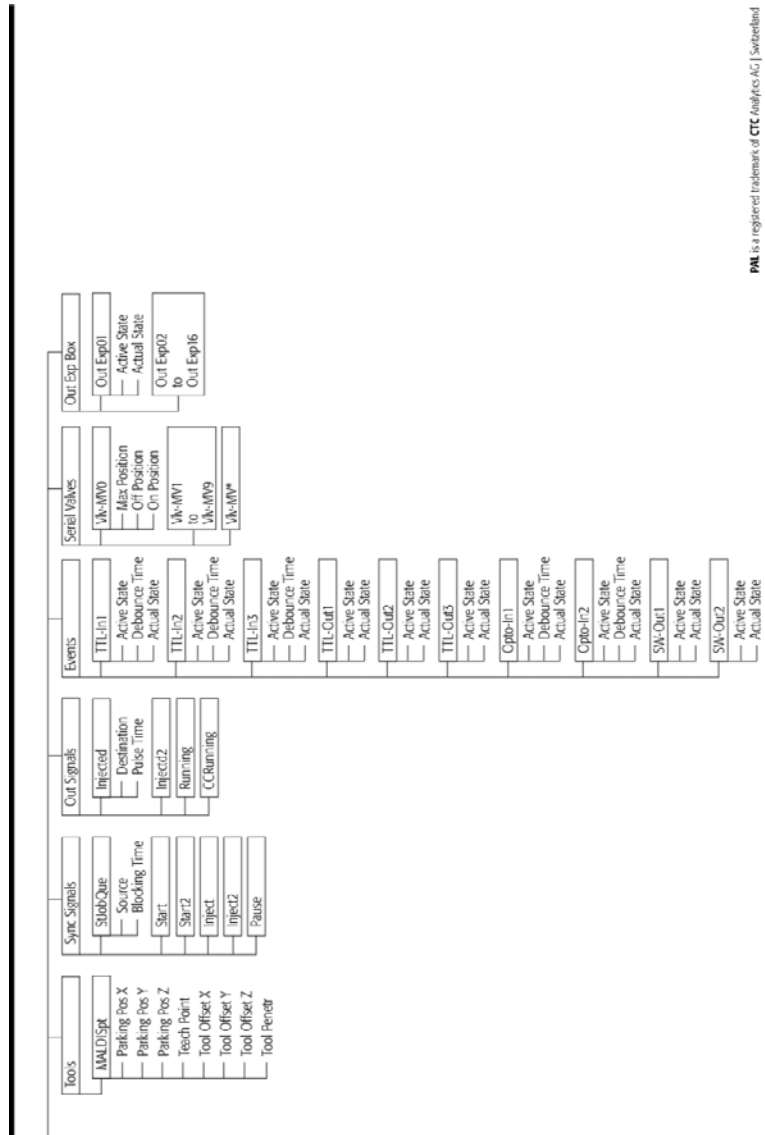
Part No.: PAL-FirmOHWHTC-H-C

Figure 71. HTC PAL - Firmware Overview, page 4



Note:
The standard software does not include every Object as shown in the overview.
The object depends on the hardware configuration for each individual PAL-system.
Revision 1 / Firmware 4.5.2 / March 2015

Figure 73. PAL HTC-xt Firmware Overview, Page 2



PAL is a registered trademark of CTC Analytics AG | Switzerland

Figure 74. PAL HTC-xt Firmware Overview, page 3

| Method Cycle | Recommended PAL Method Parameters | Remarks | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
|---------------|--|--------------|-----------------------------------|-------|----------|---------|--------|---------------|-------|------------|------|------------|---|------------|---|------------|---|------------|---------|--------------|---|-----------|--------|-----------|-------|--------------|---------|-------------|--------|------------|--------|------------|-----------------------|-----------|---|-----------|---|----------|---|----------|---|-----------|-------|-----------|--|-------------|--|---|
| LC-Inj | <table border="1"> <thead> <tr> <th>Method Cycle</th> <th>Recommended PAL Method Parameters</th> </tr> </thead> <tbody> <tr><td>CYCLE</td><td>LC - Inj</td></tr> <tr><td>SYRINGE</td><td>100 µl</td></tr> <tr><td>Sample Volume</td><td>80 µl</td></tr> <tr><td>Air Volume</td><td>0 ml</td></tr> <tr><td>Pre-Ch SW1</td><td>1</td></tr> <tr><td>Pre-Ch SW2</td><td>0</td></tr> <tr><td>Pre-Ch Spl</td><td>2</td></tr> <tr><td>Fill Speed</td><td>10 µl/s</td></tr> <tr><td>Fill Strokes</td><td>3</td></tr> <tr><td>Pulup Del</td><td>2-10 s</td></tr> <tr><td>Inject to</td><td>LC W1</td></tr> <tr><td>Inject Speed</td><td>10 µl/s</td></tr> <tr><td>Pre-Inj Del</td><td>500 ms</td></tr> <tr><td>PS-Inj Del</td><td>500 ms</td></tr> <tr><td>PS-Ch SW1</td><td>2</td></tr> <tr><td>PS-Ch SW2</td><td>0</td></tr> <tr><td>W-Ch SW1</td><td>2</td></tr> <tr><td>W-Ch SW2</td><td>0</td></tr> </tbody> </table> | Method Cycle | Recommended PAL Method Parameters | CYCLE | LC - Inj | SYRINGE | 100 µl | Sample Volume | 80 µl | Air Volume | 0 ml | Pre-Ch SW1 | 1 | Pre-Ch SW2 | 0 | Pre-Ch Spl | 2 | Fill Speed | 10 µl/s | Fill Strokes | 3 | Pulup Del | 2-10 s | Inject to | LC W1 | Inject Speed | 10 µl/s | Pre-Inj Del | 500 ms | PS-Inj Del | 500 ms | PS-Ch SW1 | 2 | PS-Ch SW2 | 0 | W-Ch SW1 | 2 | W-Ch SW2 | 0 | | | | | | | | | |
| Method Cycle | Recommended PAL Method Parameters | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| CYCLE | LC - Inj | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| SYRINGE | 100 µl | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Sample Volume | 80 µl | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Air Volume | 0 ml | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Pre-Ch SW1 | 1 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Pre-Ch SW2 | 0 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Pre-Ch Spl | 2 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Fill Speed | 10 µl/s | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Fill Strokes | 3 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Pulup Del | 2-10 s | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Inject to | LC W1 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Inject Speed | 10 µl/s | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Pre-Inj Del | 500 ms | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| PS-Inj Del | 500 ms | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| PS-Ch SW1 | 2 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| PS-Ch SW2 | 0 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| W-Ch SW1 | 2 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| W-Ch SW2 | 0 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| LC-Cut | <table border="1"> <thead> <tr> <th>Method Cycle</th> <th>Recommended PAL Method Parameters</th> </tr> </thead> <tbody> <tr><td>CYCLE</td><td>LC - Cut</td></tr> <tr><td>SYRINGE</td><td>100 µl</td></tr> <tr><td>Sample Volume</td><td>80 µl</td></tr> <tr><td>Air Volume</td><td>0 ml</td></tr> <tr><td>Pre-Ch SW1</td><td>1</td></tr> <tr><td>Pre-Ch SW2</td><td>0</td></tr> <tr><td>Pre-Ch Spl</td><td>2</td></tr> <tr><td>Fill Speed</td><td>5 µl/s</td></tr> <tr><td>Fill Strokes</td><td>2</td></tr> <tr><td>Pulup Del</td><td>2-10 s</td></tr> <tr><td>Inject to</td><td>LC W1</td></tr> <tr><td>Inject Speed</td><td>5 µl/s</td></tr> <tr><td>Pre-Inj Del</td><td>500 ms</td></tr> <tr><td>PS-Inj Del</td><td>500 ms</td></tr> <tr><td>SplRateDel</td><td>Sample Transfer Delay</td></tr> <tr><td>PS-Ch SW1</td><td>2</td></tr> <tr><td>PS-Ch SW2</td><td>0</td></tr> <tr><td>W-Ch SW1</td><td>2</td></tr> <tr><td>W-Ch SW2</td><td>0</td></tr> <tr><td>Cut Valve</td><td>LC W1</td></tr> <tr><td>Cut Delay</td><td></td></tr> <tr><td>MinCondTime</td><td></td></tr> </tbody> </table> | Method Cycle | Recommended PAL Method Parameters | CYCLE | LC - Cut | SYRINGE | 100 µl | Sample Volume | 80 µl | Air Volume | 0 ml | Pre-Ch SW1 | 1 | Pre-Ch SW2 | 0 | Pre-Ch Spl | 2 | Fill Speed | 5 µl/s | Fill Strokes | 2 | Pulup Del | 2-10 s | Inject to | LC W1 | Inject Speed | 5 µl/s | Pre-Inj Del | 500 ms | PS-Inj Del | 500 ms | SplRateDel | Sample Transfer Delay | PS-Ch SW1 | 2 | PS-Ch SW2 | 0 | W-Ch SW1 | 2 | W-Ch SW2 | 0 | Cut Valve | LC W1 | Cut Delay | | MinCondTime | | <p>Time needed to transfer sample from Loop onto 2nd valve (pre- or analytical column).</p> <p>Specify name of 2nd valve, switching valve</p> <p>Time needed for clean-up, switch to backflush sample, to analytical column or detector</p> <p>Minimum Conditioning Time: Time needed to condition pre- column on 2nd valve</p> |
| Method Cycle | Recommended PAL Method Parameters | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| CYCLE | LC - Cut | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| SYRINGE | 100 µl | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Sample Volume | 80 µl | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Air Volume | 0 ml | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Pre-Ch SW1 | 1 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Pre-Ch SW2 | 0 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Pre-Ch Spl | 2 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Fill Speed | 5 µl/s | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Fill Strokes | 2 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Pulup Del | 2-10 s | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Inject to | LC W1 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Inject Speed | 5 µl/s | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Pre-Inj Del | 500 ms | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| PS-Inj Del | 500 ms | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| SplRateDel | Sample Transfer Delay | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| PS-Ch SW1 | 2 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| PS-Ch SW2 | 0 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| W-Ch SW1 | 2 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| W-Ch SW2 | 0 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Cut Valve | LC W1 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Cut Delay | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| MinCondTime | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |

Example for the following conditions:

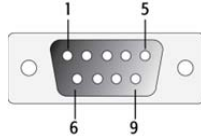
- Loop Size 20 µl, evrfill 3 - 5 times
- Partial Loop filling Allowed, sample volume range 20 - 60% of loop content for loops ≤ 100 µl
- Large Loops: 20 - 80% of loop content
- Syringe:
 - Syr LC100 - 225 - 3: Gauge 225 limits fill speed to max 20 µl/s (5-20 µl/s depends on viscosity of solvent)
 - Syr LC100 - 22 - 3: Gauge 22 allows fill speed up to 200 µl/s (depends on viscosity of solvent)
- Eject speed for 100 µl Syringe: 50 to 150 µl/s (Utilities/Syringe)
- Pre- and post Washing:
 - Use Solvent 1 and 2 for samples with components of extremely different polarities
 - Samples contain proteins should not contact organic solvents
- Wash Steps for biological samples:
 - 1st Wash Cycle: Aqueous solvent
 - 2nd Wash Cycle: Organic solvent
- 1st Wash Cycle before next sample:
 - Pre-wash with aqueous solvent. (dissolve organic solvents in Syringe and Valve)

Pal No.: PAL.FirmwareHTC1

Figure 75. PAL HTC-xt Firmware Overview, Page 4

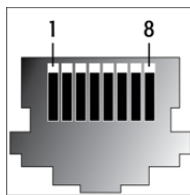
5. External Connectors for PAL and -*xt* System

Connector SER1 | PAL and PAL-*xt* System



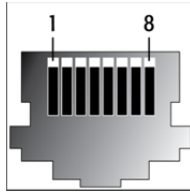
| Pin | Signal Name |
|-----|---|
| 1 | NC |
| 2 | RXD |
| 3 | TXD |
| 4 | DTR bridged with Pin7; Special grounding, do not alter. |
| 5 | GND |
| 6 | NC |
| 7 | RTS bridged with Pin 4; Do not alter. |
| 8 | NC |
| 9 | NC |

Connector TERMINAL or SER3 | PAL and PAL-*xt* System



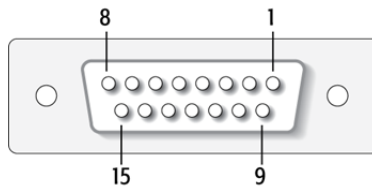
| Pin | Signal Name |
|-----|-------------|
| 1 | GND |
| 2 | RXD |
| 3 | TXD |
| 4 | NC |
| 5 | NC |
| 6 | +5V |
| 7 | NC |
| 8 | GND |

Connector SER2 | PAL System



| Pin | Signal Name |
|-----|-------------|
| 1 | GND |
| 2 | RXD |
| 3 | TXD |
| 4 | NC |
| 5 | NC |
| 6 | +5V |
| 7 | NC |
| 8 | GND |

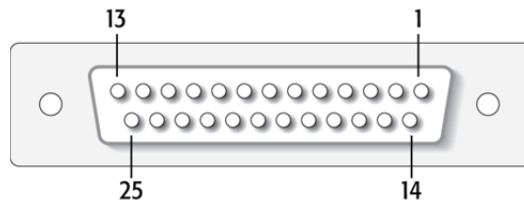
Connector INTERFACE 1 | PAL and PAL-*xt* System ¹



| Pin | Signal Name |
|-----|-------------|
| 1 | Pwr-Out1 + |
| 2 | Pwr-Out2 + |
| 3 | SW-Out1 NO |
| 4 | SW-Out1 COM |
| 5 | SW-Out2 NO |
| 6 | Opto-In1 + |
| 7 | TTL-In1 |
| 8 | GND |
| 9 | Pwr-Out1 - |
| 10 | Pwr-Out2 - |
| 11 | TTL-In2 |
| 12 | SW-Out2 COM |
| 13 | TTL-In3 |
| 14 | Opto-In1 - |
| 15 | +5V |

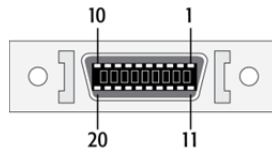
¹ APR Control-HTC Board: "INTERFACE" and not "INTERFACE1"

Connector INTERFACE 2 | PAL-*xt* System



| Pin | Signal Name |
|-------|-------------|
| 1 | TTL-In1 |
| 2 | TTL-In2 |
| 3 | TTL-In3 |
| 4 | TTL-Out1 |
| 5 | TTL-Out2 |
| 6 | TTL-Out3 |
| 7 | Opto-In1 + |
| 8 | Opto-In2 + |
| 9 | SW-Out1 NO |
| 10 | SW-Out2 NO |
| 11 | Pwr-Out1 + |
| 12 | Pwr-Out2 + |
| 13 | +5V |
| 14-19 | GND |
| 20 | Opto-In1 - |
| 21 | Opto-In2 - |
| 22 | SW-Out1 COM |
| 23 | SW-Out2 COM |
| 24 | Pwr-Out1 - |
| 25 | Pwr-Out2 - |

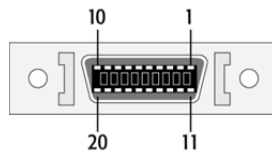
Connector AUX1 | PAL and PAL-*xt* System ¹



| Pin | Signal Name |
|----------|-------------|
| 1,2 | Motor A1 |
| 11,12 | Motor A2 |
| 3,4 | Motor B1 |
| 13,14 | Motor B2 |
| 15,18,19 | GND |
| 6 | Temp + |
| 16 | Temp - |
| 7 | Sens |
| 17 | +5V |
| 8,9 | Heater |
| 20,10 | 36V |

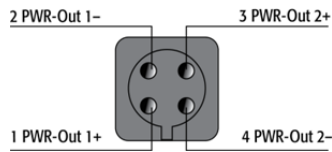
¹ APRControl-HTC Board: "AUX" and not "AUX1"

Connector AUX2 | PAL-*xt* System



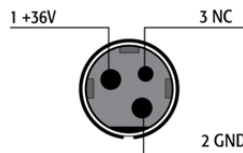
| Pin | Signal Name |
|----------|-------------|
| 1,2 | Motor A1 |
| 11,12 | Motor A2 |
| 3,4 | Motor B1 |
| 13,14 | Motor B2 |
| 15,18,19 | GND |
| 6 | Temp + |
| 16 | Temp - |
| 7 | Sens |
| 17 | +5V |
| 8,9 | Heater |
| 20,10 | 36V |

Connector Wash Station | PAL and PAL-*xt* System



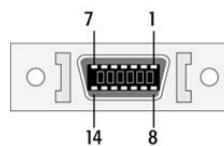
| Pin | Signal Name |
|-----|-------------|
| 1 | PWR – Out1+ |
| 2 | PWR – Out1- |
| 3 | PWR – Out2+ |
| 4 | PWR – Out2- |

Connector Power | PAL and PAL-*xt* System



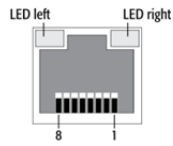
| Pin | Signal Name |
|-----|-------------|
| 1 | +36 V |
| 2 | GND |
| 3 | NC |

Connector MODBUS | PAL-*xt* System



| Pin | Signal Name |
|--------|-------------|
| 1 | TXD |
| 2 – 7 | +36 V |
| 8 | RXD |
| 9 – 14 | GND |

Connector LAN | PAL-*xt* System



| Pin | Signal Name | DIR | Primary Function |
|------|-------------|-----|------------------|
| 1 | TX+ | Out | Transmit Data + |
| 2 | TX- | Out | Transmit Data - |
| 3 | RX+ | In | Receive Data + |
| 4,5, | Not used | | Terminated |
| 6 | RX- | In | Receive Data - |
| 7,8 | Not used | | Terminated |

Connector Fuse | PAL-*xt* System

| | |
|---------------|----------|
| Fuse Type | FST 5x20 |
| Rating | 6.3A |
| Rated Voltage | 250 VAC |

6.0 Intended Use of the PAL and PAL-xt Systems by CTC Analytics AG

6.1. Introduction

The brand name 'PAL System' encompasses an entire product family. The following description of intended use applies to the product group 'PAL and PAL-xt Systems' and its related design-dependent subclasses.

If the PAL or PAL-xt System is distributed through OEM partners, the product or model name may be replaced with the distributor's own trade name but the original 'Intended Use' remains valid.

6.2. Intended Use

The PAL and the PAL-xt Systems are X-, Y-, Z-robotic systems offering a high degree of flexibility and functionality.

The PAL System is intended to be used mainly as an autosampler or sample preparation device for all relevant applications in chemical and physical analysis.

Typical applications include:

- Environmental analysis
- Quality control in the chemical and pharmaceutical industries
- Drug discovery
- Metabolic studies on agrochemicals or pharmaceutical products

The above list of typical applications is not exhaustive.

The classical use of the PAL or PAL-xt Systems has been chiefly as an autosampler in chromatography, with gas chromatography (GC) and high-pressure liquid chromatography (HPLC) being the two main applications. Sample preparation steps such as filtration, purification or separation by solid phase extraction (SPE), derivatization, etc. are possible in combination with chromatographic or other techniques.

The PAL and the PAL-xt System can also be used for a variety of other techniques or areas of application.

X-, Y-, Z-robotic systems are typically used where sample transport, liquid handling or sample preparation need to be automated. Well known examples include tablet dissolution testing, viscosimetry, etc.

To a large extent, the users themselves will determine which substances or liquids the system will come into contact with, as well as the applications for which the PAL or the PAL-xt System will be used.

The PAL and the PAL-xt System have been developed following the ISO Guide 9001.

6.3. Disclaimer and Restrictions on Use

CTC Analytics AG assumes no responsibility for sample placement, syringe insertion, reagent and wash solvent selection, and other related preparatory tasks. The inadvertent switching of samples or omission of an item cannot be detected or prevented by the PAL or the PAL-xt System. The system boundary is defined by the placement of samples in the fully prepared system.

It is the user's (operator's) responsibility to set method parameters (variables) according to the technique used and required by the application.

It is the user's (operator's) responsibility to handle hazardous chemicals or biological compounds including (but not limited to) bacterial or viral samples and the associated waste safely and according to international and local regulations.

By definition, CTC Analytics AG also excludes the use of PAL or the PAL-xt Systems directly on living animals or humans, for example in patients (invasive devices).

In addition, the PAL or the PAL-xt System may not be used in an environment in which explosion protection is required for safety reasons.

CTC Analytics AG assumes no responsibility for the integration of the PAL or the PAL-xt System software into an overriding system of a third party, such as a CDS (Chromatography Data System). In particular, the additional treatment of commands, data, or any other information sent or received from the overriding system is the sole responsibility of the third party.

CTC Analytics AG assumes no responsibility for any script, cycle, or method (any logical operation of commands) developed by a third party. The actions and movements of the robotic system as well as error treatment is the sole responsibility of the originator and user of the particular script.

The 'Intended Use' described above is valid only for the PAL or the PAL-xt System and does not apply to the later models of the 'PAL System' product family, such as the product groups 'PAL3 System', which include for example the model PAL RTC.

The PAL and the PAL-xt System, like all CTC Analytics products, must only be used in the manner described in the corresponding User Manual and the corresponding CTC Analytics User Manuals for the other CTC Analytics products.

CTC Analytics assumes no responsibility for any other usage which may result in damage to the product or personal injury.

CTC Analytics assumes no responsibility for any damages caused, in whole or in part, through improper use of the PAL or the PAL-xt System, unauthorized alterations, adjustments or modifications to the PAL or the PAL-xt System, or failure to comply with procedures in the PAL or the PAL-xt System User Manual and the other CTC Analytics User Manuals.

CTC Analytics assumes no responsibility for any usage of the PAL or the PAL-xt System which violates applicable rules, laws or regulations.

7. PAL Accessories

The accessories for the PAL System are described in the attached "PAL accessories Catalog" or on the web page: www.ctc.ch.

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